

# **Deterministic Max-Flows in Simple Graphs**

Tianyi Zhang, Tsinghua Univ.

# Max-flows in simple graphs

Graph  $G = (V, E)$

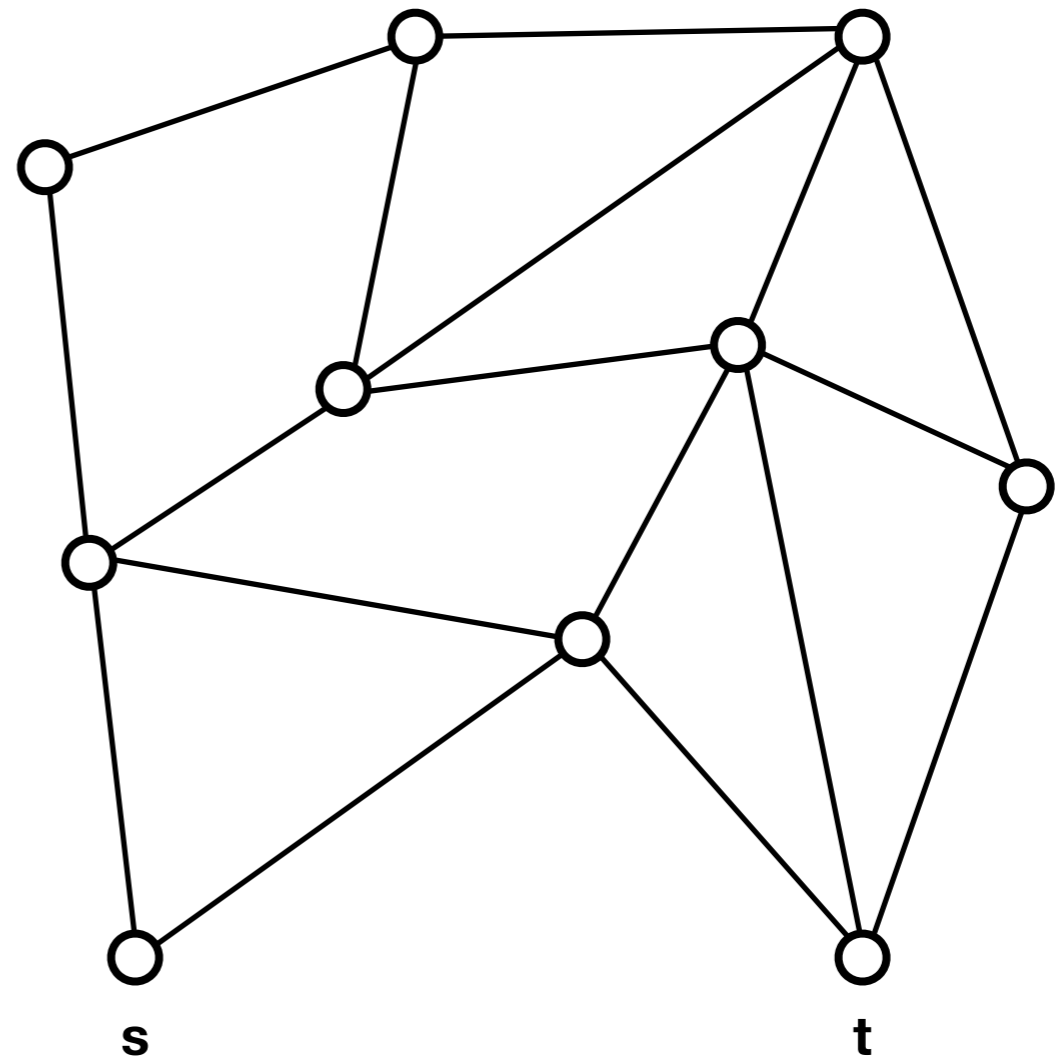
- n vertices
- m edges
- No parallel edges

Capacities

- Unit

Terminals

- $s, t \in V$



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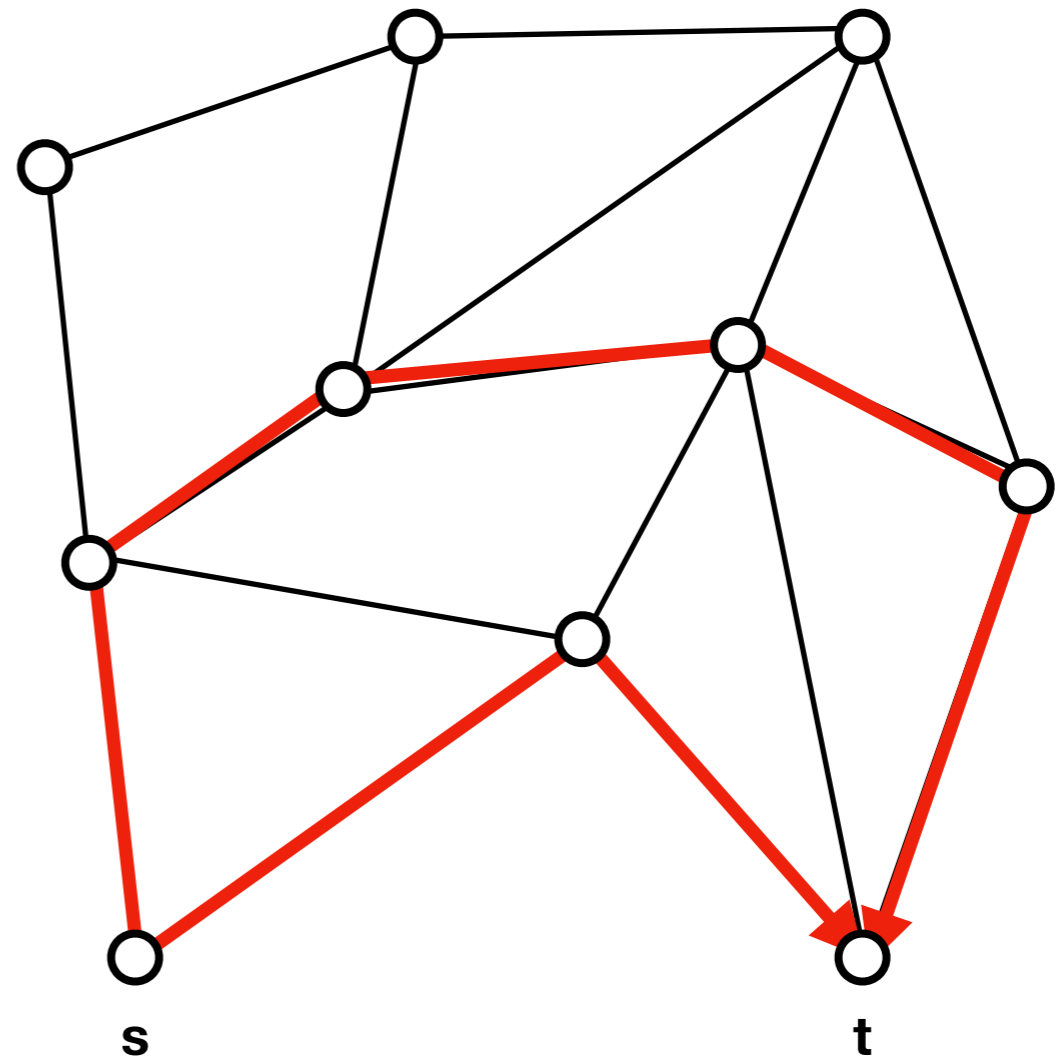
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max-flow has value 2

# History

Reference	Running time	det / rand ?
[KL'98]	$O(m + n\tau^{3/2})$	det
[KL'02]	$\tilde{O}(m + n\tau)$	rand
[Duan'13]	$\tilde{O}(n^{9/4}\tau^{1/8})$	det
<b>Ours</b>	$\tilde{O}(m + n^{5/3}\tau^{1/2})$	det

Fastest when

$$\tau > n^{0.67}$$

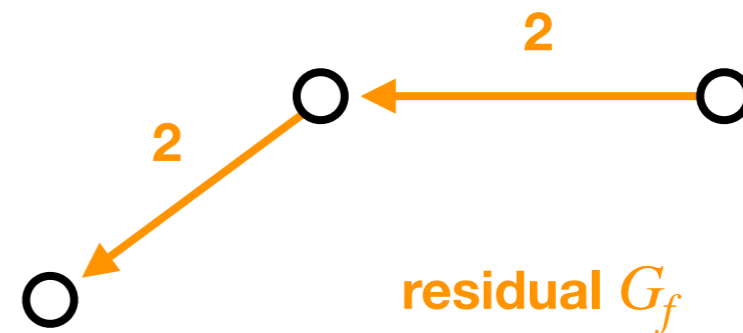
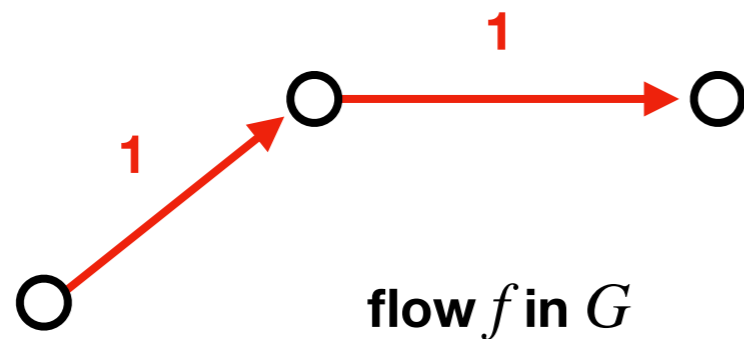
$n$  = #vertices,  $m$  = #edges

$\tau$  = an upper bound on max-flow

# Flow decycling

# Ford-Fulkerson

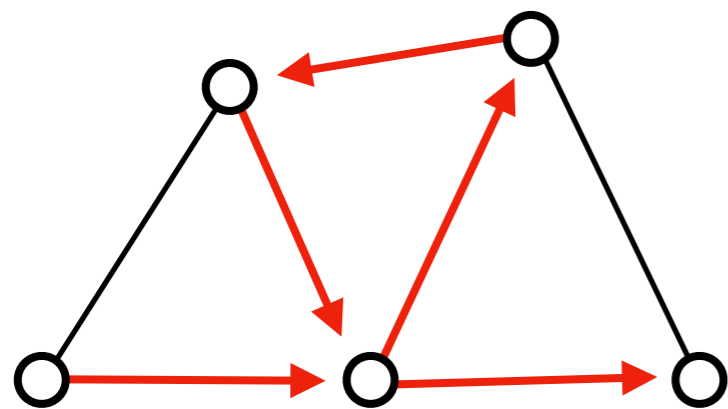
- **Residual** graph  $G_f$  of  $G$  w.r.t flow  $f$



- Ford-Fulkerson:  
Keep finding **augmenting paths** from  $s$  to  $t$  in  $G_f$
- Running time =  $\tilde{O}(m\tau)$   
 $\tau$  is a known upper bound on the max-flow value

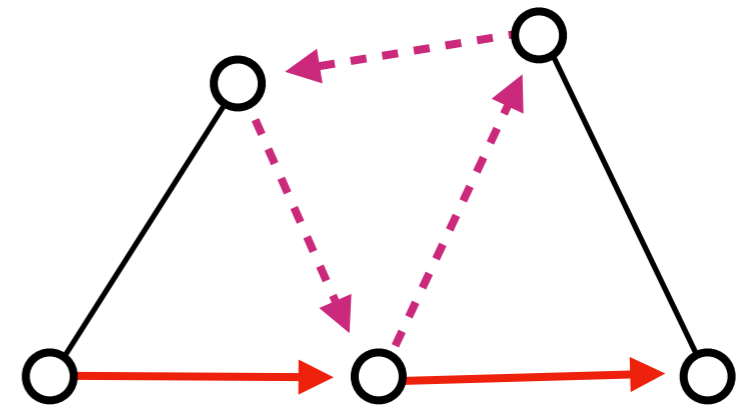
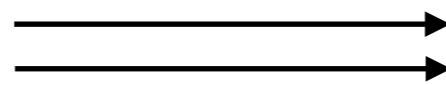
# Flow decycling

- Lemma: [Karger & Levine '98]  
Acyclic flow  $f$  with value  $|f|$  has  $O(n |f|^{1/2})$  flow edges
- $G_f$  has at most  $O(n |f|^{1/2})$  directed edges when  $f$  is acyclic



many **flow edges**

decycle



at most  $O(n |f|^{1/2})$  **flow edges**

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- Algorithm: [Karger & Levine '98]  
**While**  $\exists$  augmenting path in  $G_f$   
    contract all connected components by **undi**-edges in  $G_f$   
    BFS on the contracted  $G_f$  which contains only  $O(n |f|^{1/2})$  **di**-edges  
    augment flow  $f$ , then decycle  $f$

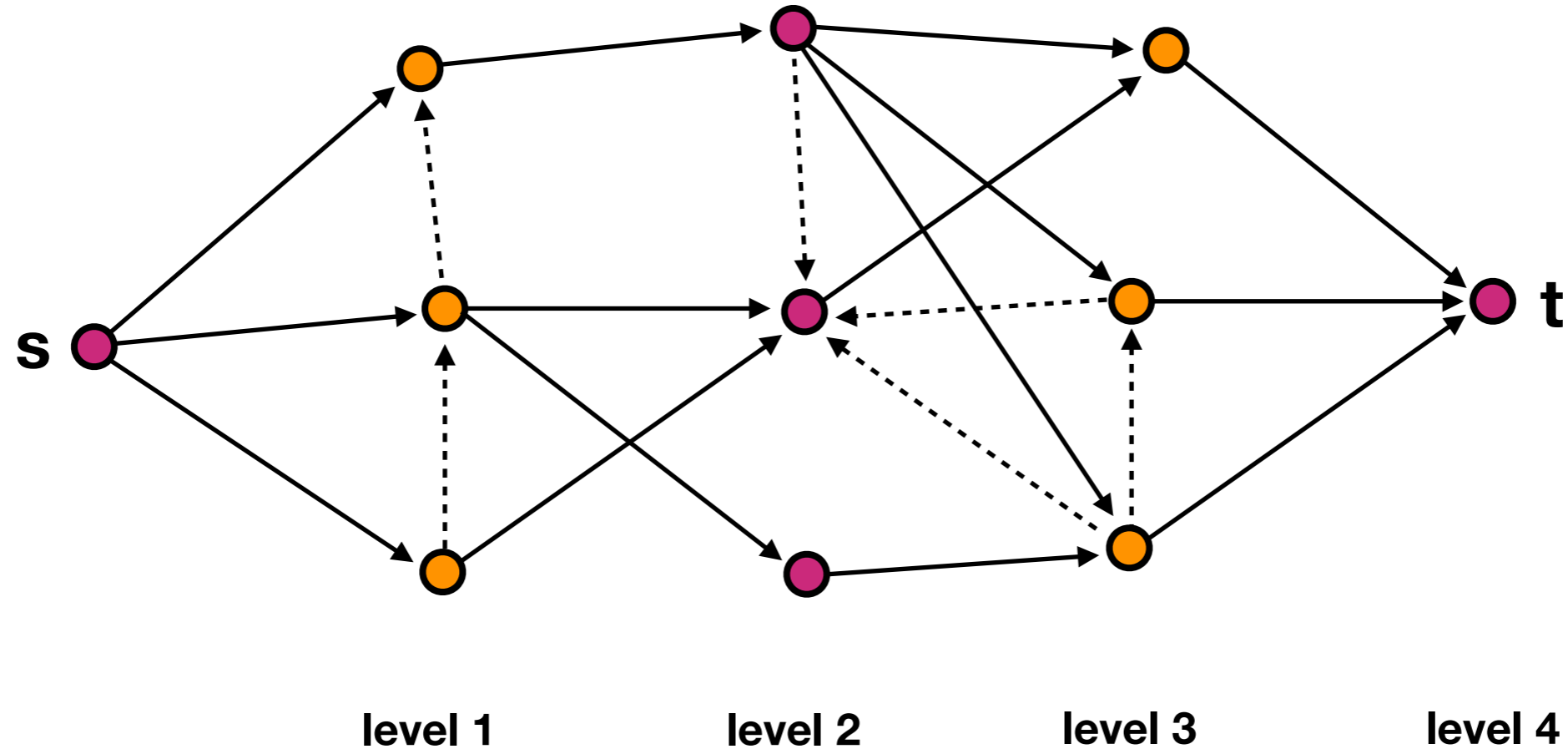
- Running time =  $\tilde{O}(m + n\tau^{3/2})$   
 $G_f$  always has  $O(n\tau^{1/2})$  edges, so total time =  $\tilde{O}(m + \tau \cdot n\tau^{1/2})$



# Blocking flows

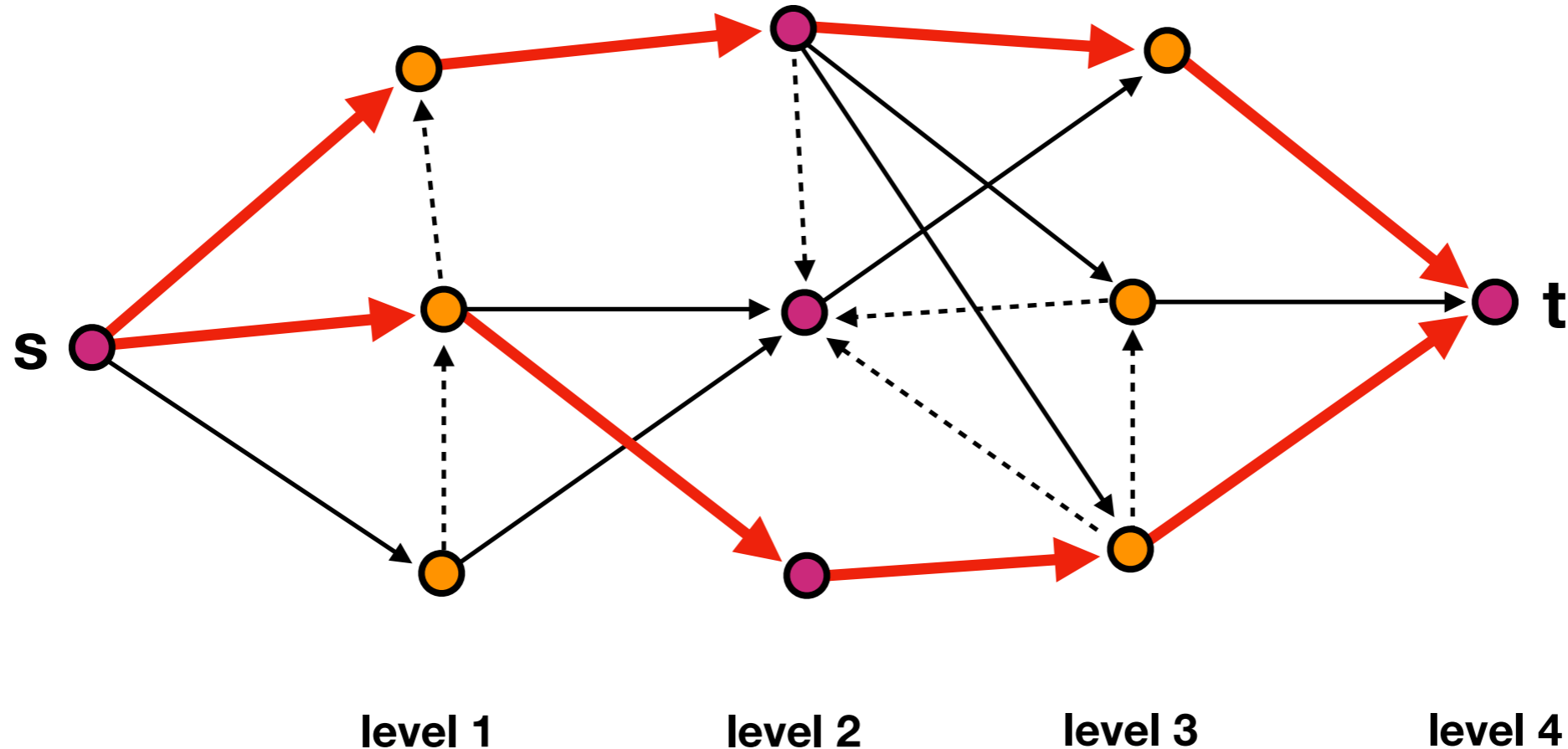
# Blocking flows

- Form a level graph by the **distance from  $s$**  in  $G_f$



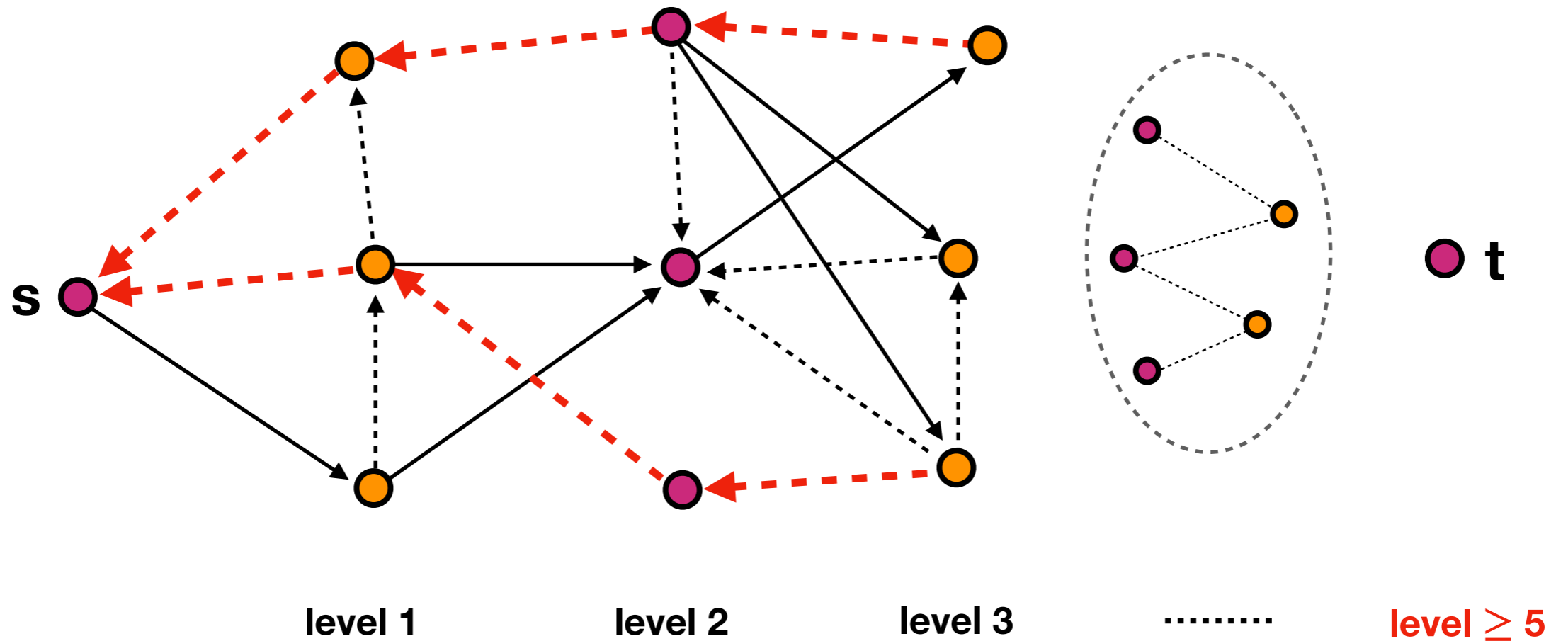
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- Form a level graph by the **distance from  $s$**  in  $G_f$
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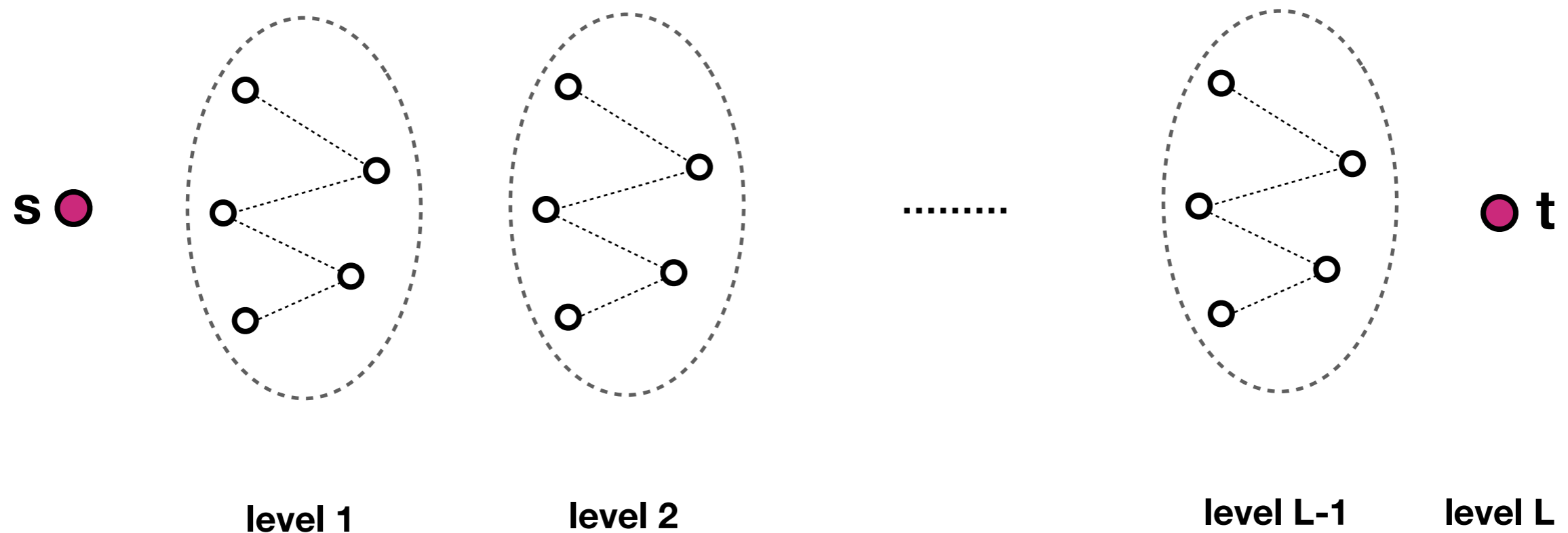
# Blocking flows

- Form a level graph by the **distance from  $s$**  in  $G_f$
- Find a **maximal set of shortest disjoint** aug-paths
- $\text{Dist}(s, t)$  in  $G_f$  **increases**



# Blocking flows

- Repeat blocking-flows until  $\text{Dist}(s, t) \geq L$
- Residual flow in  $G_f$  becomes at most  $O(n^2/L^2)$
- Then apply Ford-Fulkerson  $O(n^2/L^2)$  times



- Running time =  $L \cdot \text{BF} + \frac{n^2}{L^2} \cdot \text{FF} = mn^{2/3}$  [Goldberg & Rao '98]

# Decycling + Blocking-flow

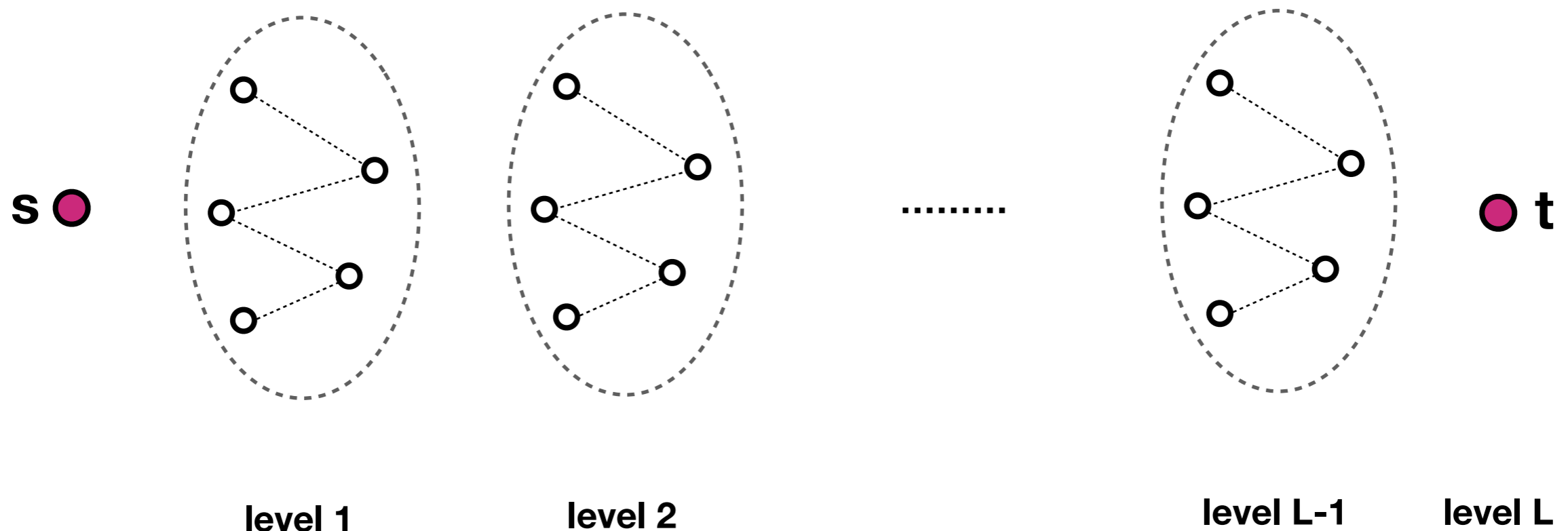
- Lemma: [Karger & Levine '98]  
Acyclic flow  $f$  with value  $|f|$  has  $O(n |f|^{1/2})$  flow edges
- Exists subgraph  $H \subseteq G$  with  $O(n\tau^{1/2})$  edges that contains the max-flow
- If we knew  $H$  beforehand, then applying blocking-flow on  $H$  can compute max-flow in  $\tilde{O}(n^{5/3}\tau^{1/2})$  time
- Ideally, shoot for  $\tilde{O}(m + n^{5/3}\tau^{1/2})$

# Decycling + blocking-flows

[Duan '13]

# Combining two techniques

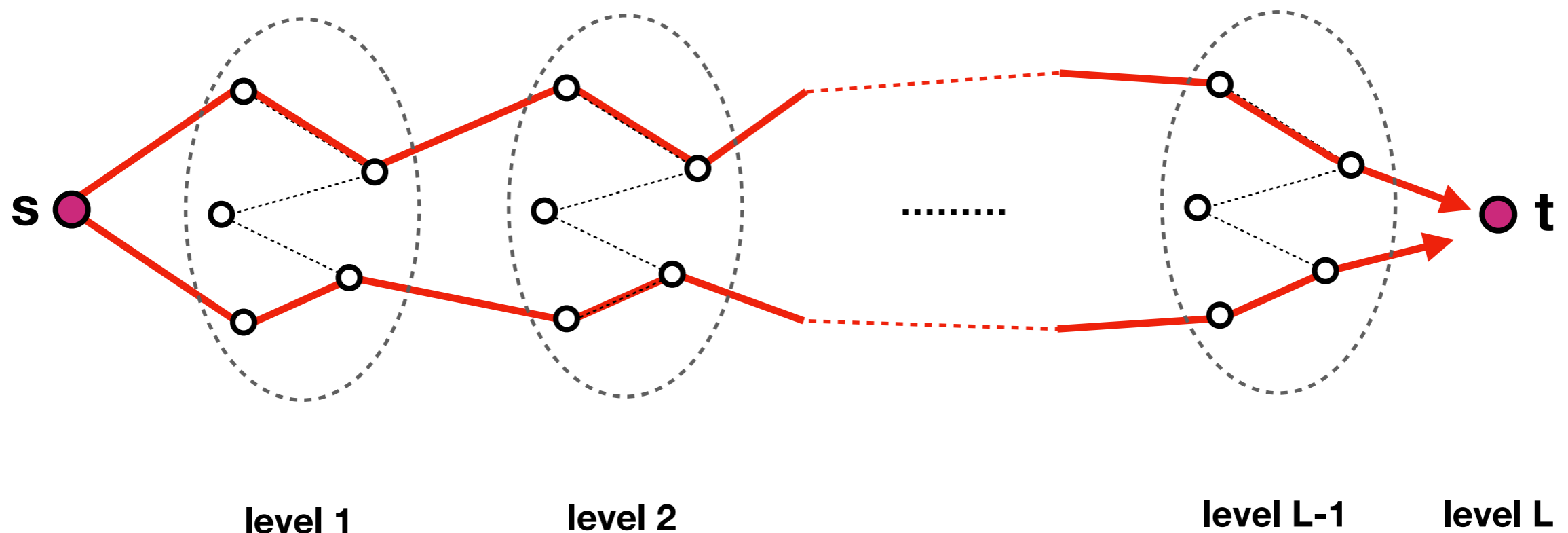
- Compute a blocking-flow in  $G_f$  where  $f$  is acyclic  
Take time  $\tilde{O}(n |f|^{1/2})$  since undirected edges are contracted





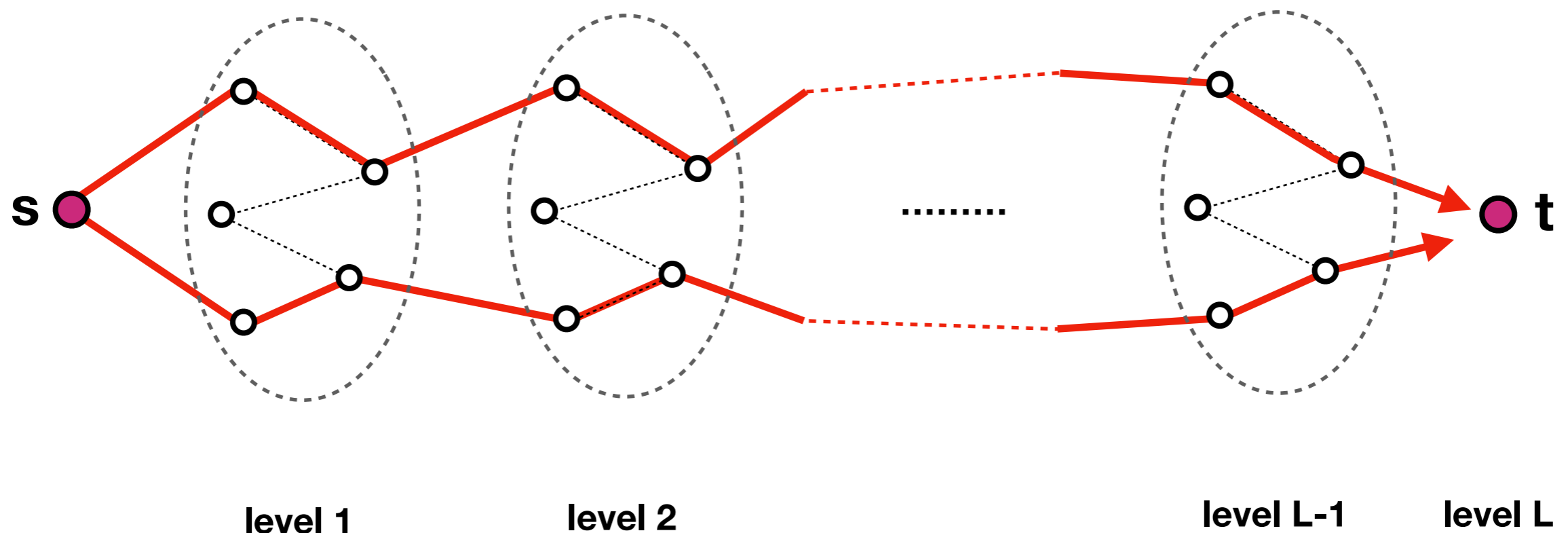
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- Augment flow  $f \leftarrow f + \Delta f$ , so  $\text{Dist}(s, t)$  in  $G_f$  increases  
But now,  $f$  might contain **cycles**



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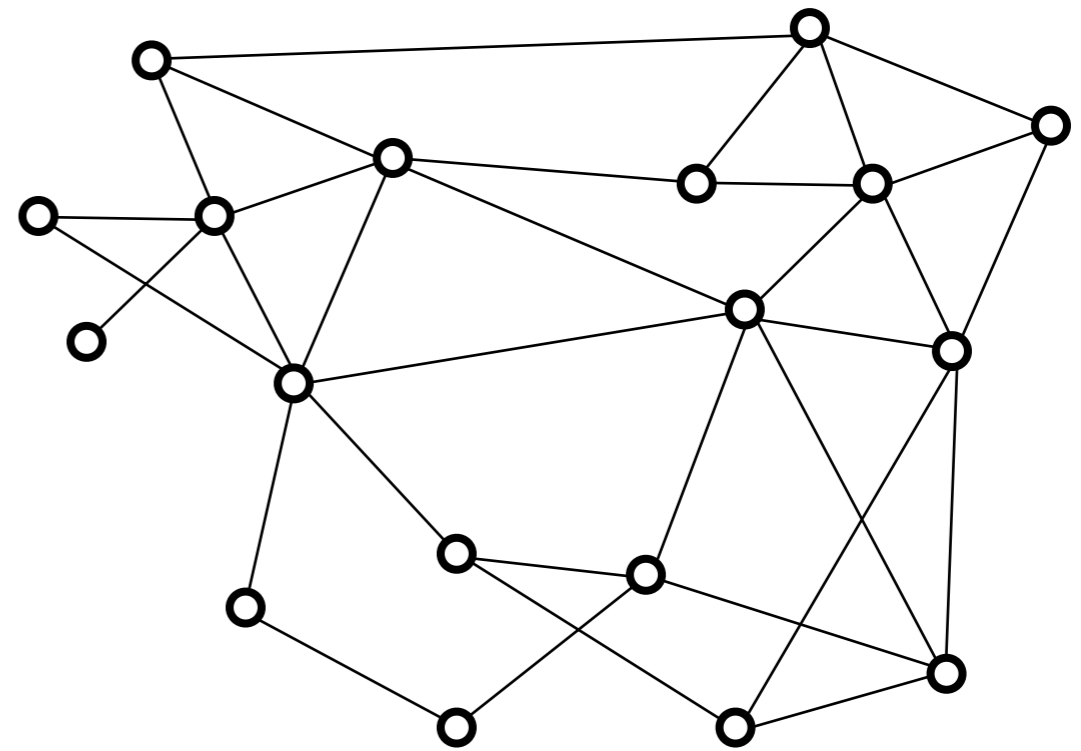
- Augment flow  $f \leftarrow f + \Delta f$ , so  $\text{Dist}(s, t)$  in  $G_f$  increases  
But now,  $f$  might contain **cycles**
- Decycling adds **undirected edges** between level  $i$  &  $(i+1)$
- Blocking-flows becomes costly as #undi-edges grows  
Cannot contract these undirected edges



# Clustering

- Trouble: #undi-edges grows larger than  $n\tau^{1/2}$   
Computing blocking-flows becomes costly
- Key idea: [Duan'13] partition into star-subgraphs

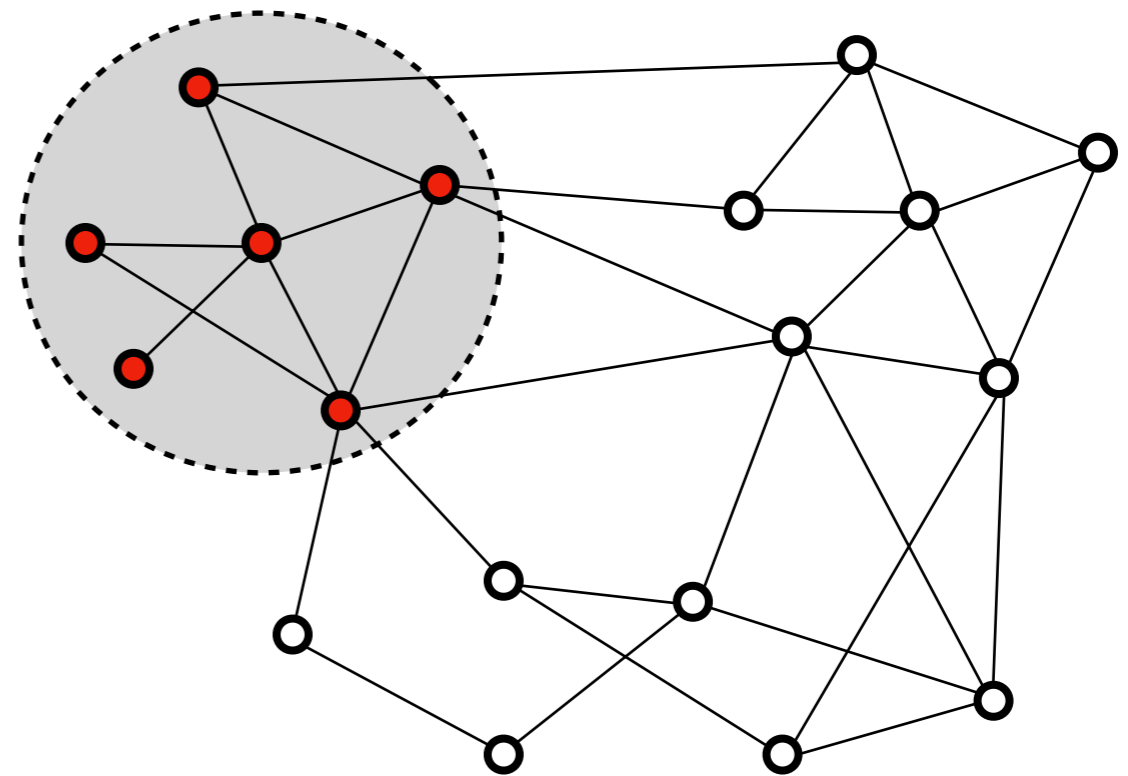
- Partition vertices into  $V_1 \cup V_2$
- $V_1$  is a union of star-graphs, each of size  $\geq h$
- Edges between  $V_2$  is at most  $O(nh)$



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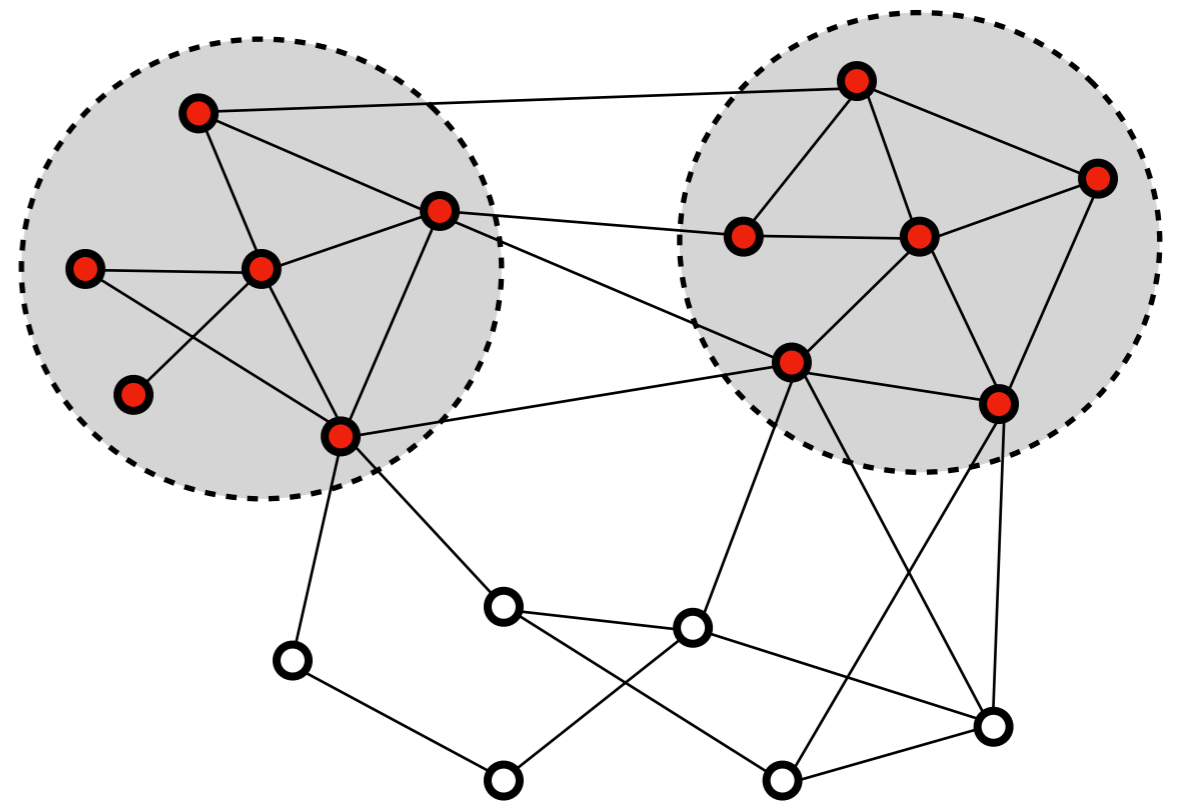


greedy clustering

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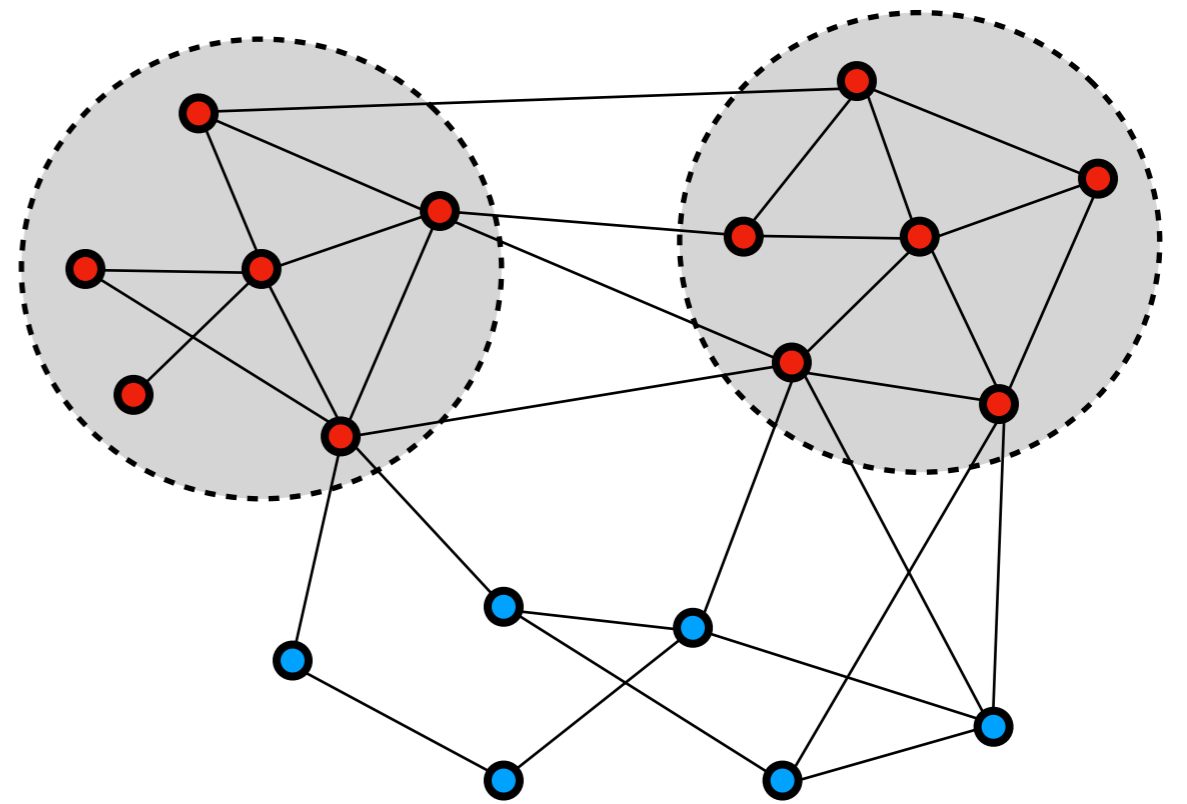
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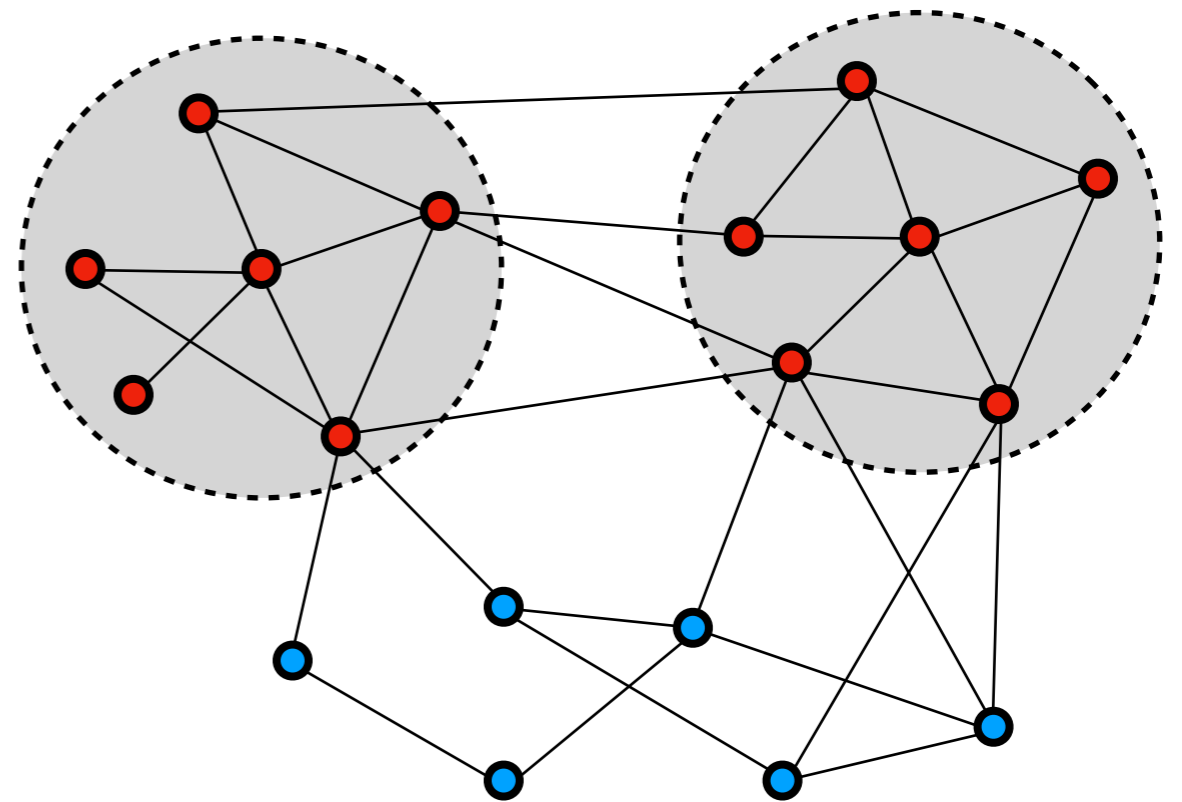
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# Dynamic maintenance

- Updates: augmentations turn undi-edges to di-edges  
**Delete** di-edges from the clustering structure
- Need dynamic maintenance of the clustering structure

## Deletion of star edges:

- Disconnects the vertex, and move it downward
- Increase total degree by at most  $O(n)$
- **Rebuild if total degree exceeds  $nh$**

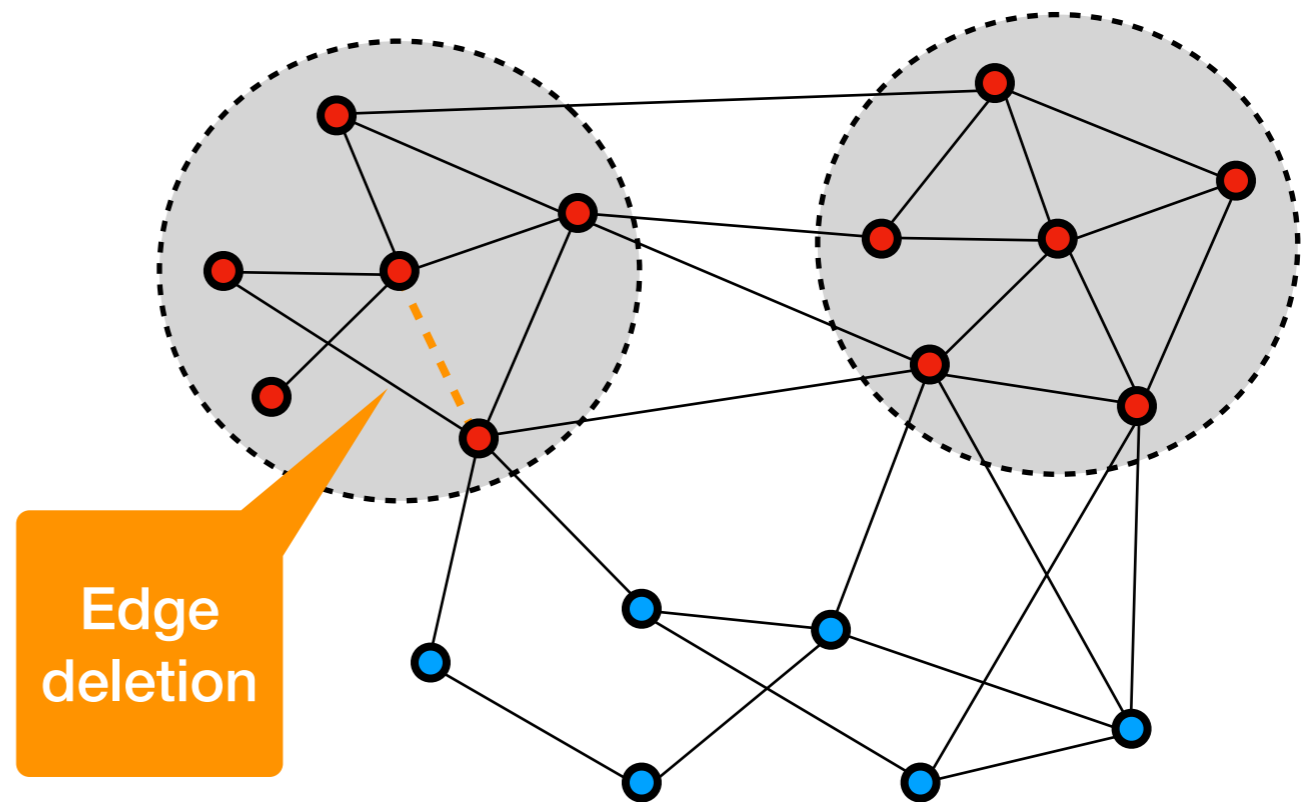


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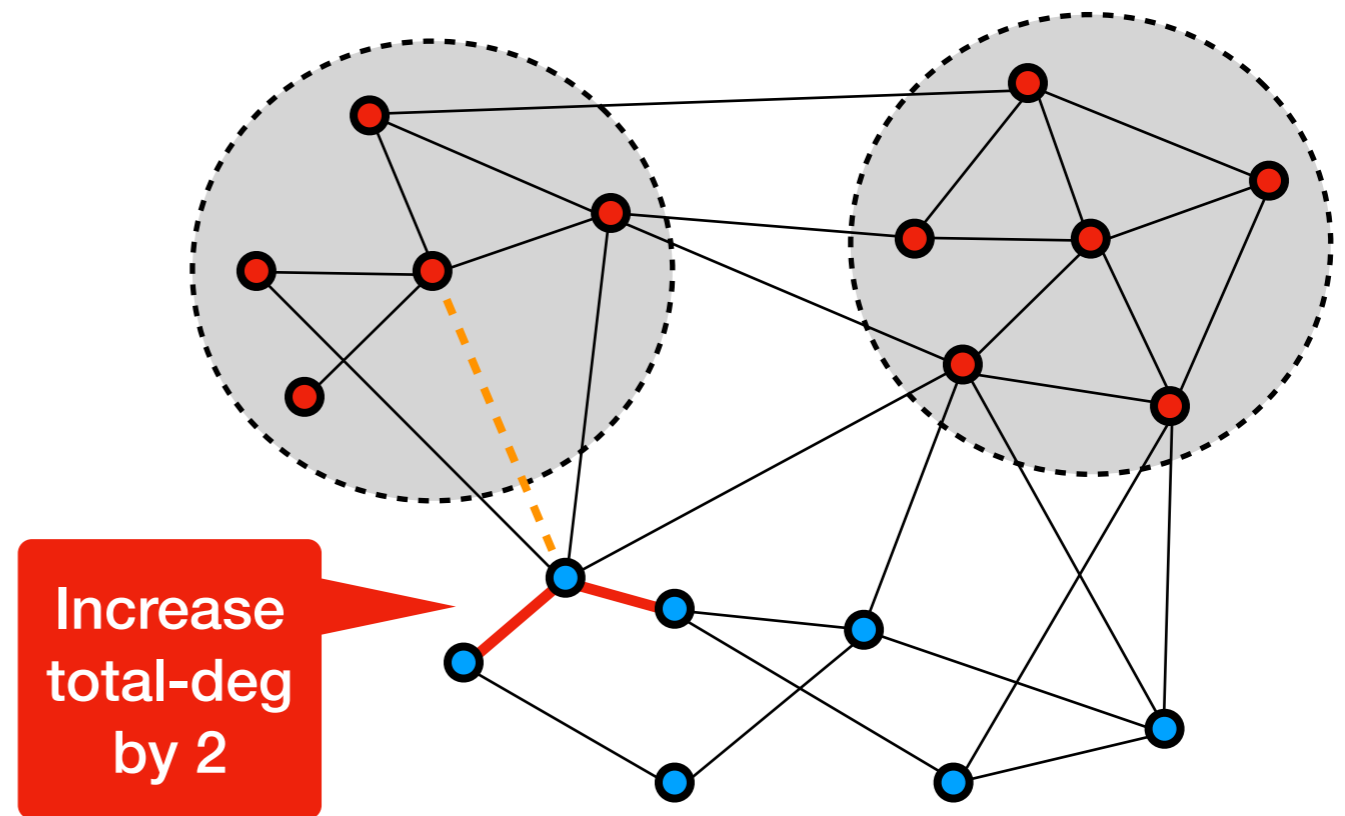


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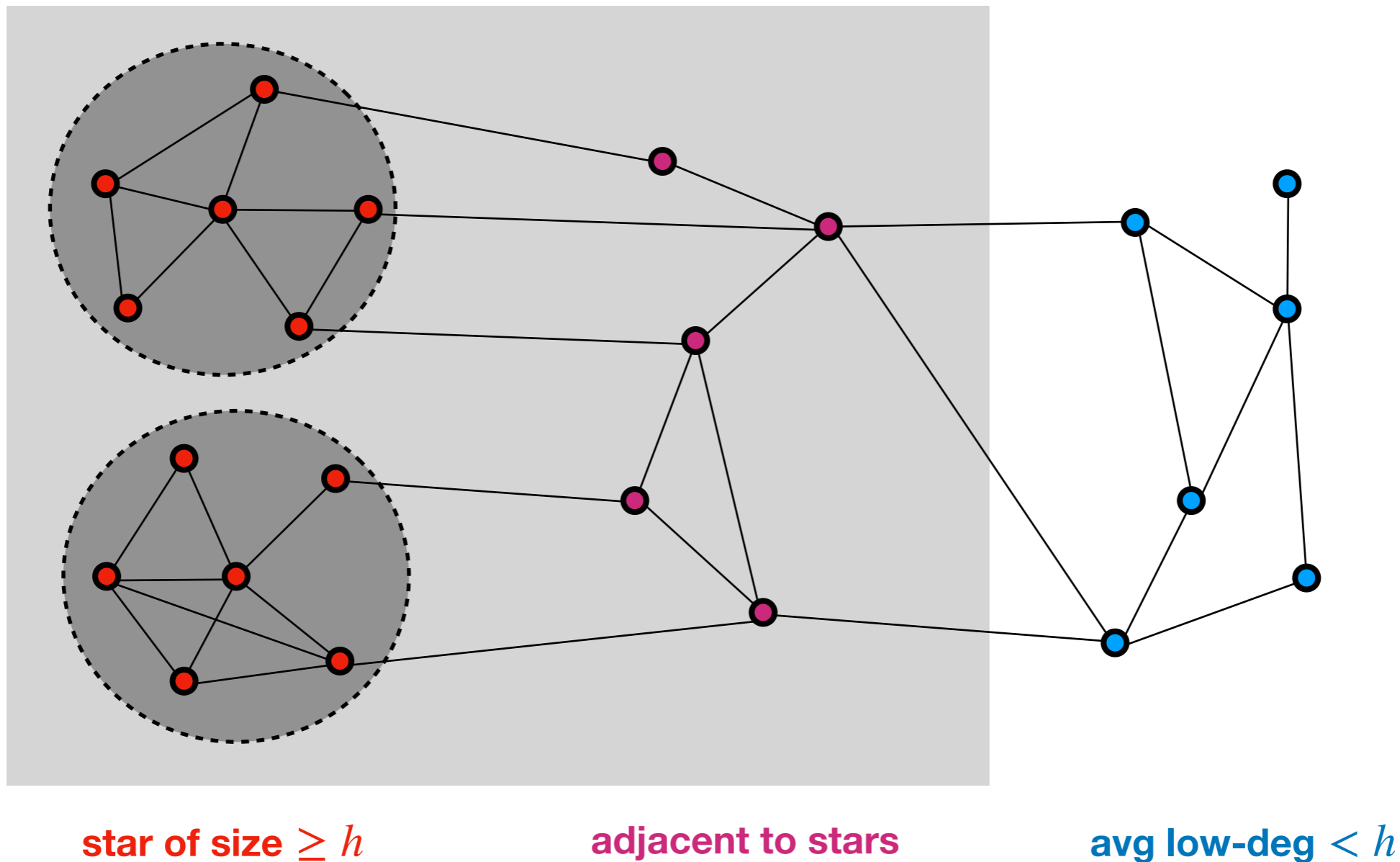


# Our technique

a more careful clustering scheme

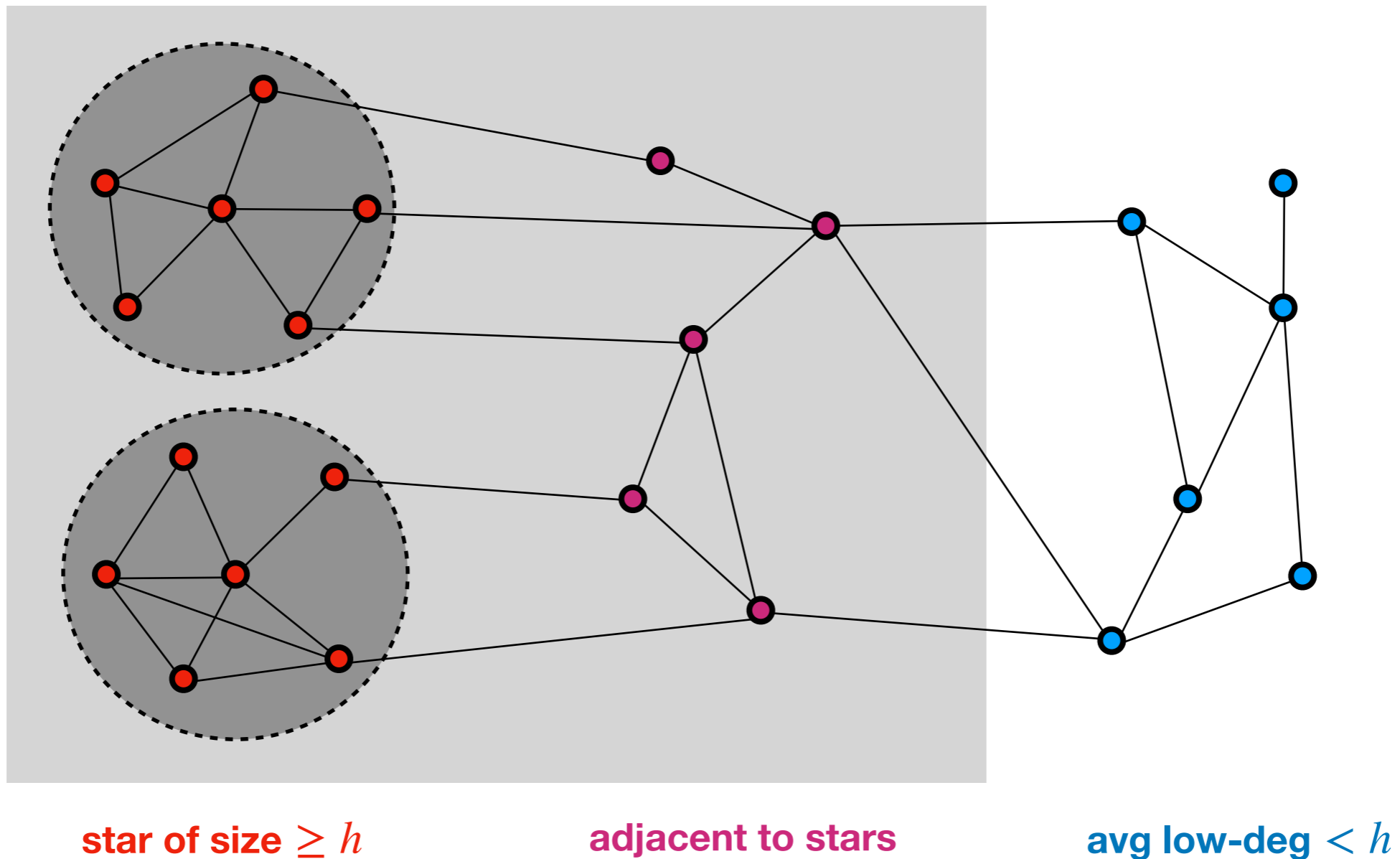
# Avoid rebuilding

- Previously in [Duan'13], the clustering scheme needs frequent rebuilding procedures
- Solution: try to **avoid rebuilding** entirely



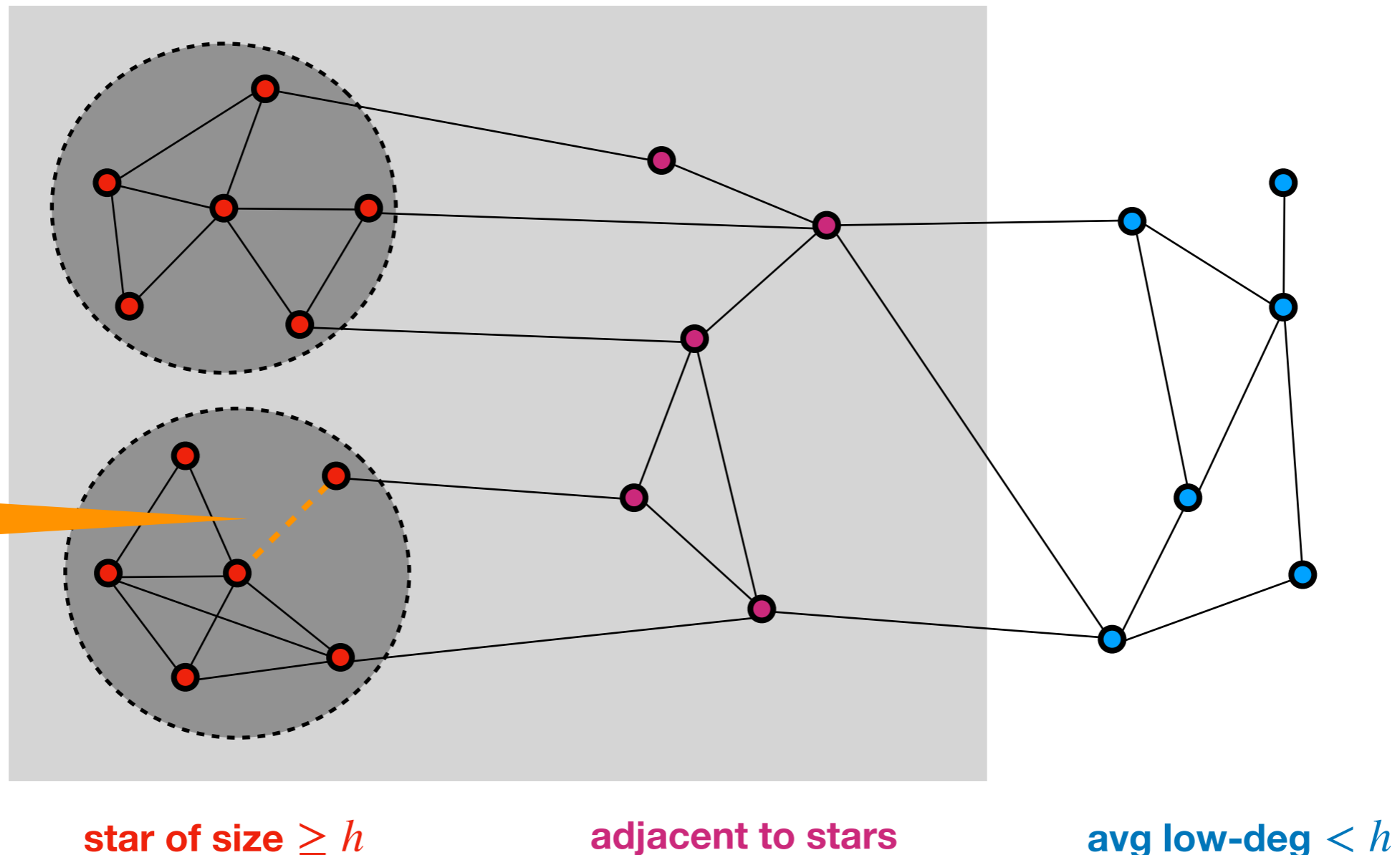
# Avoid rebuilding

- Solution: try to **avoid rebuilding** entirely
- When a star edge is deleted, if it is not adjacent to stars, either collect a **new star**, or move to **low-degree part**



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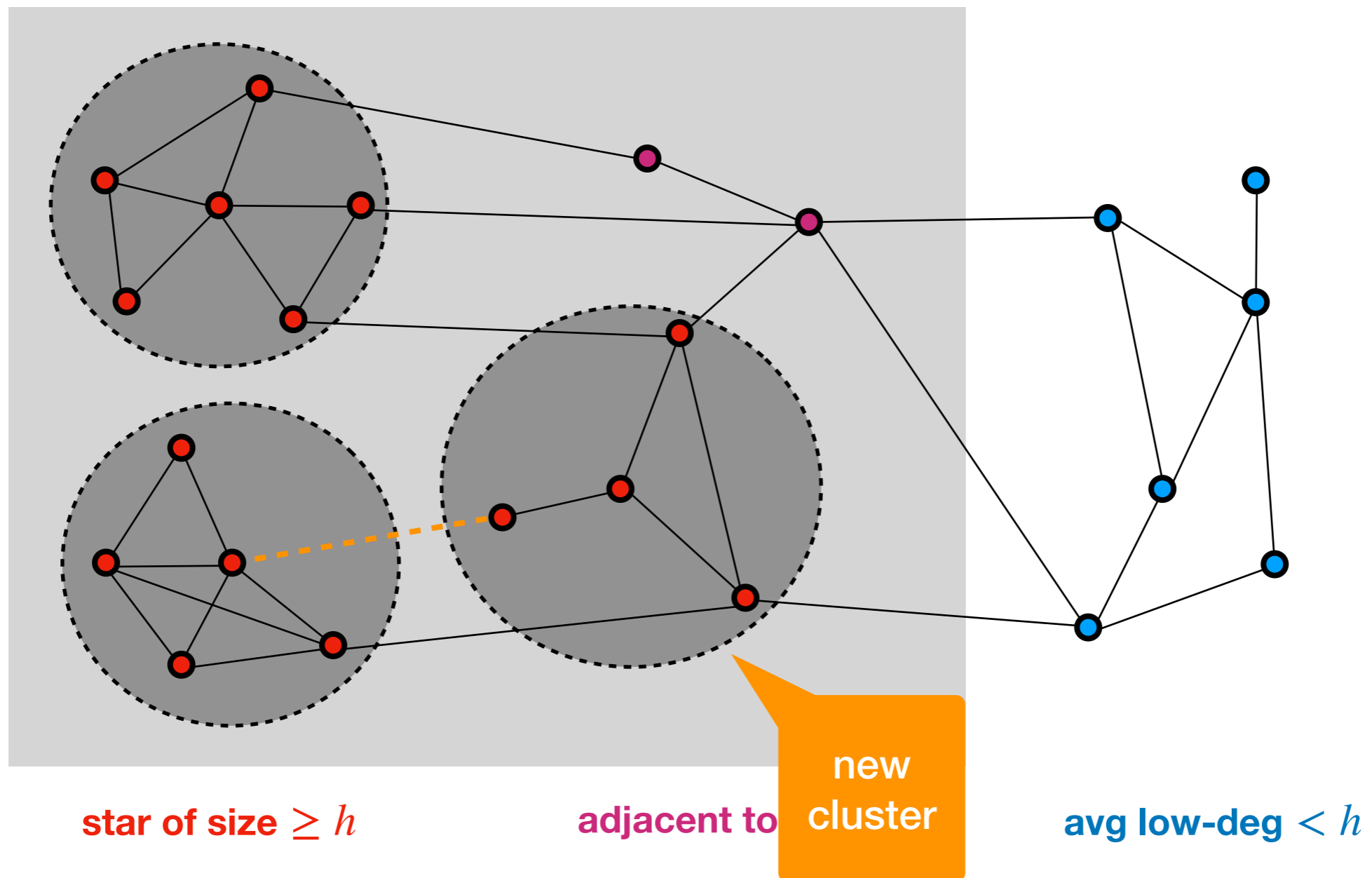
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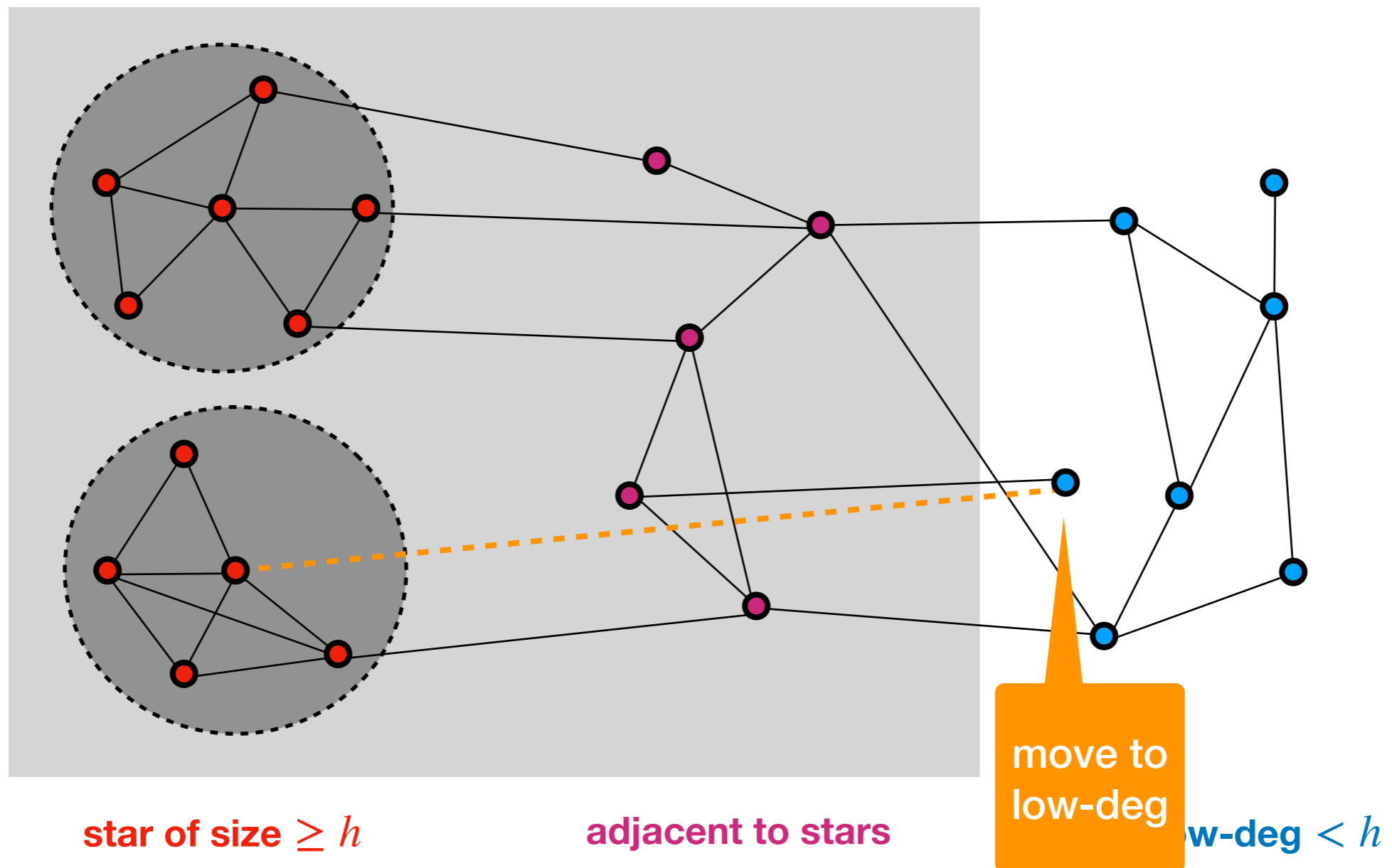
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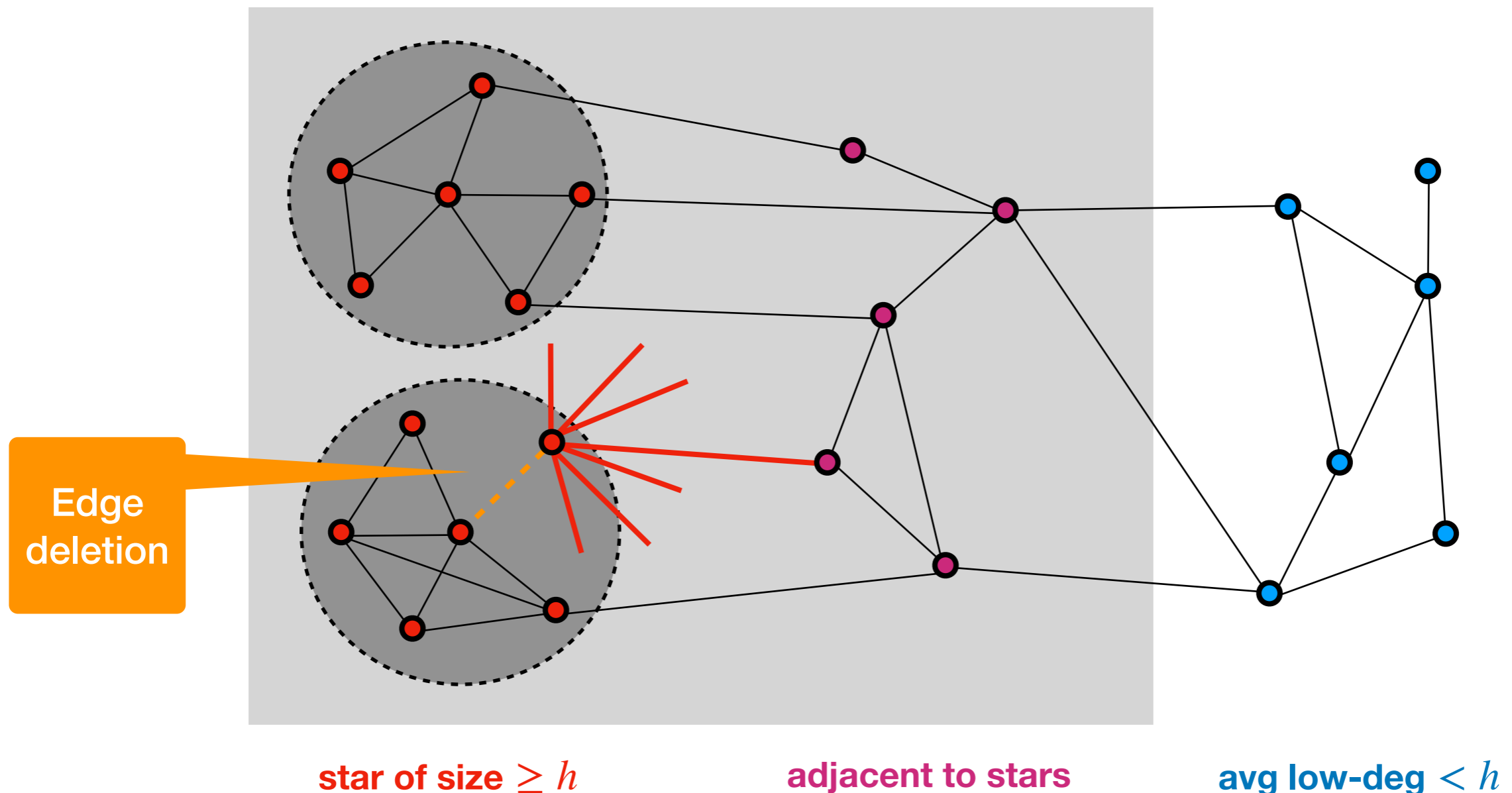
# Proof of concept

When  $\tau = \Theta(n)$

- [Duan'13] has running time  $\tilde{O}(n^{2.375})$  for max-flow
- New clustering scheme already improves to  $\tilde{O}(n^{2.25})$

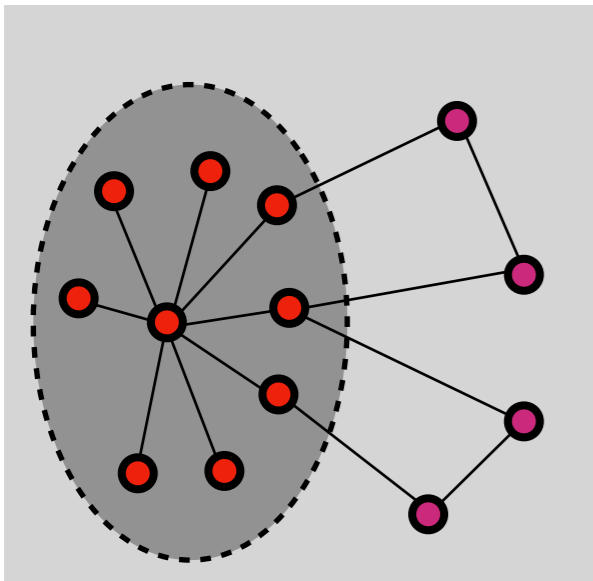
# A multi-layer approach

- Handling a deletion needs to **scan the adjacency list**  
Adjacency list can be as large as  $O(n)$
- If adjacency list is large, then can have **larger stars**  
Use **multiple layers** to handle different vertex degrees



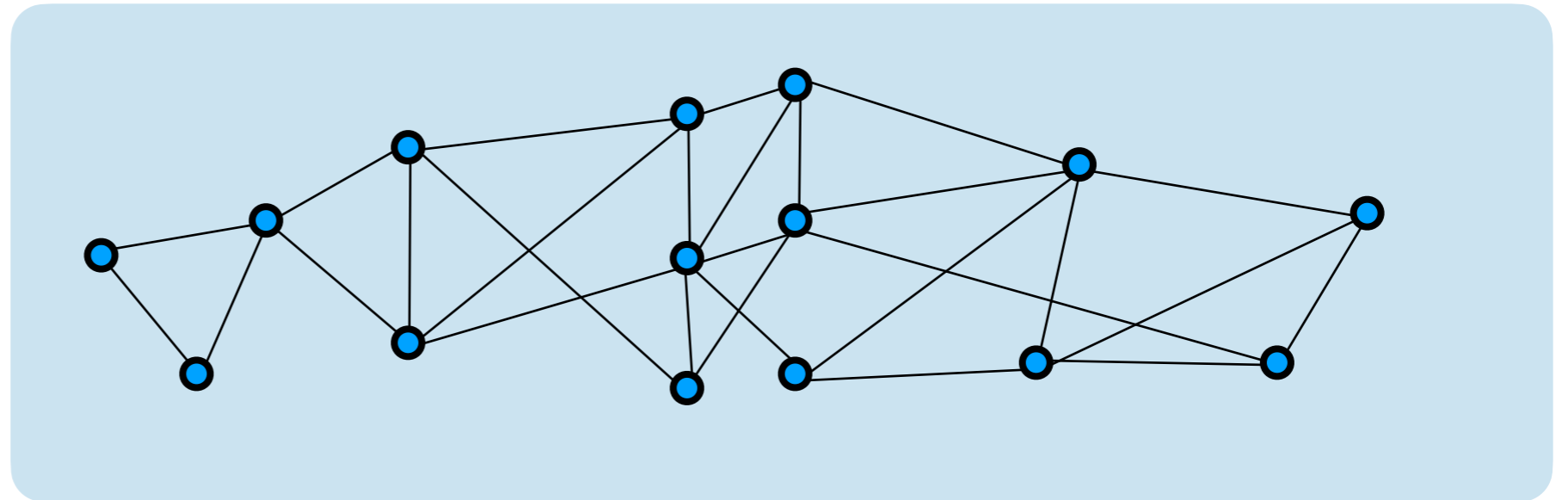
# A multi-layer approach

stars adjacent  
to stars



$$\text{deg} \leq n$$

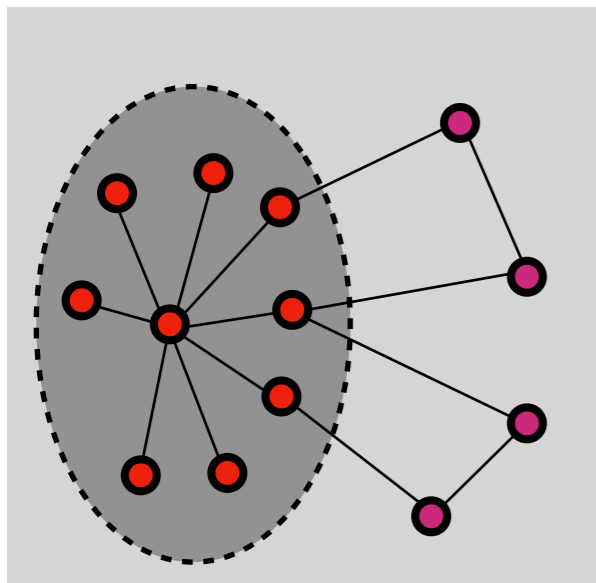
low-deg



$$\text{deg} \leq n/2$$

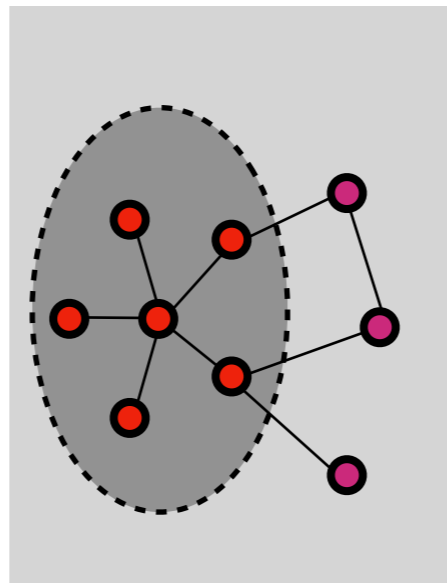
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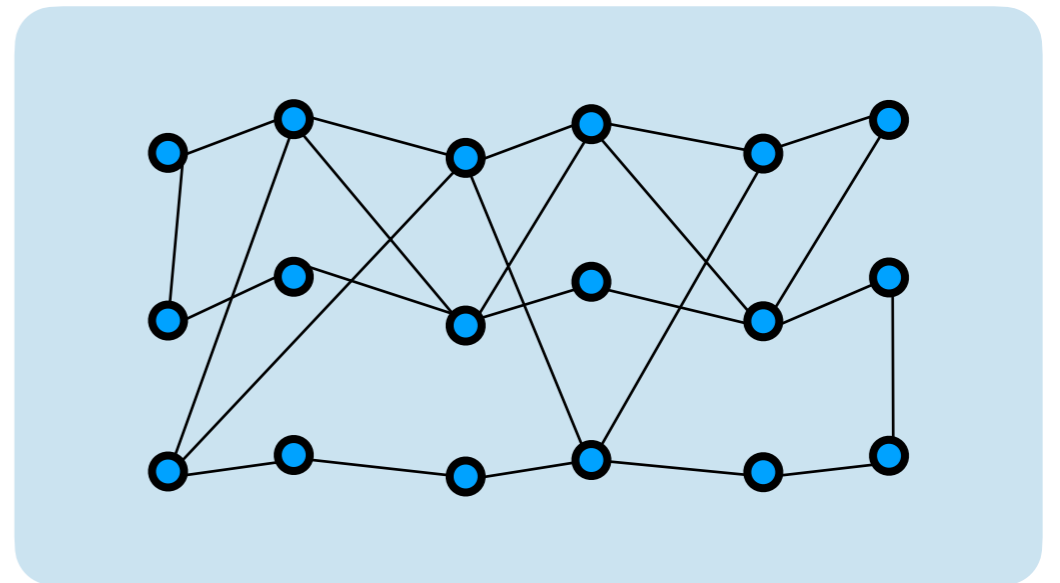
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stars adjacent  
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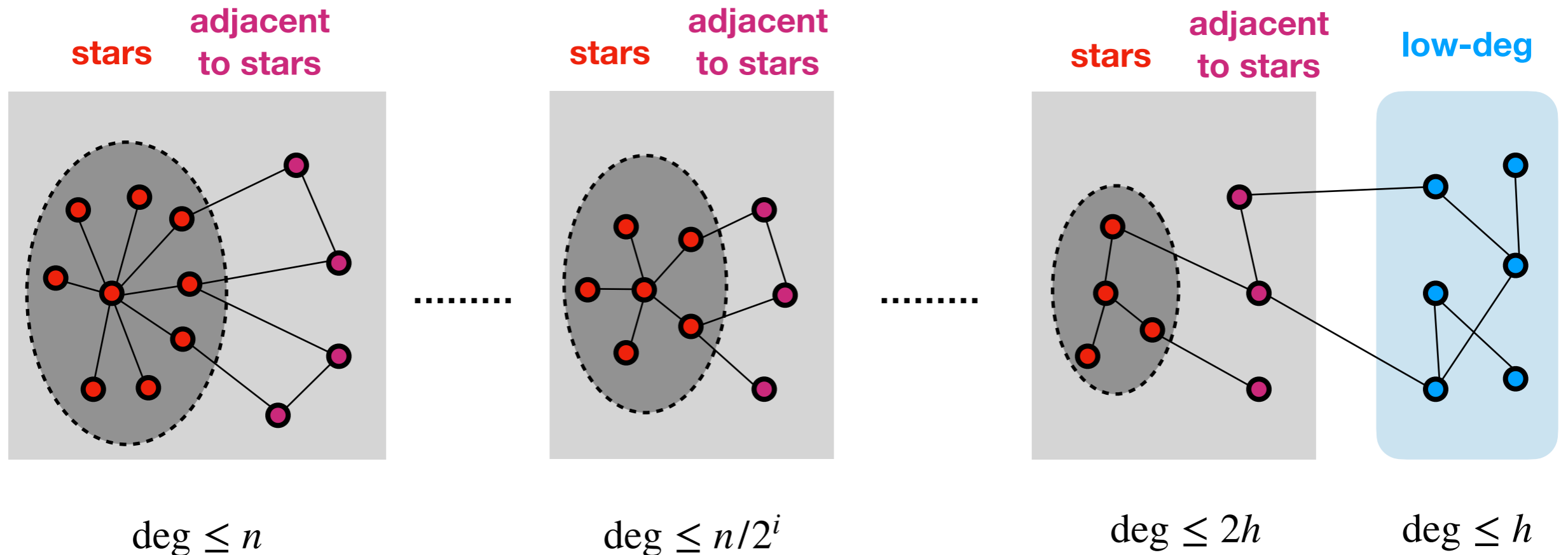
$$\text{deg} \leq n/2^i$$

low-deg

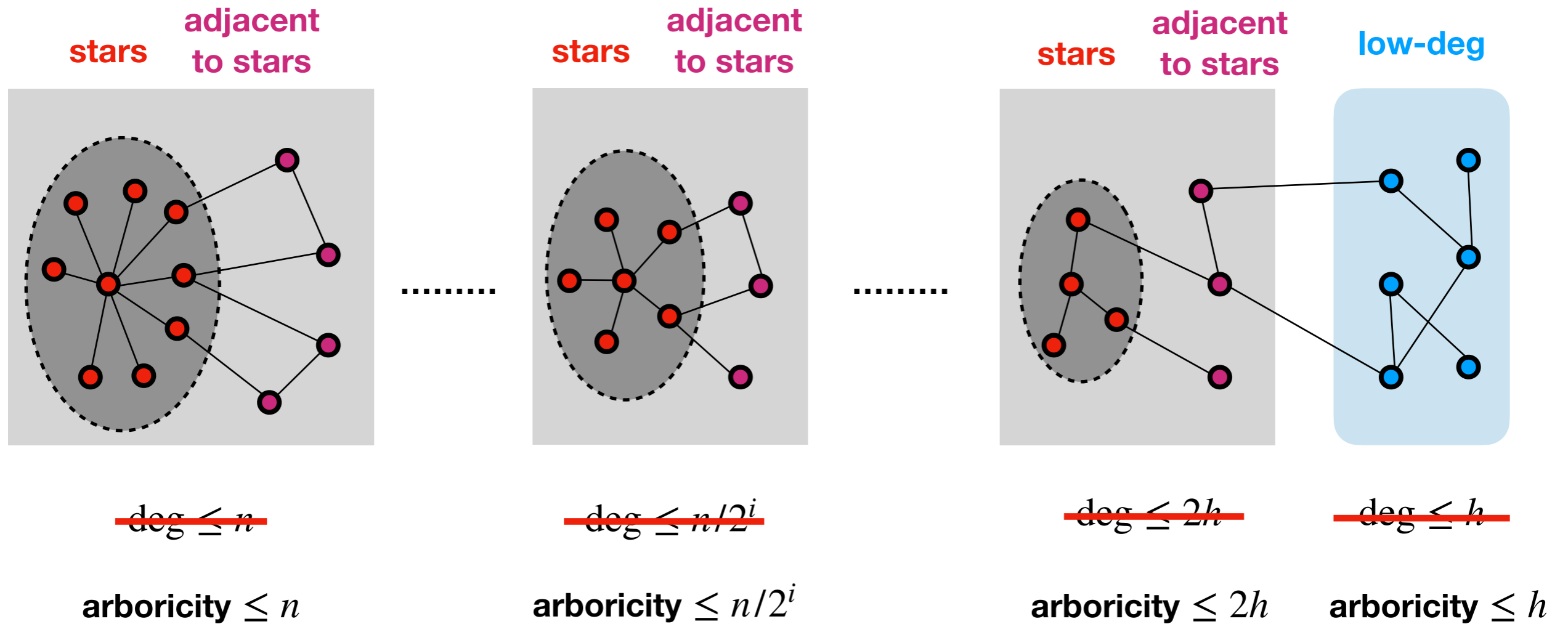


$$\text{deg} \leq n/2^{i+1}$$

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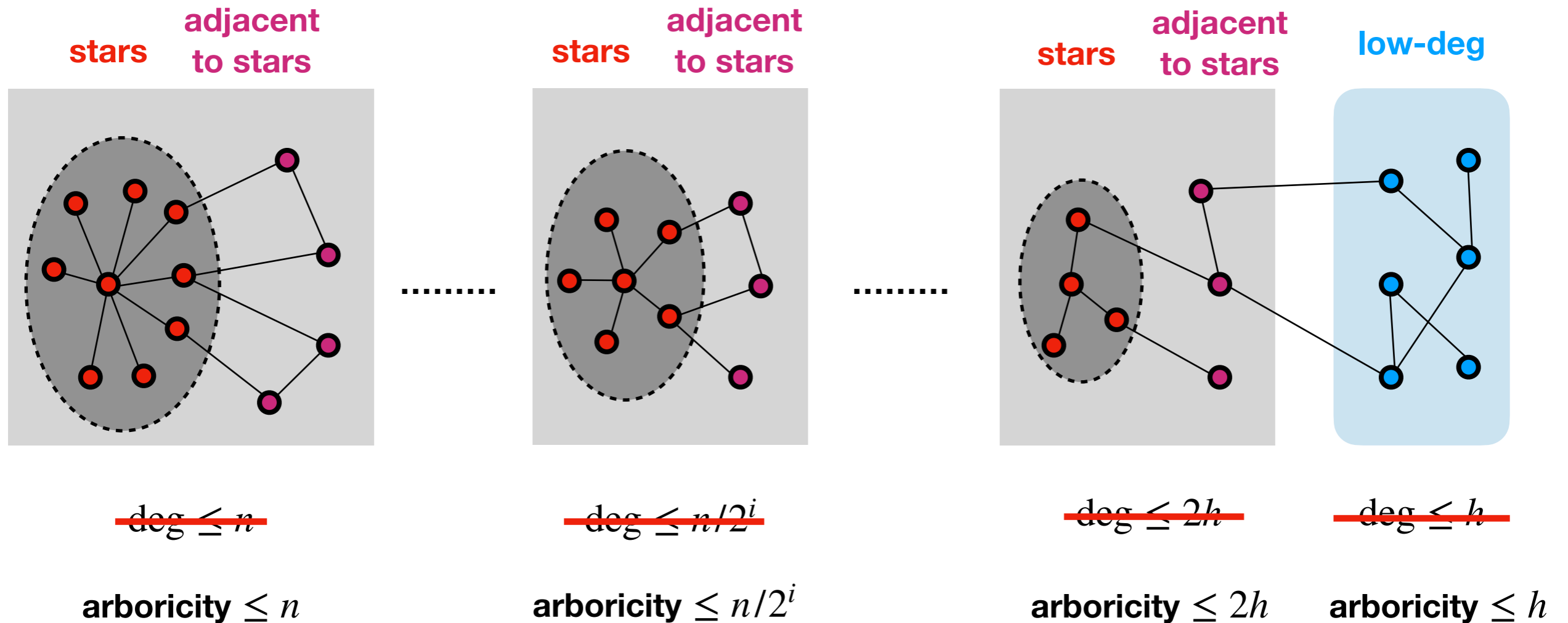


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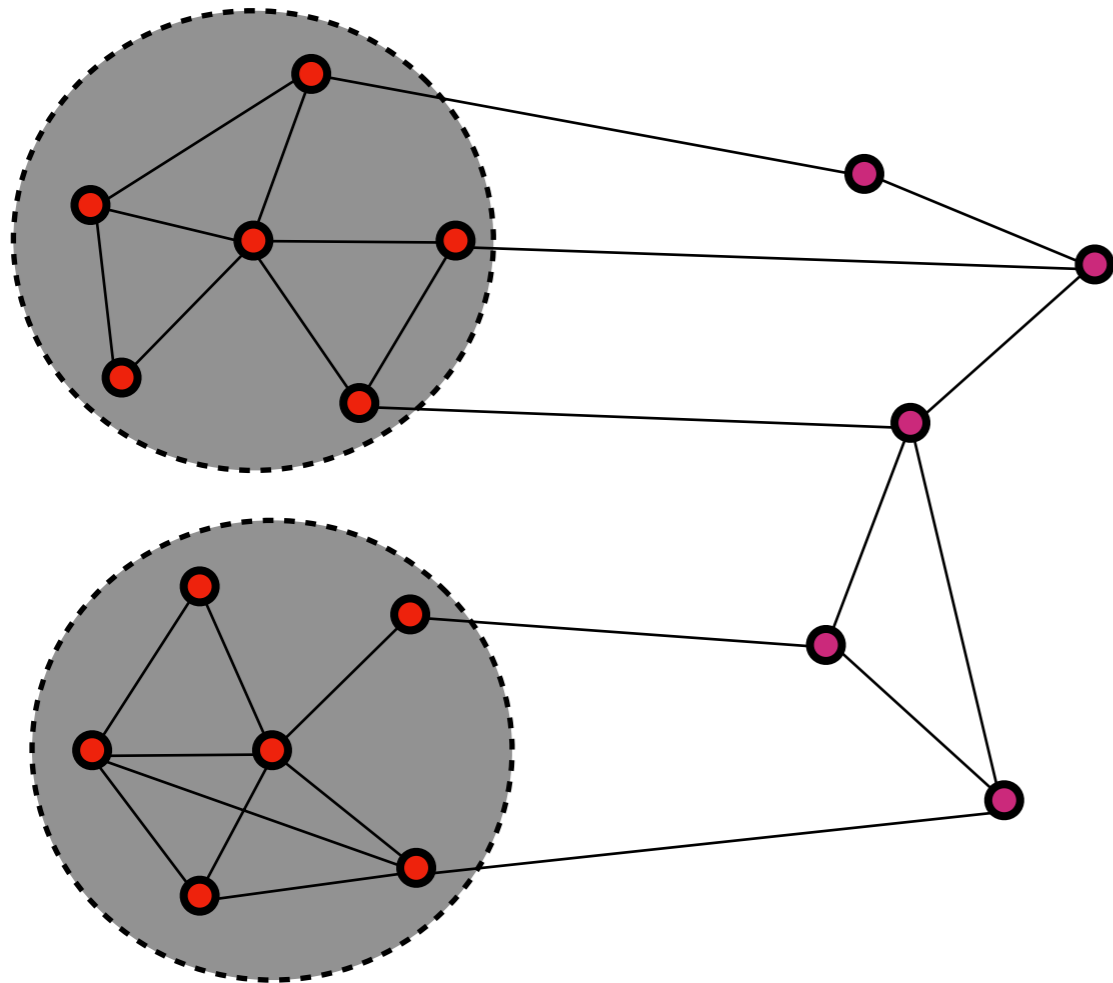


# A multi-layer approach



How to utilize low arboricity?

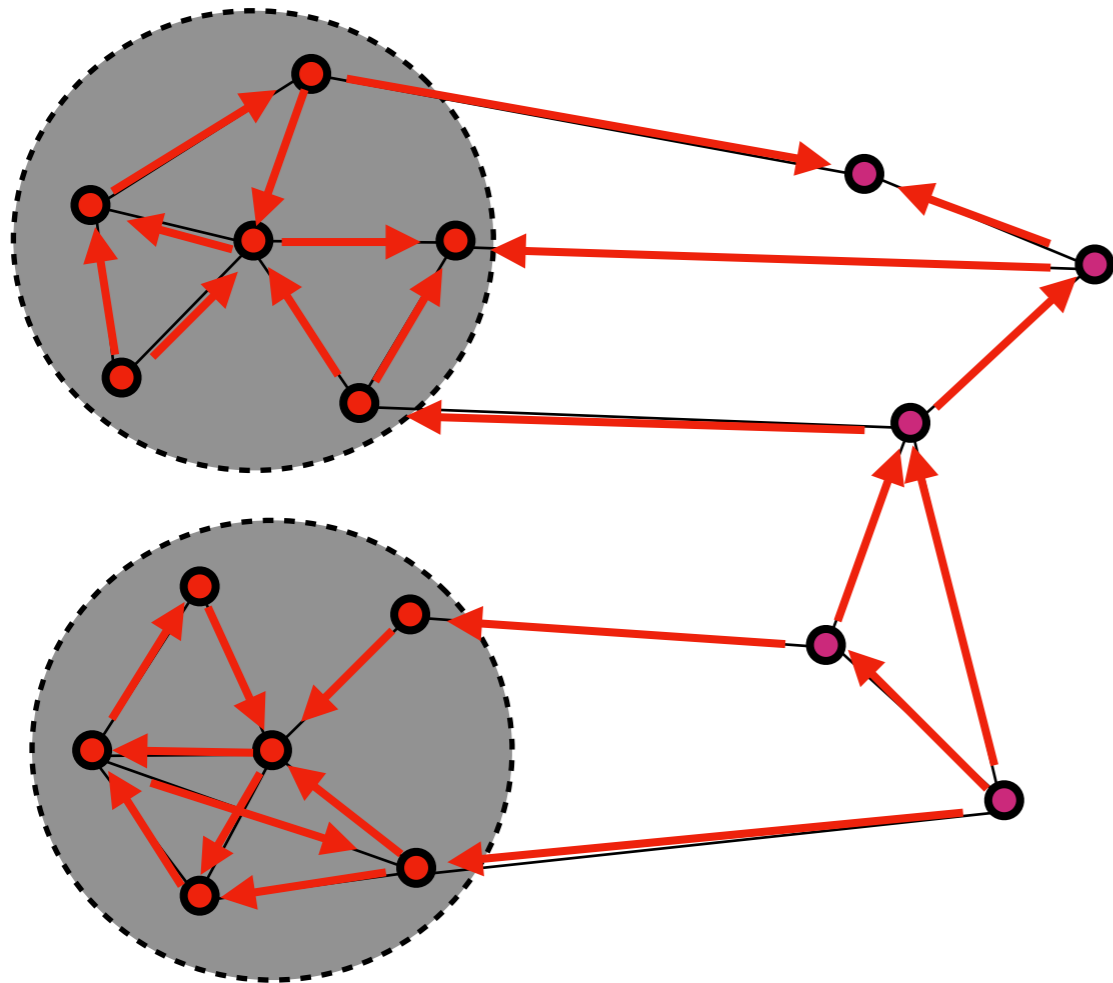
# Low arboricity



star of size  $\geq n/2^i$

adjacent to stars

# Low arboricity

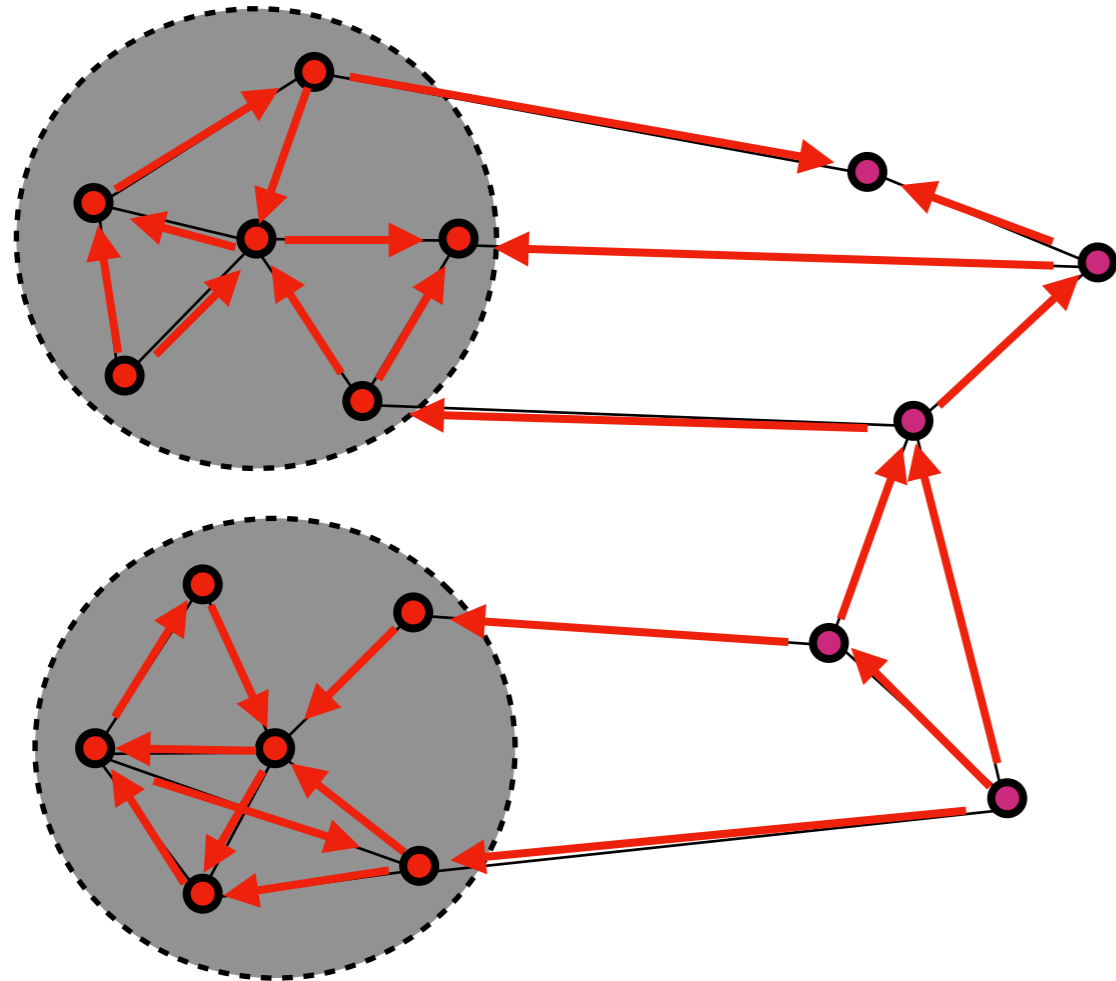


star of size  $\geq n/2^i$

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Edge orientation such that out-degrees  $\leq n/2^{i-1}$

# Low arboricity



Two kinds of operations:

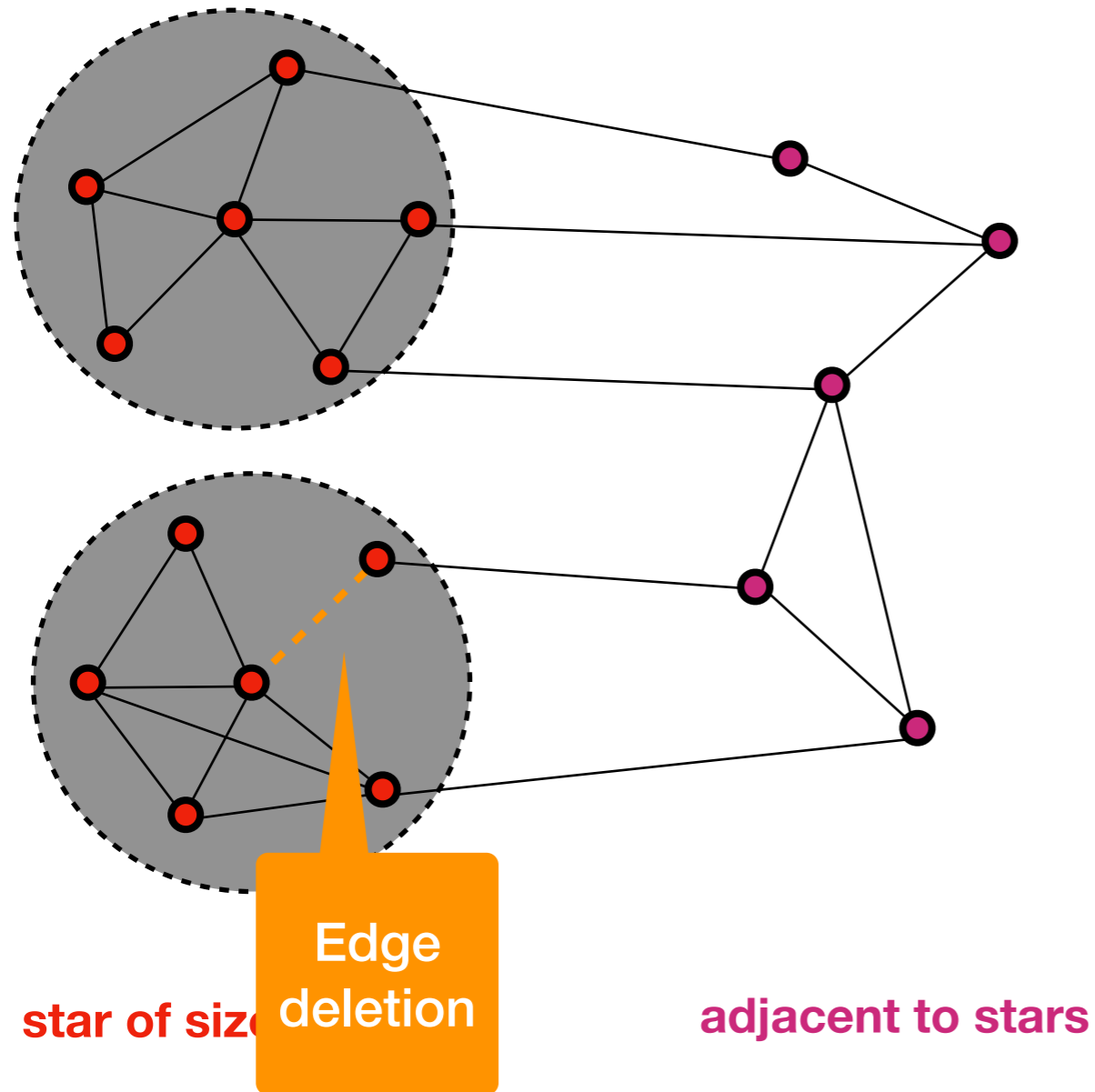
- Turn red vertices into purple vertices
- Find stars among purple vertices, and turn them red ones

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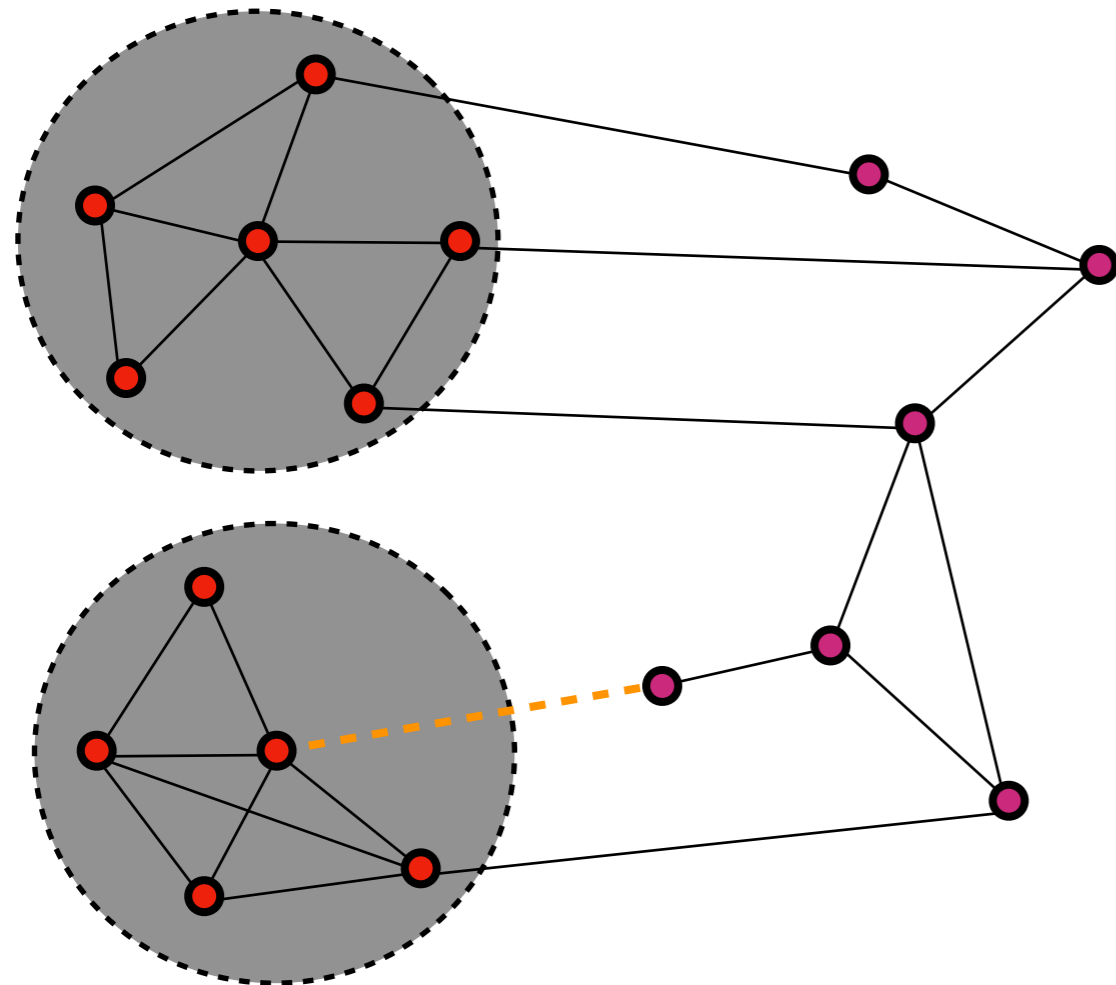
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# Low arboricity



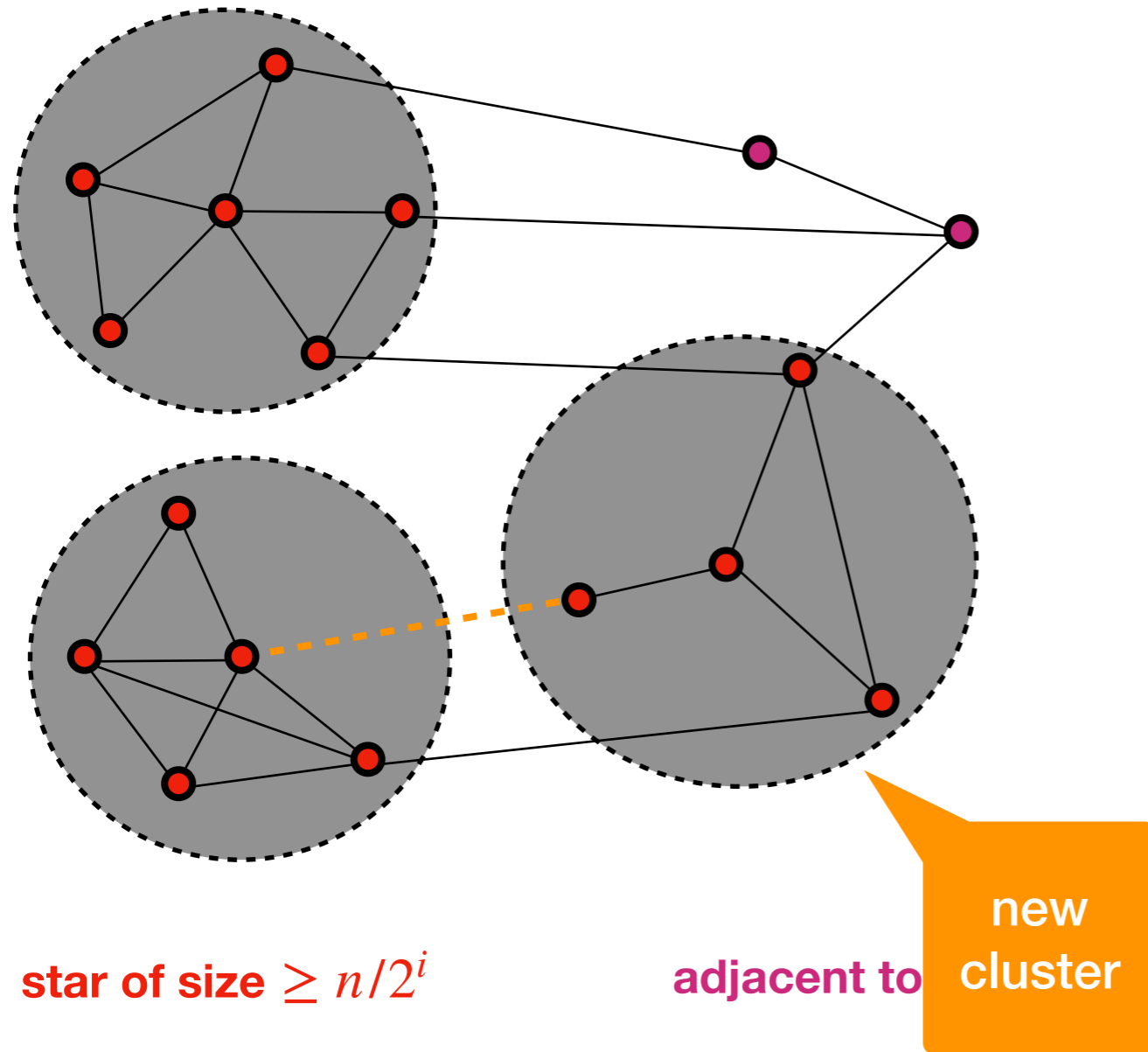
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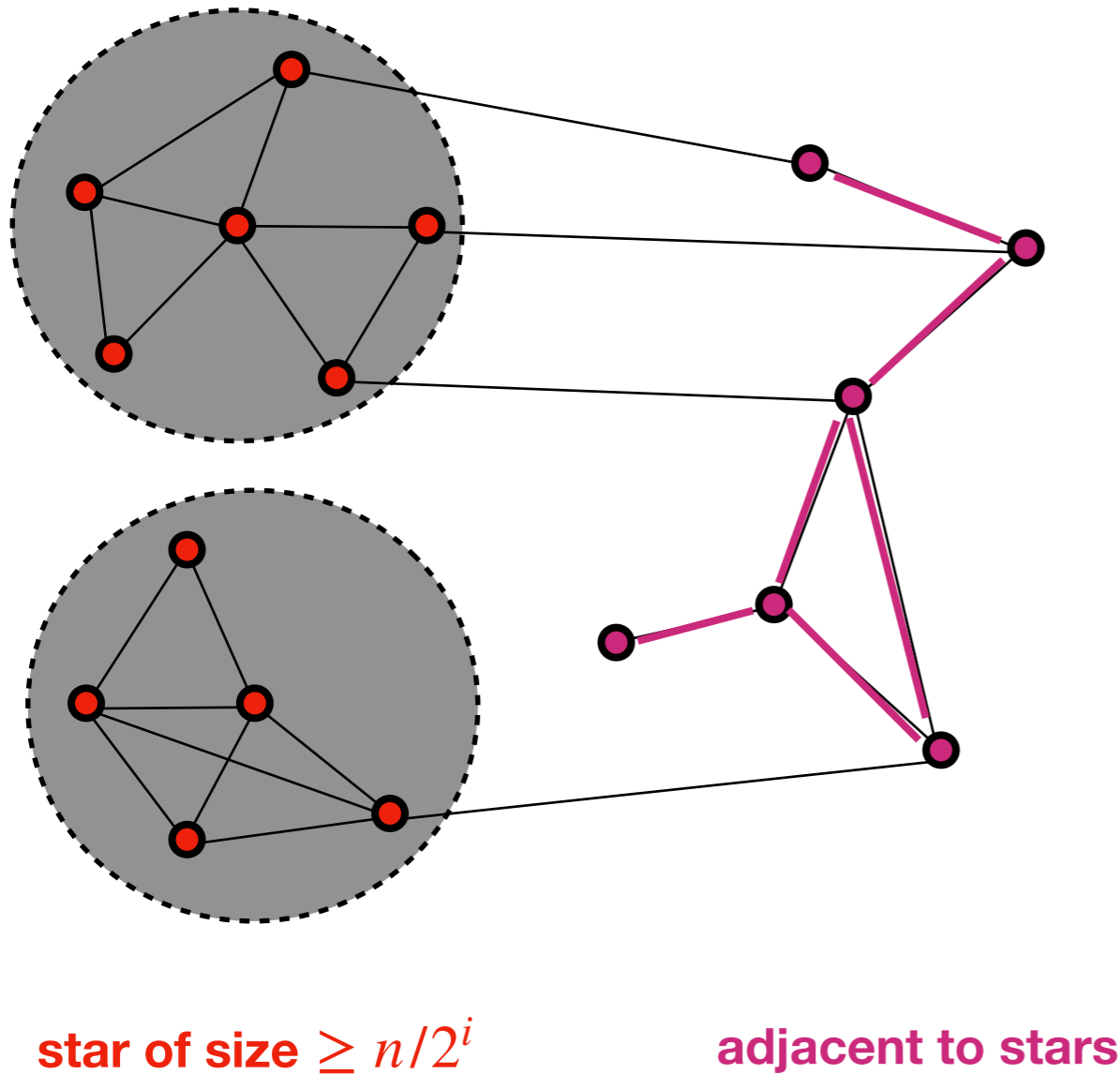
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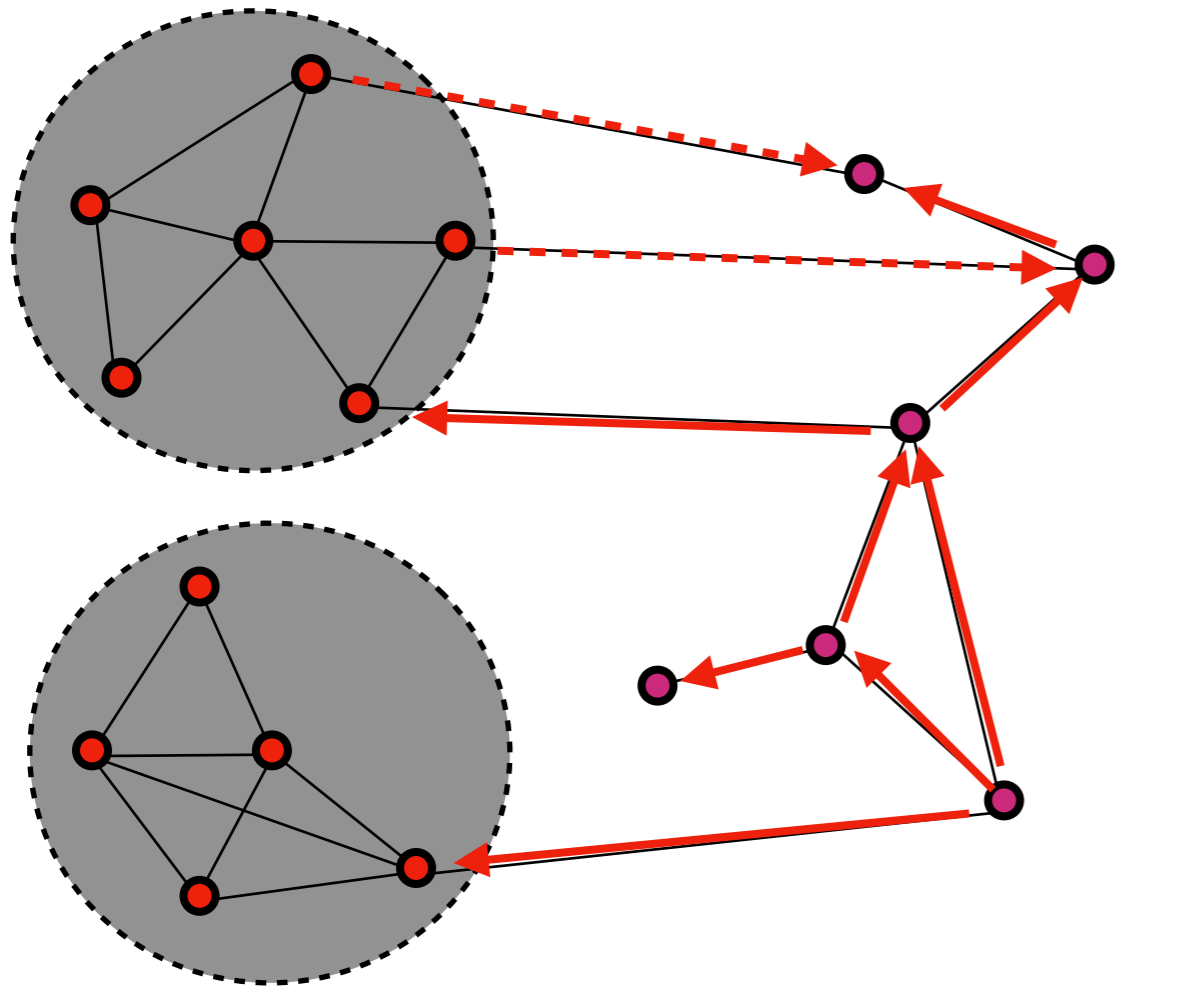
# Low arboricity



- To detect large stars, need to **explicitly store the induced subgraph on purple vertices**
- When **red**  $\rightarrow$  **purple**  
Need to scan adjacency-list to find all purple neighbors which is costly



# Low arboricity

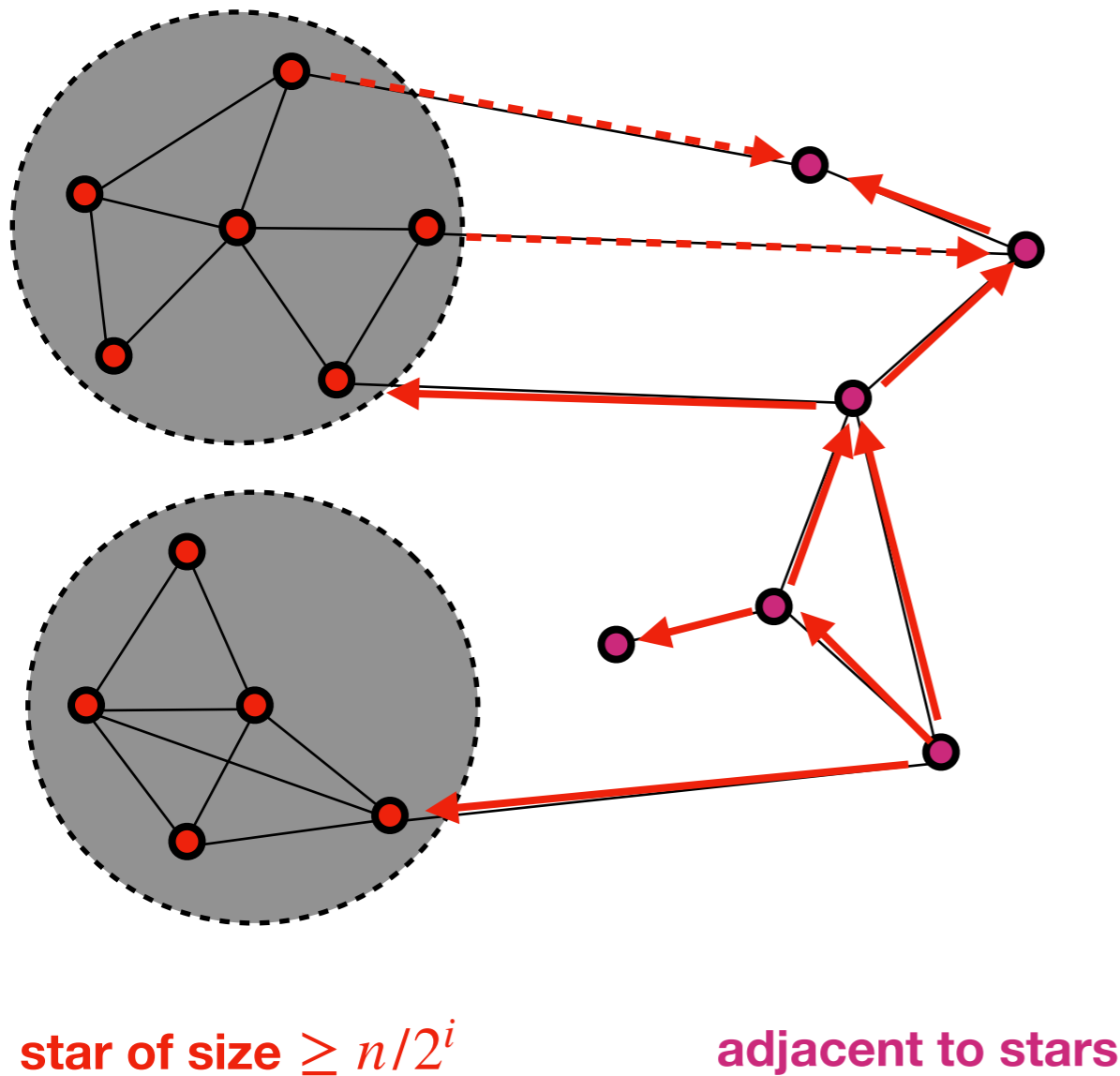


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adjacent to stars

- When **red**  $\rightarrow$  **purple**  
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- **Arboricity helps!**
- **Purple** vertices store **in/out-purple** neighbors
- **Red** vertices only store **in-purple** neighbors

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- **Arboricity helps!**
- **Purple** vertices store **in/out-purple** neighbors
- **Red** vertices only store **in-purple** neighbors
- When **red**  $\leftarrow$  **purple**  
Only need to scan out-neighbors, which is at most  $n/2^{i-1}$

# Further questions

- How about deterministic max-flow in multi-graphs?
- .... in weighted graphs?

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Thanks for listening