

Dynamic Low Stretch Spanning Trees in Sub-polynomial Time

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Sparsification

Approximate dense objects using sparse objects



masonry arch



truss arch

This example is taken from www.cosy.sbg.ac.at/~sk/talks/Salzburg2017.pdf

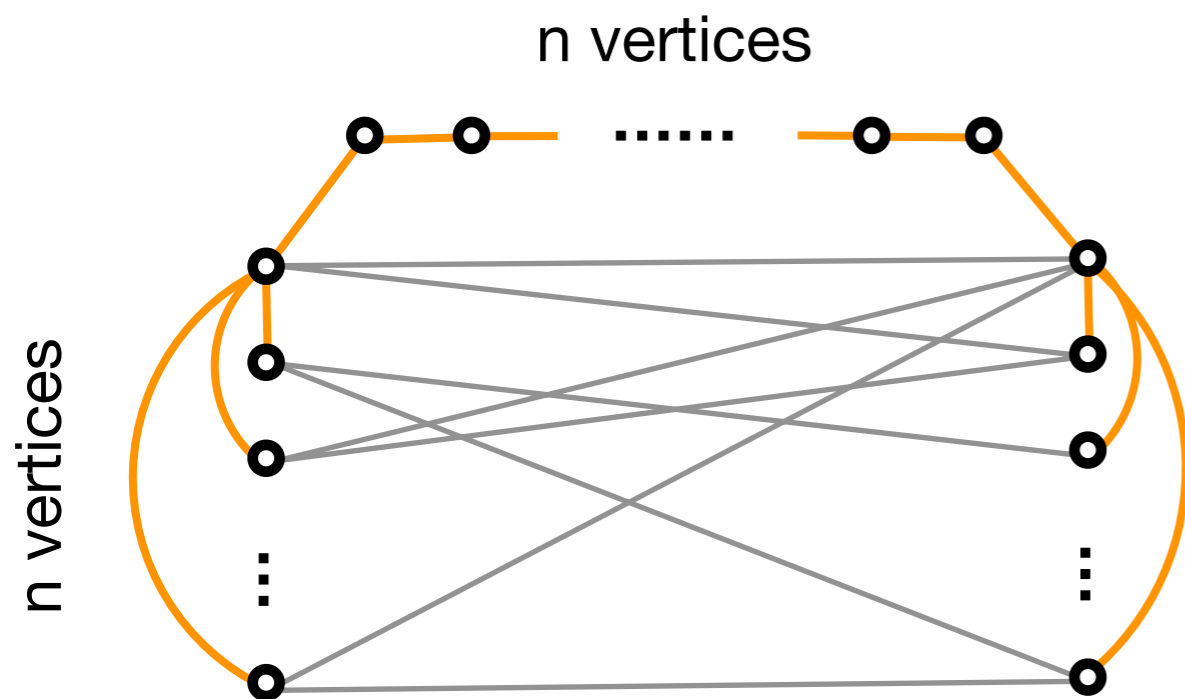
Graph sparsification

- Let $G = (V, E)$ be an undirected (multi-)graph
- Want to reduce number of edges while preserving certain graph properties
- Example:
(Spanners) Every graph has a subgraph with $O(n^{1.5})$ edges that 3-approximates pairwise distances
- What if we want to sparsify G as a **spanning tree**?

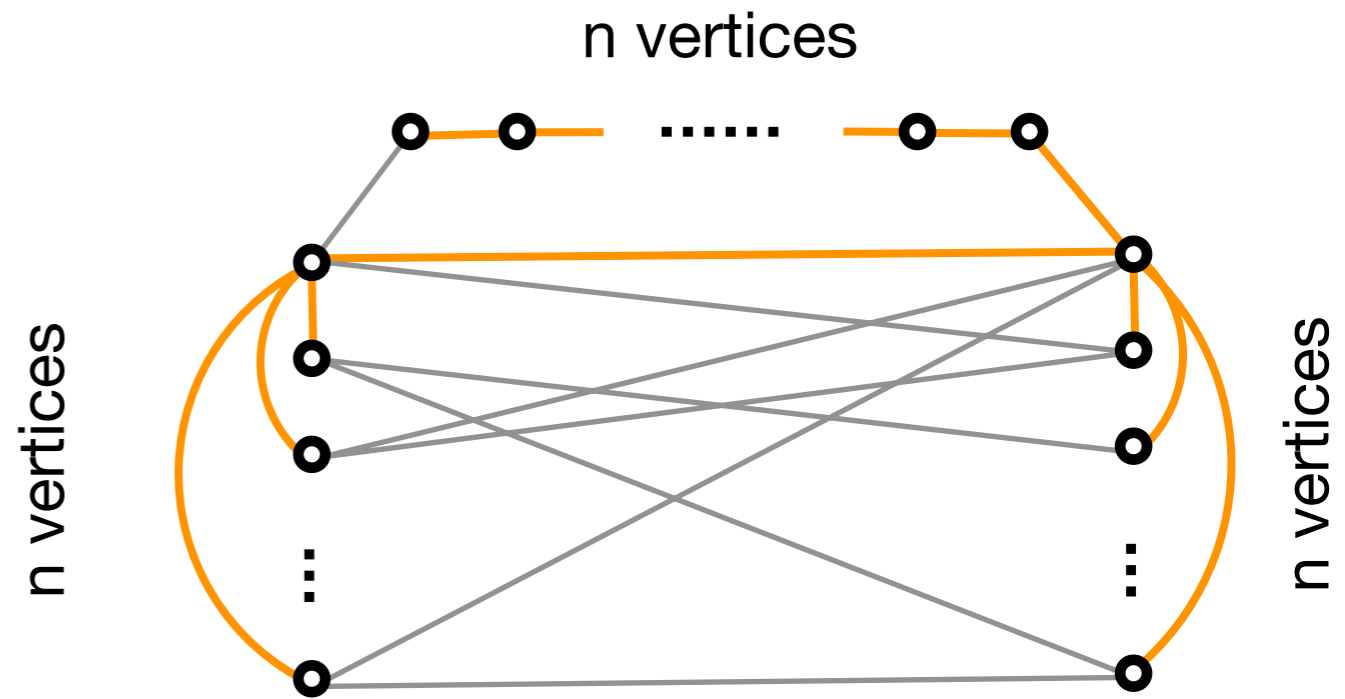
Definition: low-stretch spanning trees

- Let T be a **spanning tree** of graph G
- Want **low average stretch** of T :

$$\text{stretch of } T = \frac{1}{|E|} \sum_{(u,v) \in E} \text{dist}_T(u, v)$$



average stretch = $\Omega(n)$



average stretch = $O(1)$

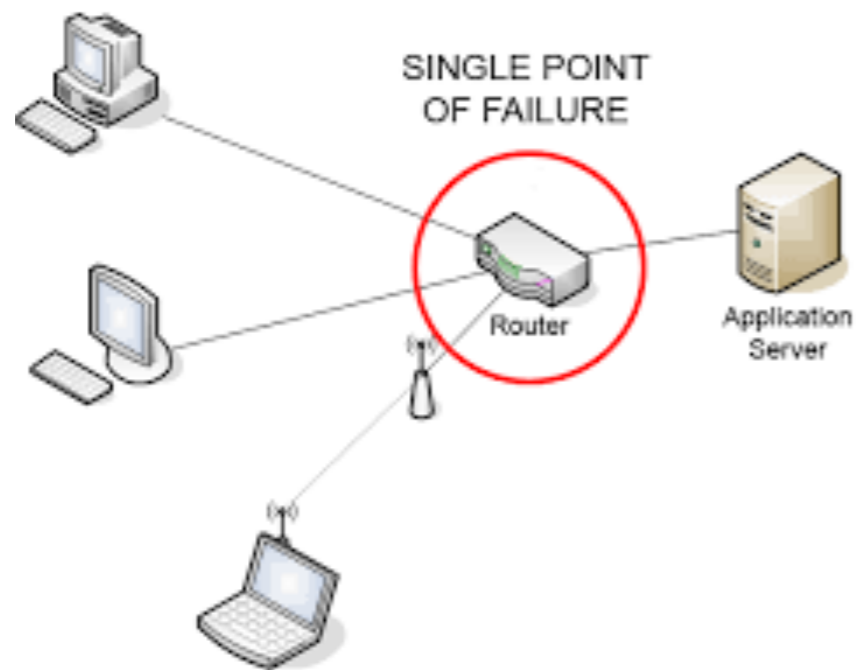
History of low-stretch trees

Reference	Average stretch	Construction time
[Alon+'95]	$\Omega(\log n)$	
[Alon+'95]	$2^{O(\sqrt{\log n \cdot \log \log n})}$	$\tilde{O}(m)$
[Elk+'08]	$O(\log^2 n \log \log n)$	$\tilde{O}(m)$
[ABN'09]	$O(\log n \cdot \log \log n \cdot (\log \log \log n)^3)$	$\tilde{O}(m)$
[AN'12]	$O(\log n \cdot \log \log n)$	$\tilde{O}(m)$

$n = \#$ vertices, $m = \#$ edges

The dynamic setting

Our world keeps changing



change of network topologies



change of traffic conditions

Definition: **dynamic** low-stretch trees

- Graph G suffers a sequence of edge insertions / deletions
- Want to maintain a spanning tree
 - Low average stretch, say $n^{o(1)}$
 - Fast update time, ideally $\log^{O(1)} n$
- Raised in [BKS'12]; first studied in [FG'19]

Our results

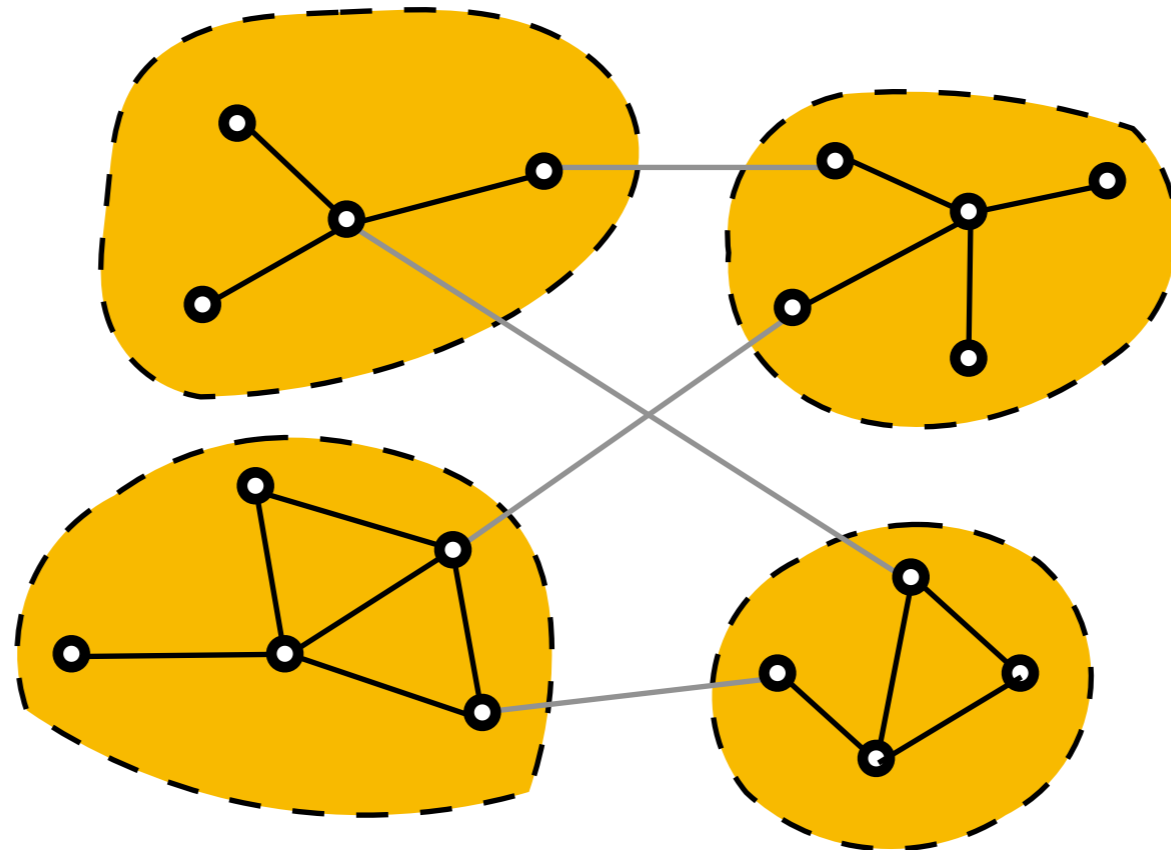
- [FG'19]
Average stretch: $n^{o(1)}$
Randomized update time: $n^{1/2+o(1)}$
- [CZ'20]
Average stretch: $n^{o(1)}$
Randomized update time: $n^{o(1)}$
- Extend to **weighted** graphs but only with edge **deletions**
- In this talk, we only focus on **unweighted** graphs

An overview of [Alon+'95]

Low diameter decomposition

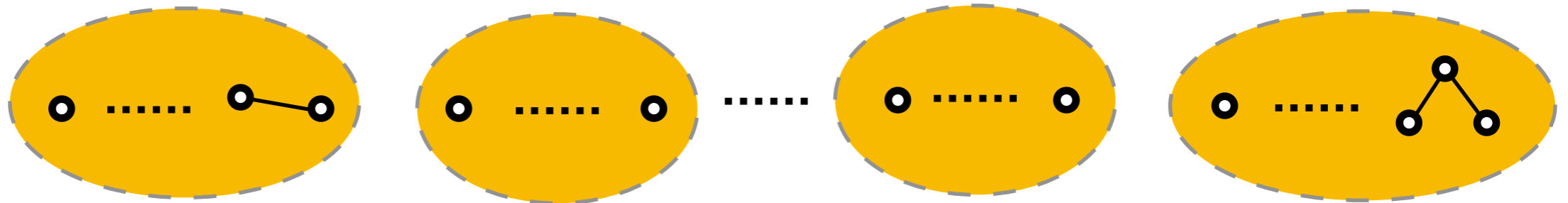
Definition: A β -decomposition is a partition of V into clusters C_1, C_2, \dots, C_k such that:

- (1) diameter of each $G[C_i]$ is $\leq O\left(\frac{\log n}{\beta}\right)$
- (2) number of inter-cluster edges is $\leq \beta m$

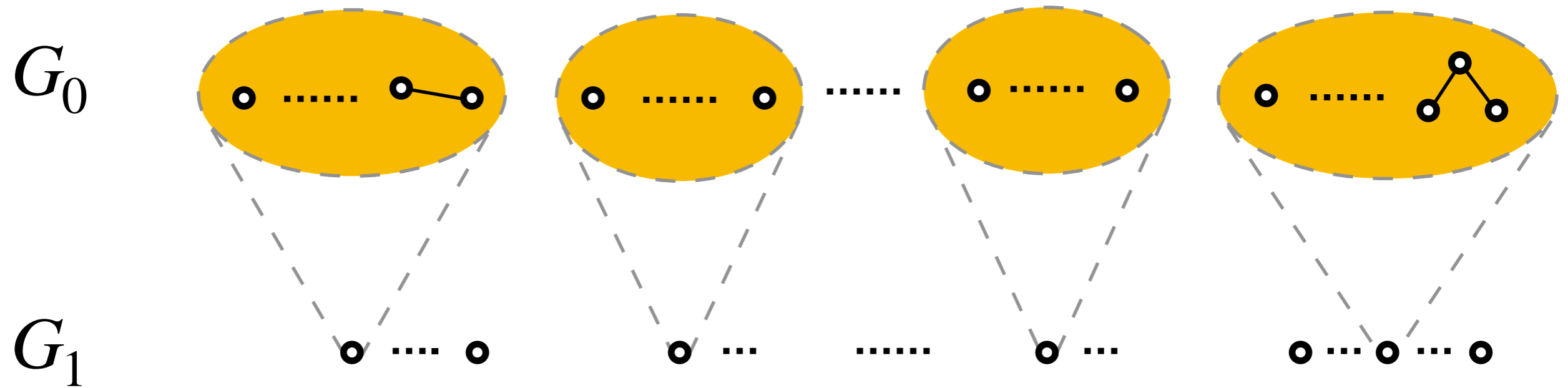


Hierarchical clustering

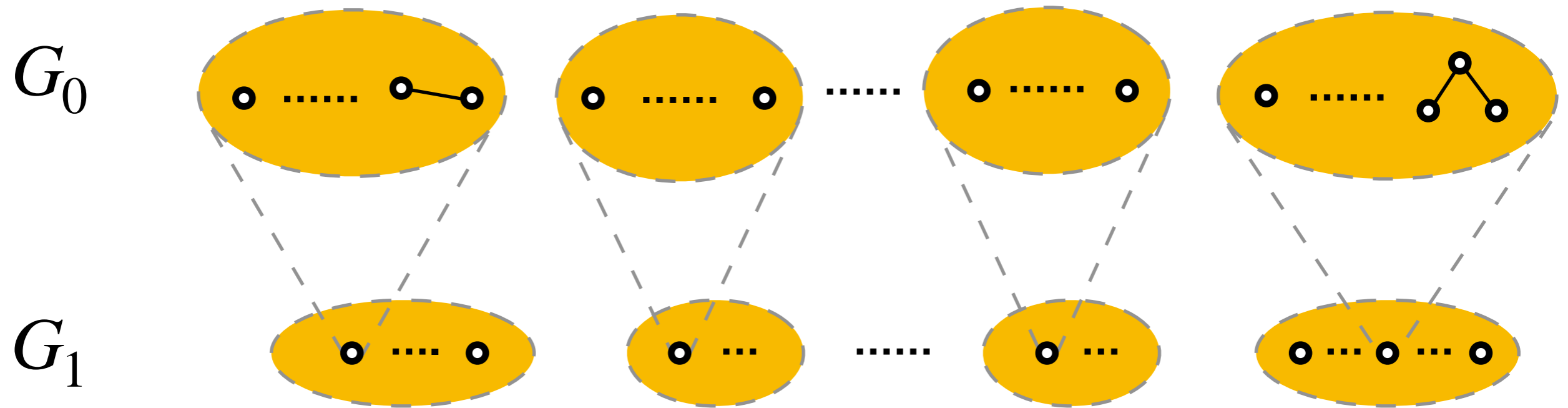
G_0



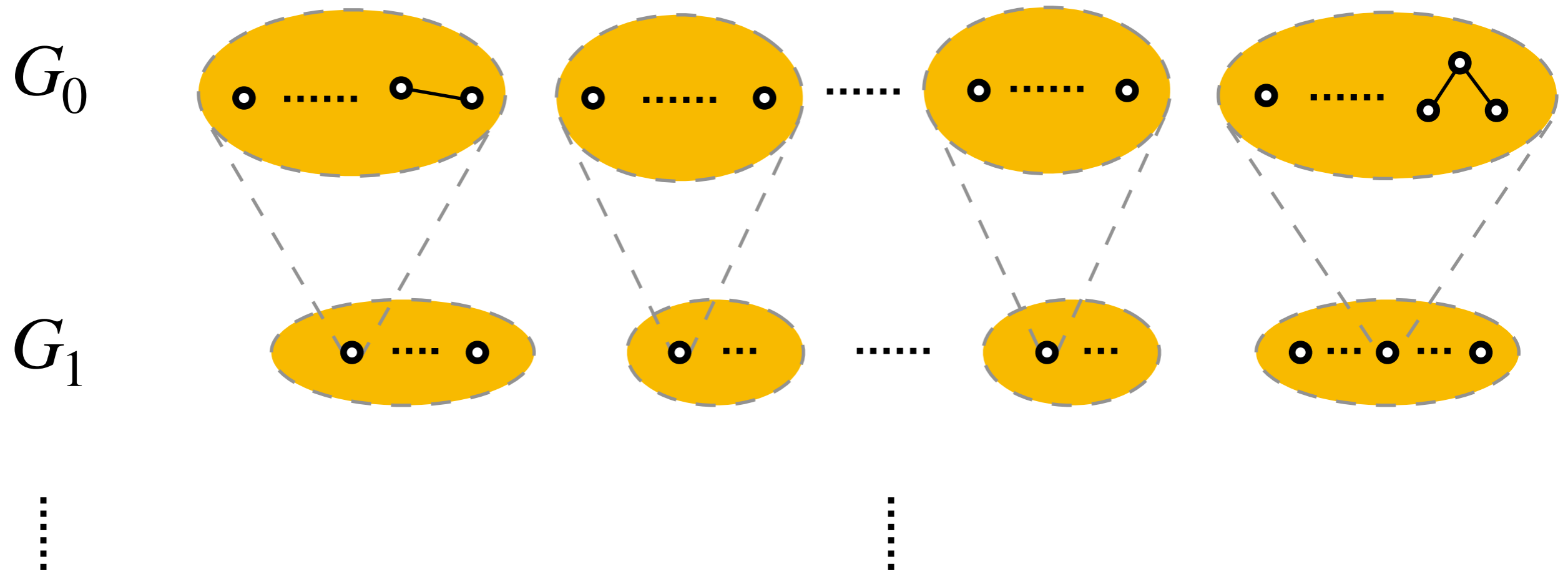
Hierarchical clustering



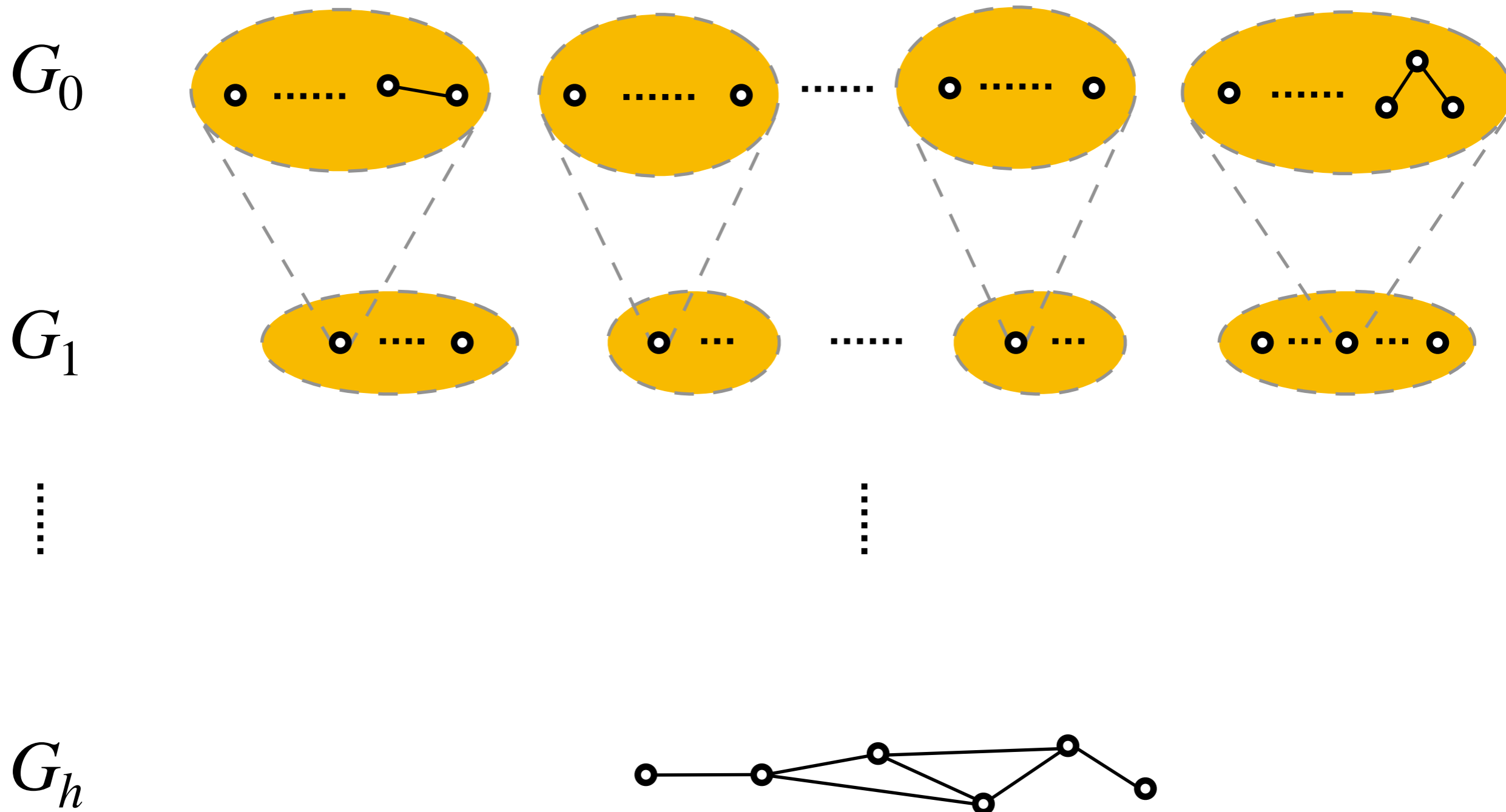
Hierarchical clustering



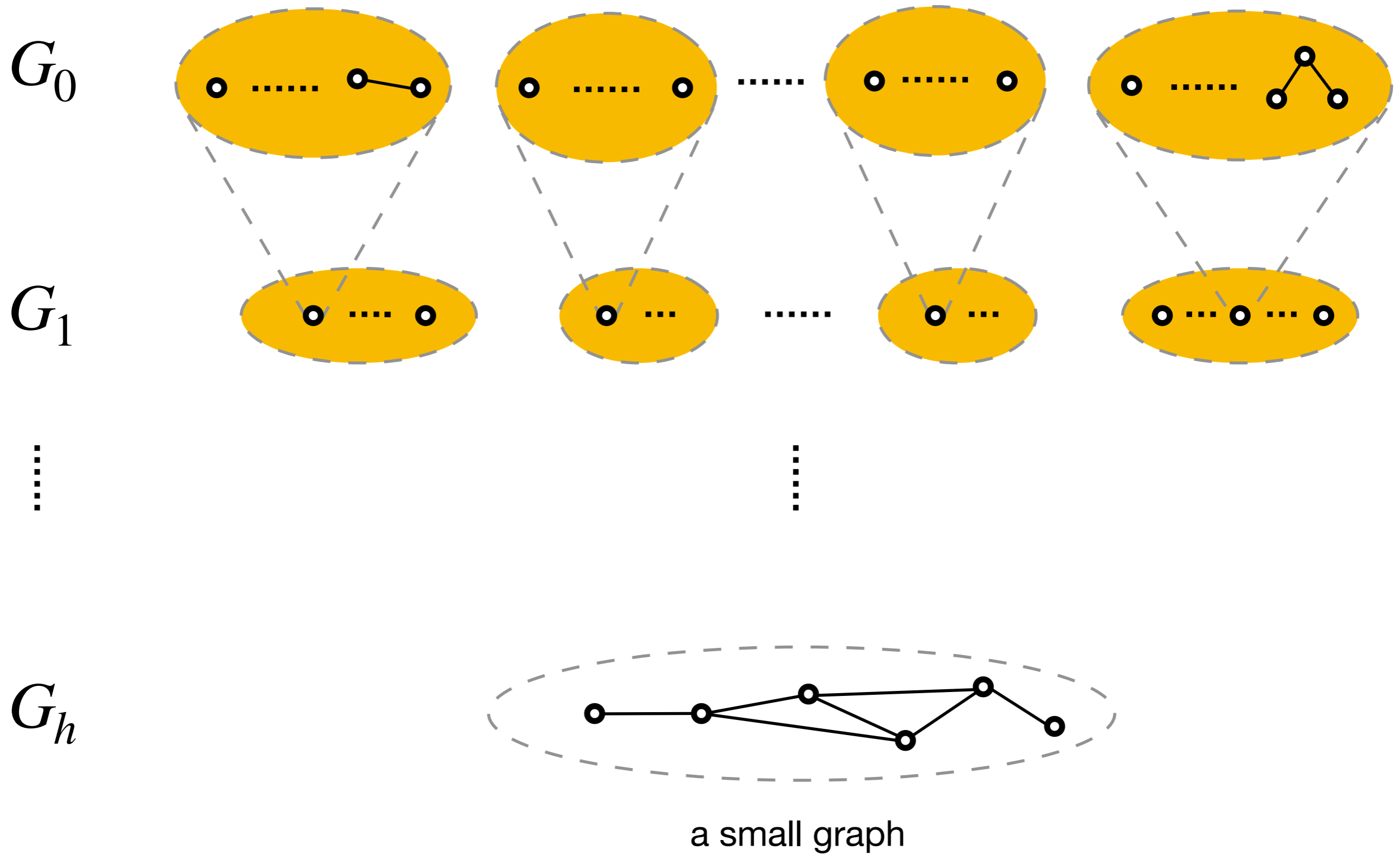
Hierarchical clustering



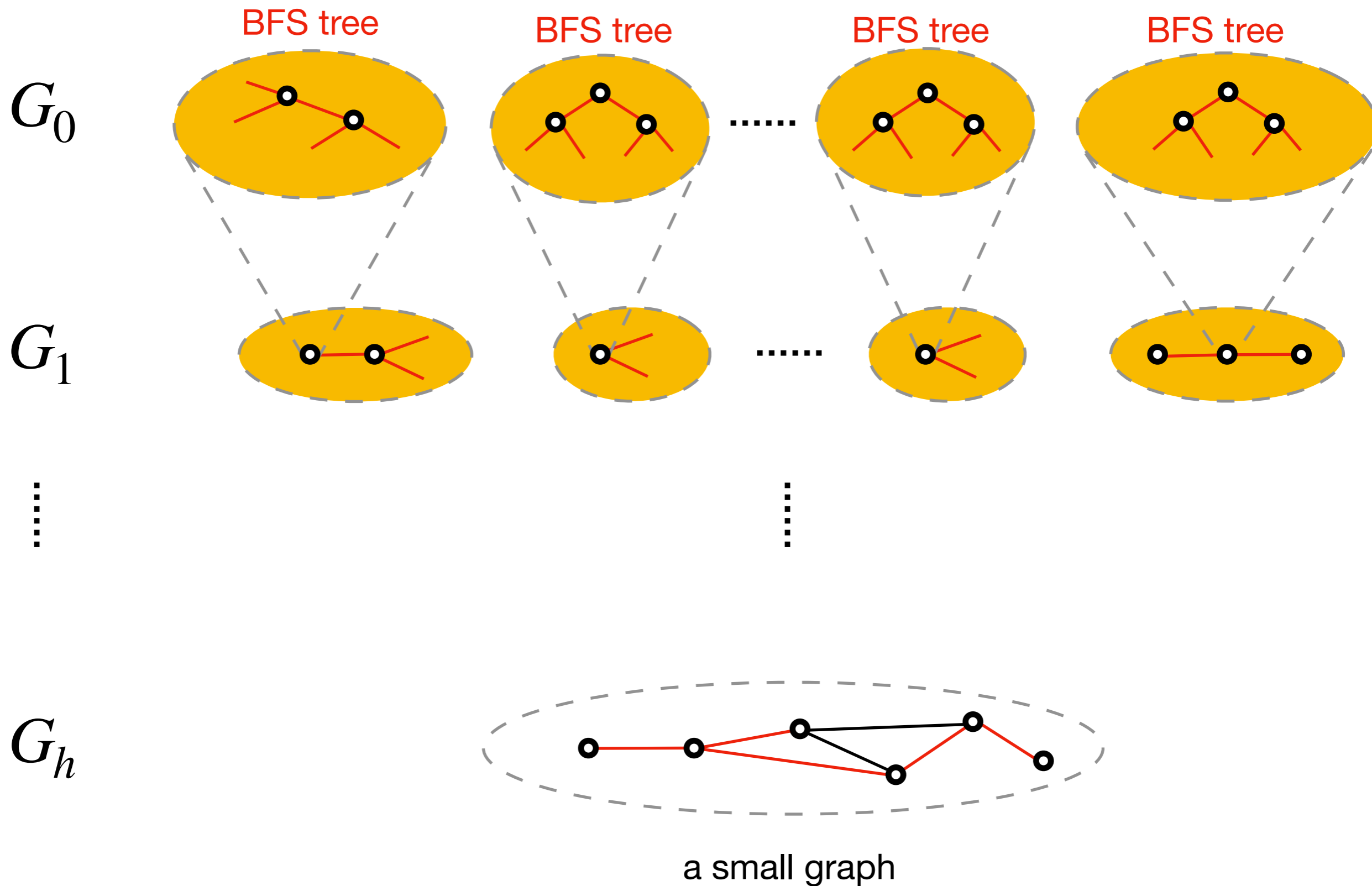
Hierarchical clustering



Hierarchical clustering



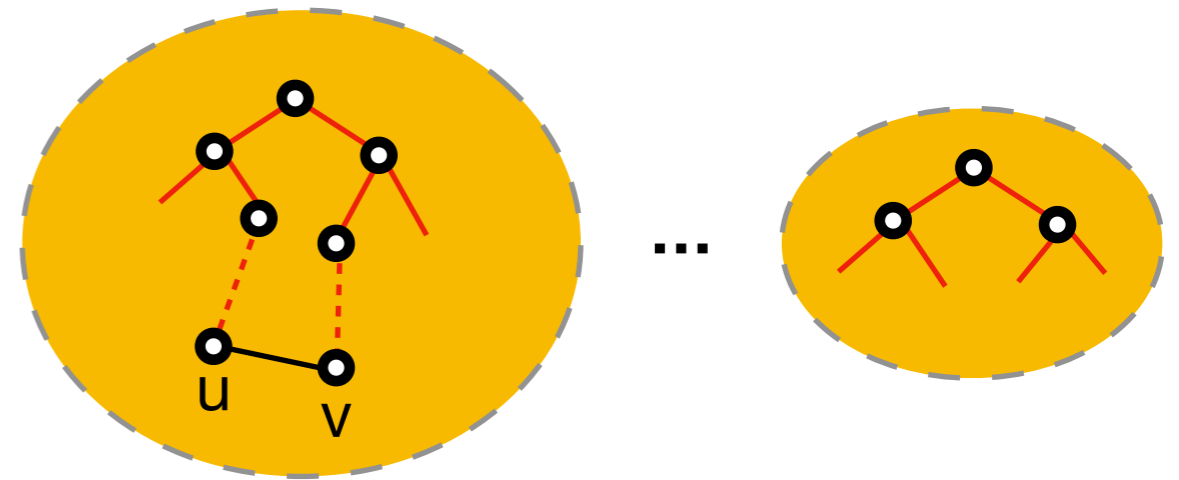
Low-stretch spanning tree



Average stretch

- Diameter of node in G_i is at most $(\log n/\beta)^i$
- Number of edges in G_i is at most $\beta^i m$
- Stretch of any intra-cluster edge in $G_i \setminus G_{i+1}$ is $(\log n/\beta)^{i+1}$
- Total stretch becomes $m^{1+o(1)}$

contracted graph G_i



$$\mathbf{dist}_T(u, v) \leq (\log n/\beta)^{i+1}$$

$$\sum_{(u,v) \in G_i \setminus G_{i+1}} \mathbf{dist}_T(u, v) \leq m \log^{i+1} n/\beta$$

$$\sum_{0 \leq i \leq h} \sum_{(u,v) \in G_i \setminus G_{i+1}} \mathbf{dist}_T(u, v) \leq m \log^{h+1} n/\beta$$

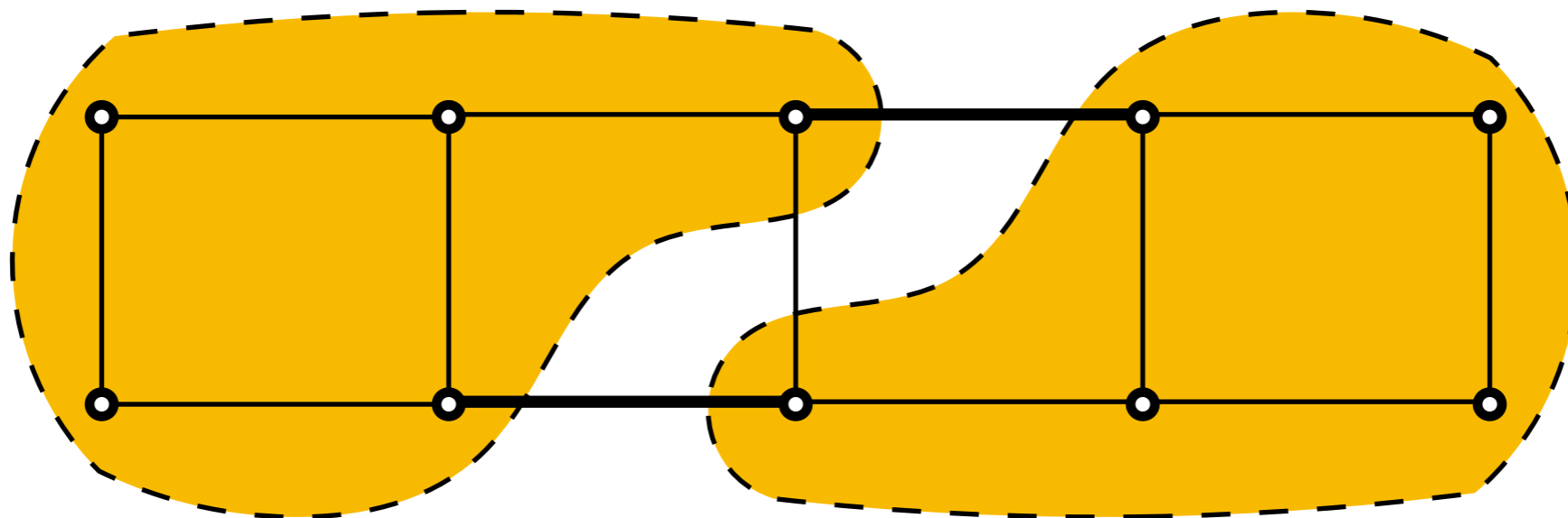
$$\leq m^{1+o(1)}$$

$$h = \sqrt{\log n}, \beta = m^{-1/h}$$

An overview of [FG'19]

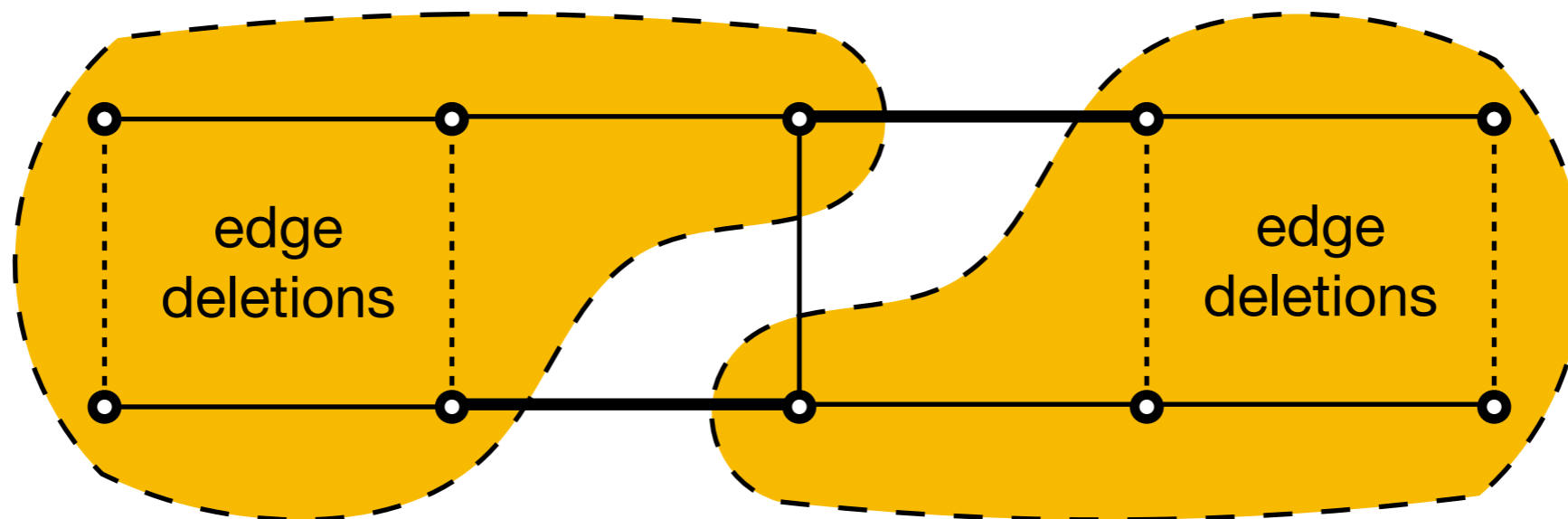
Decremental low-diameter decomposition

- Lemma: [FG'19]
A β -decomposition can be maintained under edge deletions such that:
 - (1) total update time is $\tilde{O}(m/\beta)$
 - (2) total number of **changes to inter-cluster** edges is $\tilde{O}(m)$



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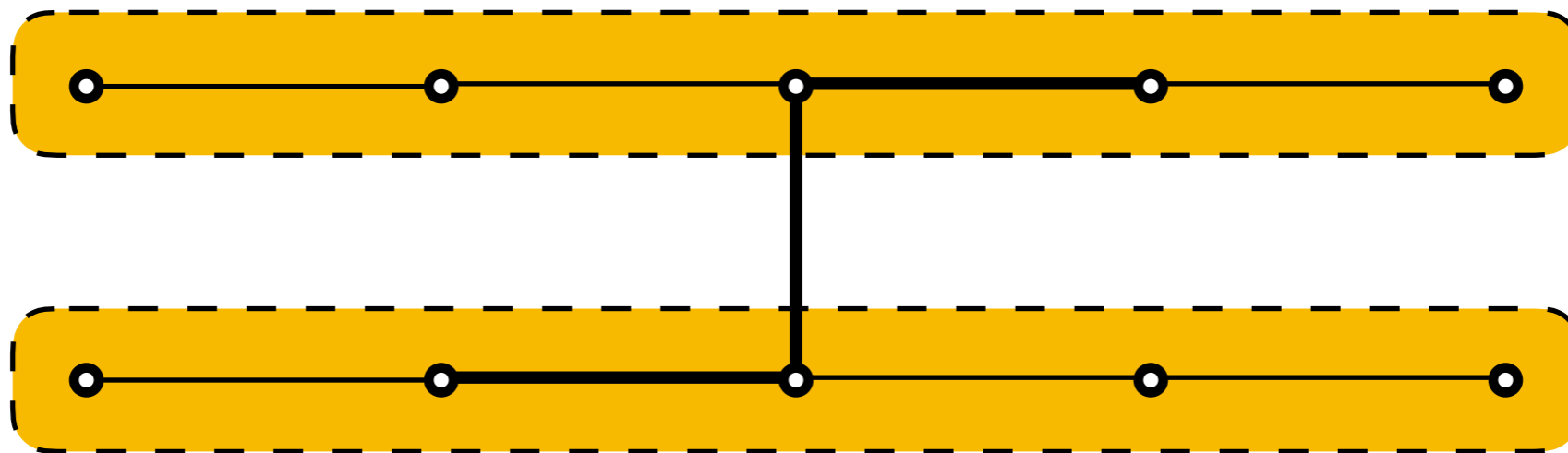
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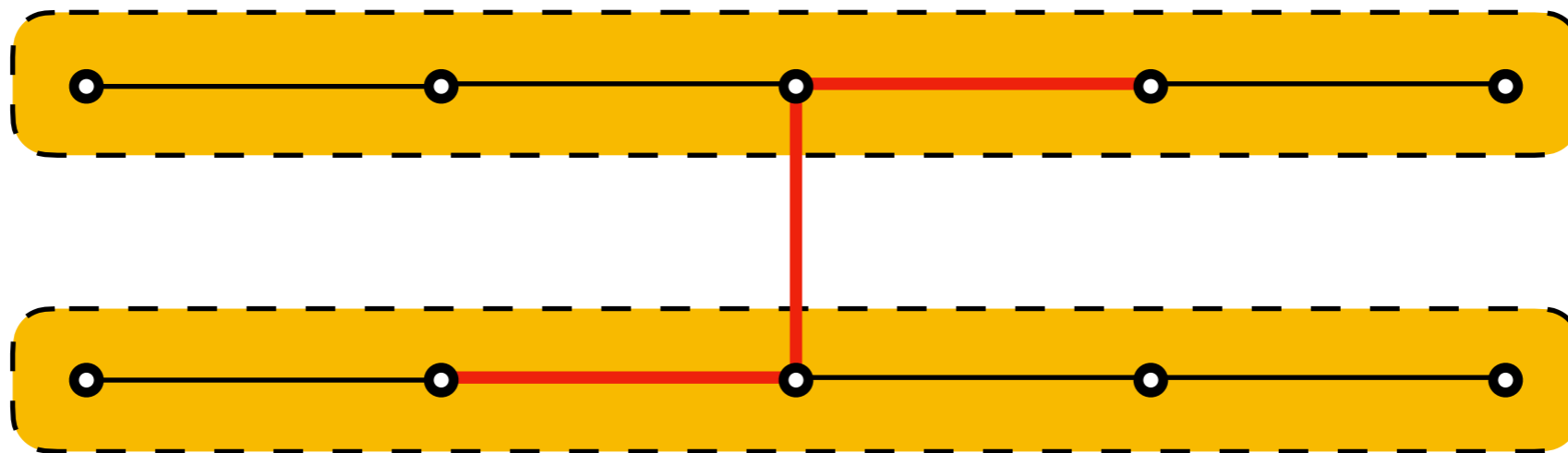
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update the β -decomposition

Decremental low-diameter decomposition

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 - (1) total update time is $\tilde{O}(m/\beta)$
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total #inter-cluster edges = 3

Fully dynamic low-diameter decomposition

- Lemma: [FG'19]

A β -decomposition can be maintained under edge updates such that:

(1) amortized update time is $\tilde{O}(1/\beta^2)$

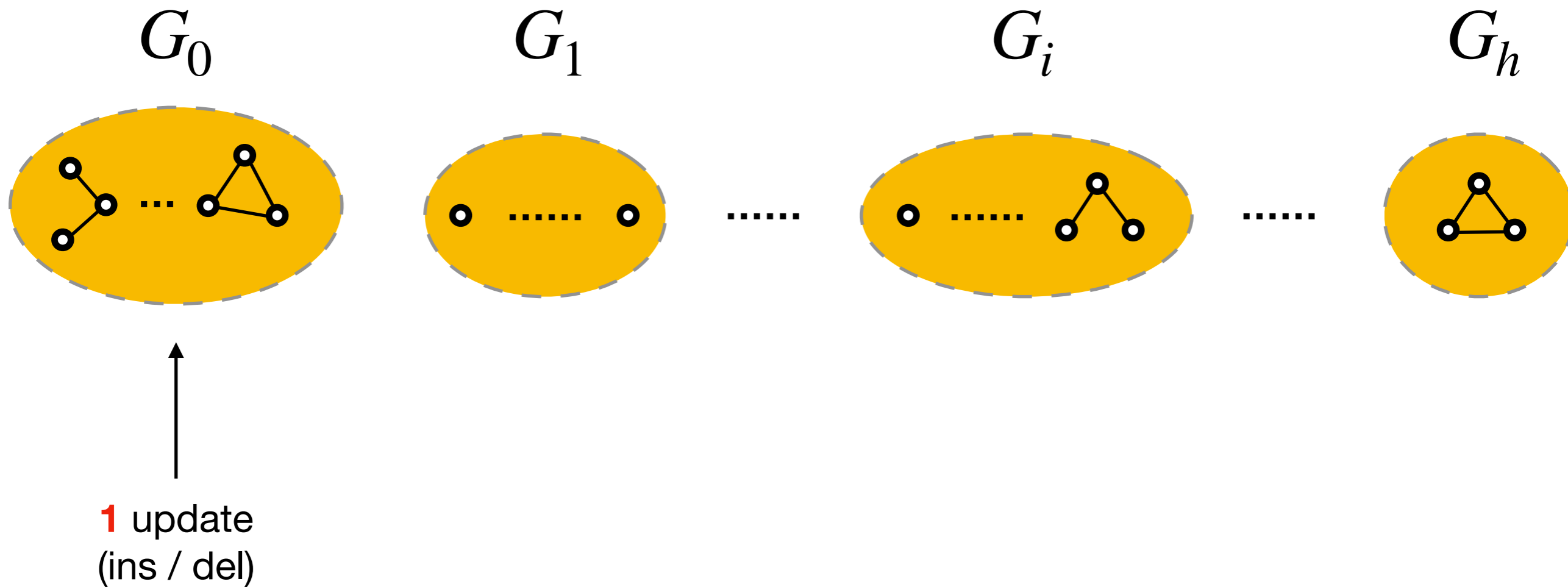
(2) amortized **changes to inter-cluster** edges is $\tilde{O}(1/\beta)$

- Handle edge insertions **lazily**

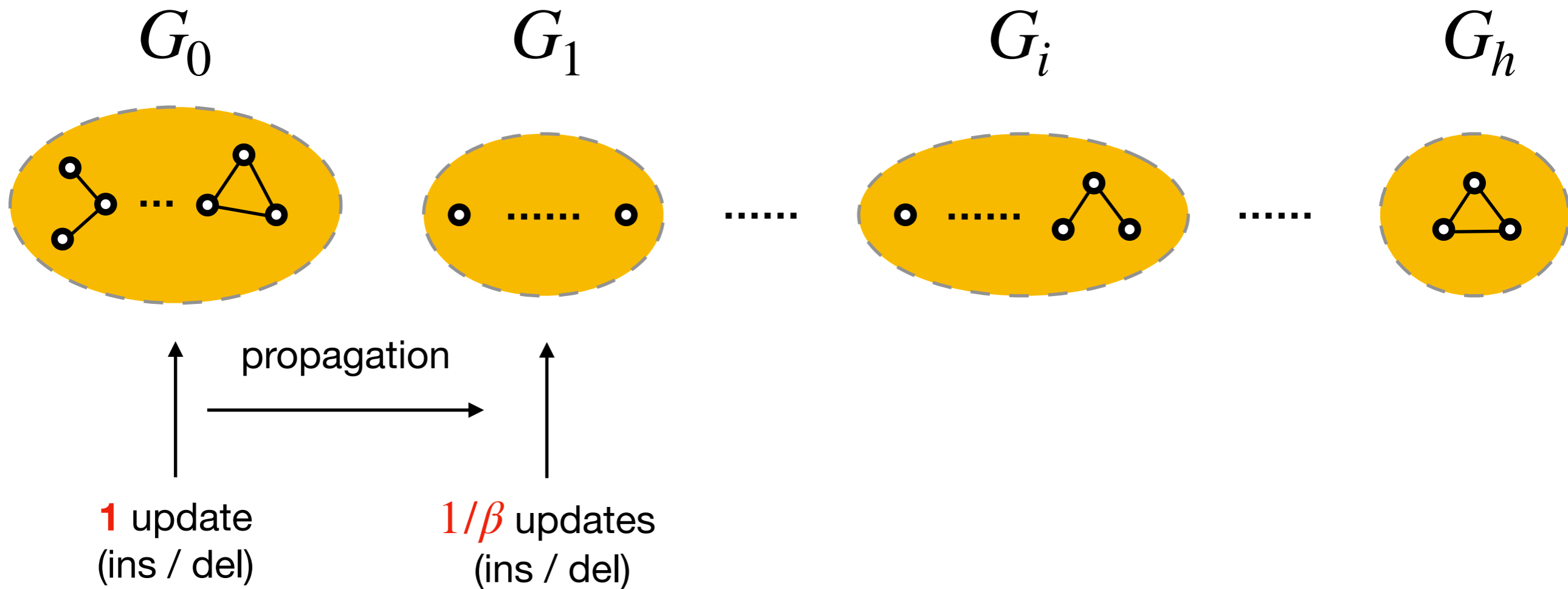
Apply decremental β -decomposition, and ignore all edge insertions, and **rebuild after every βm** edge updates

- **Amortized changes** $\approx \frac{\text{total changes}}{\text{total updates}} = \frac{m}{\beta m} = 1/\beta$

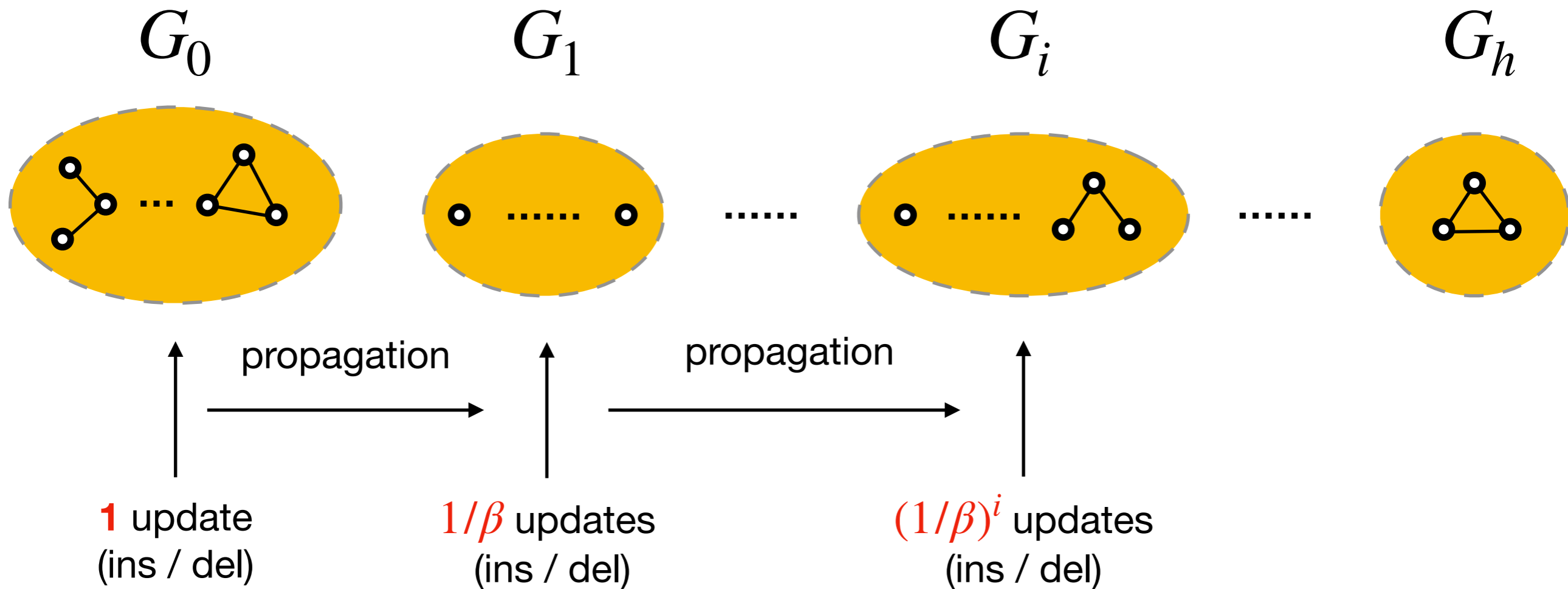
Total update time of hierarchical clustering



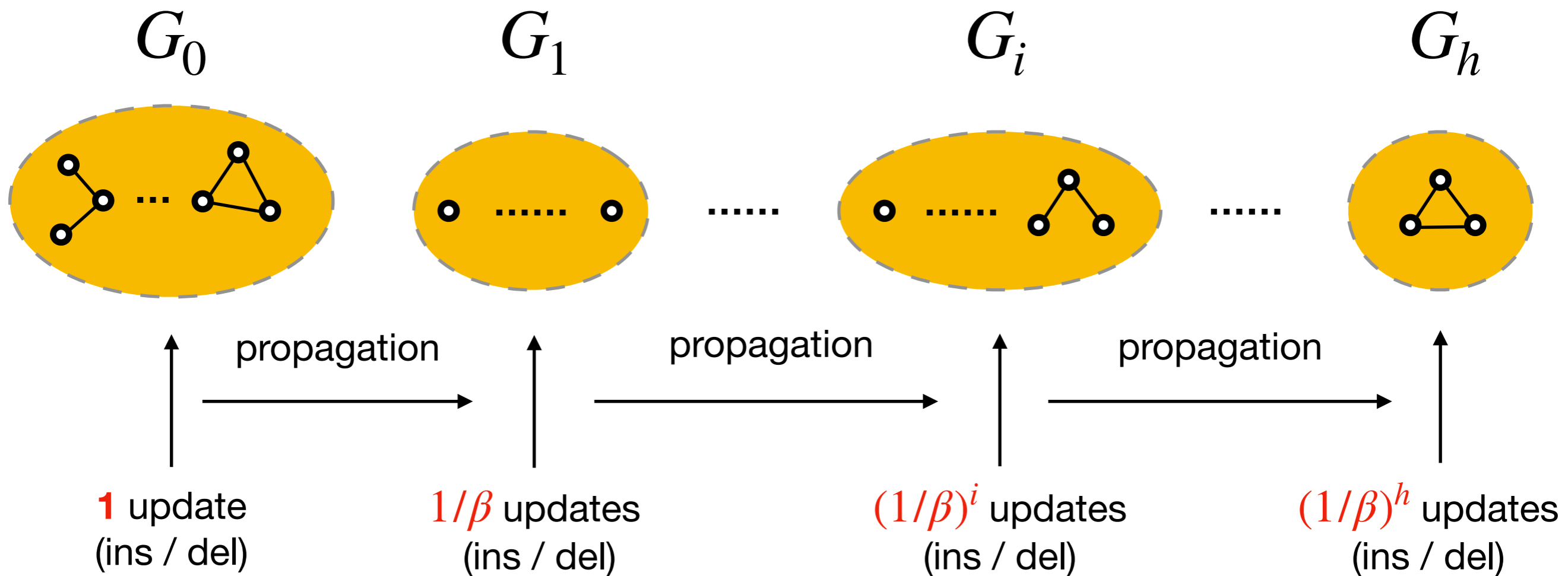
Total update time of hierarchical clustering



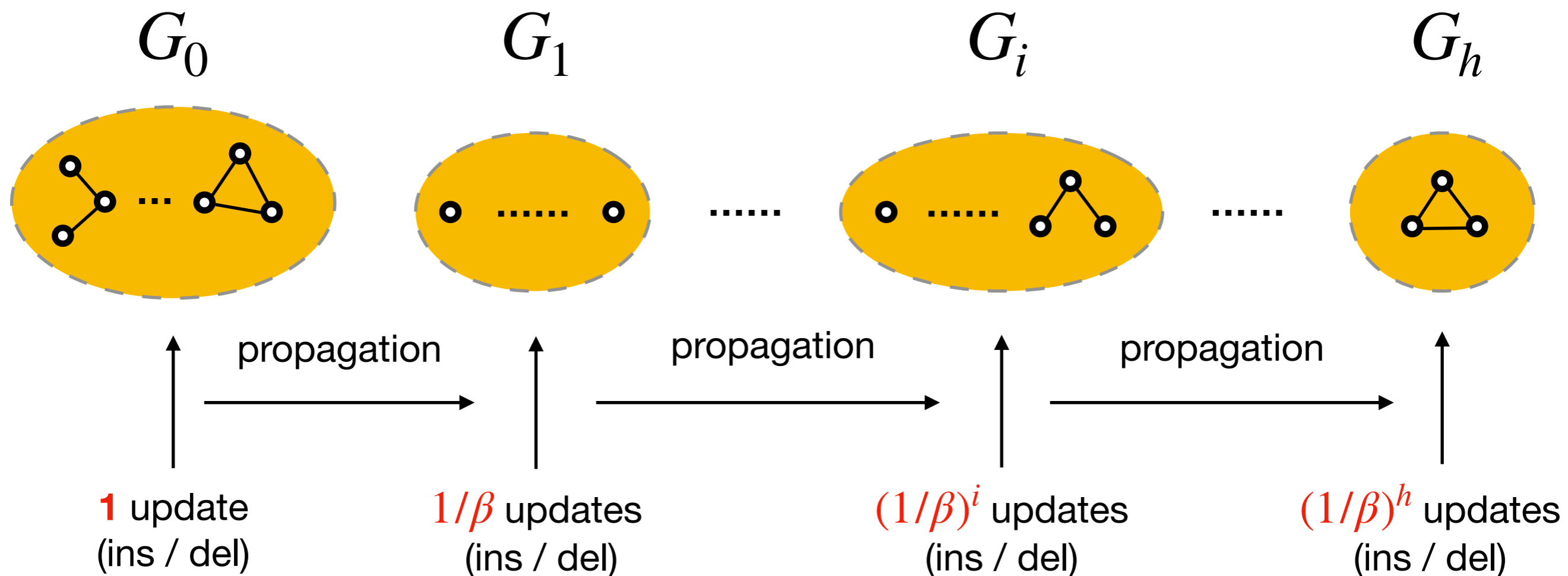
Total update time of hierarchical clustering



Total update time of hierarchical clustering



Total update time of hierarchical clustering



- Overall update time $\approx (1/\beta)^{h+2} + m\beta^h = m^{0.5+o(1)}$
- Graph sparsification can improve $m^{0.5+o(1)}$ to $n^{0.5+o(1)}$

Our improvement

Reducing total changes to inter-cluster edges

- Lemma: [FG'19]

A β -decomposition can be maintained under edge deletions such that:

(1) total update time is $\tilde{O}(m/\beta)$

(2) total number of **changes to inter-cluster** is $\tilde{O}(m)$

- Lemma:

A β -decomposition can be maintained under edge deletions such that:

(1) total update time is $\tilde{O}(m/\beta)$

(2) total number of **changes to inter-cluster** is $\tilde{O}(\beta \cdot m)$

Fully dynamic low-diameter decomposition

- Lemma:

A β -decomposition can be maintained under edge updates such that:

(1) amortized update time is $\tilde{O}(1/\beta^2)$

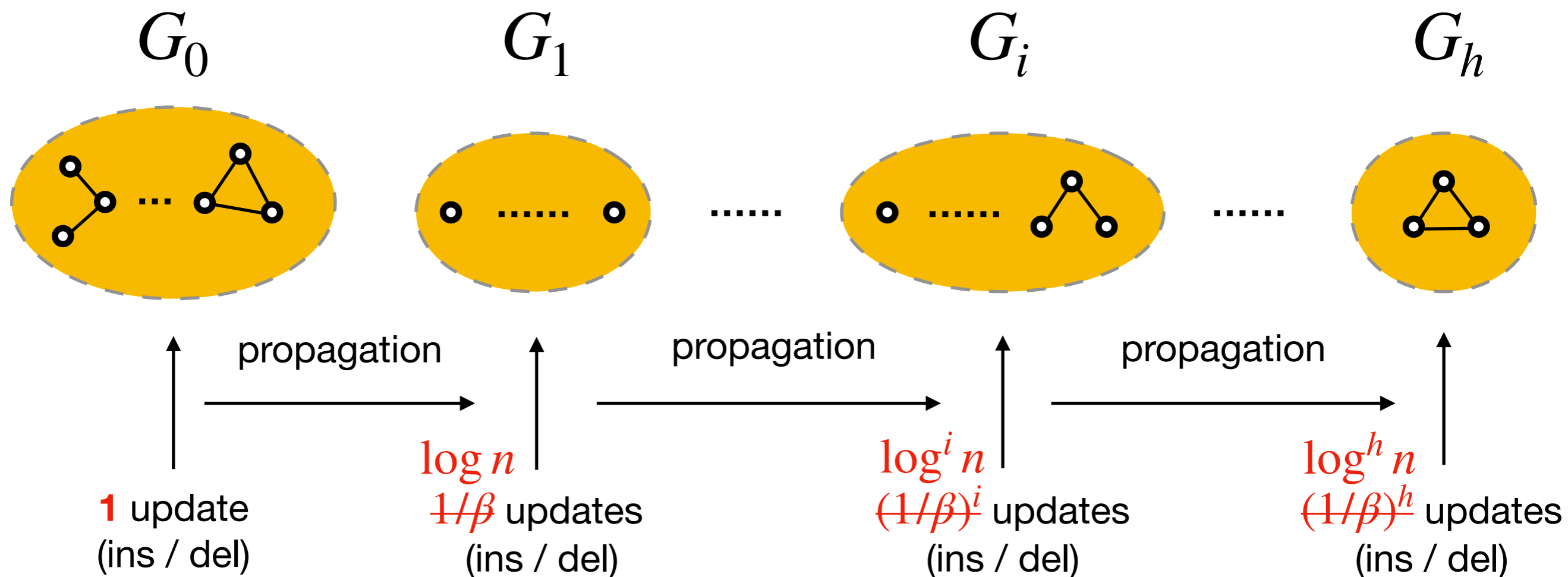
(2) amortized **changes to inter-cluster** edges is $\tilde{O}(1)$

- Handle edge insertions **lazily**

Apply decremental β -decomposition, and ignore all edge insertions, and **rebuild after every βm** edge updates

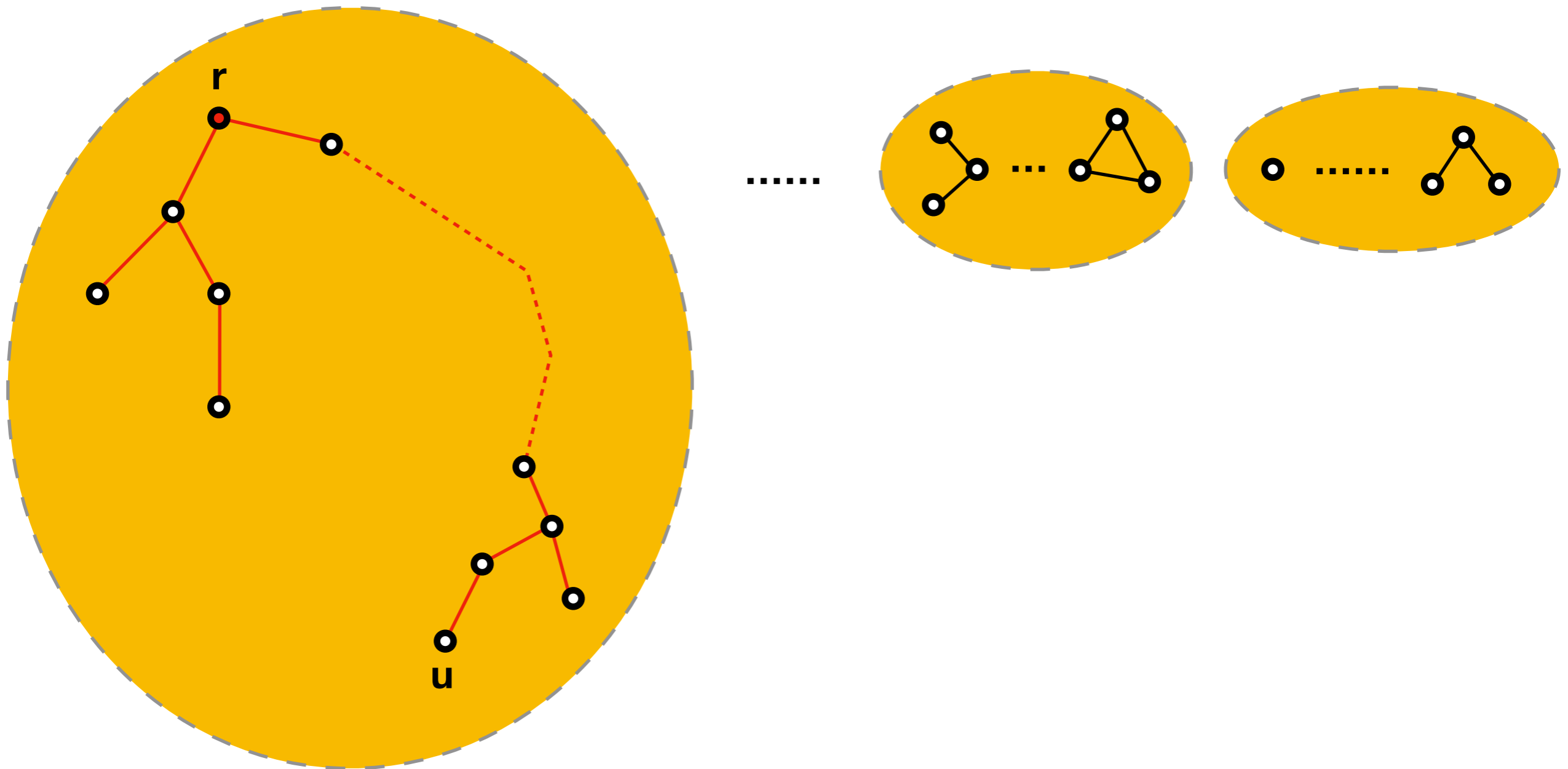
- **Amortized changes** $\approx \frac{\text{total changes}}{\text{total updates}} = \frac{\beta m}{\beta m} = 1$

Total update time of hierarchical clustering

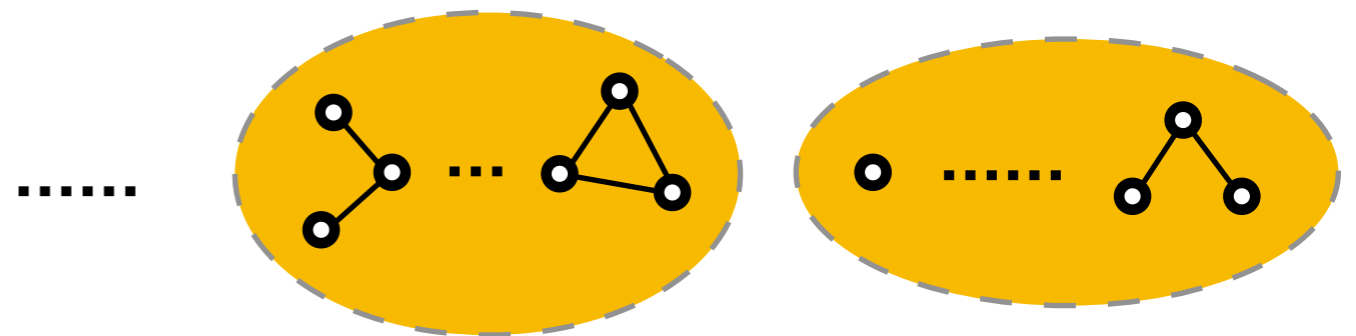
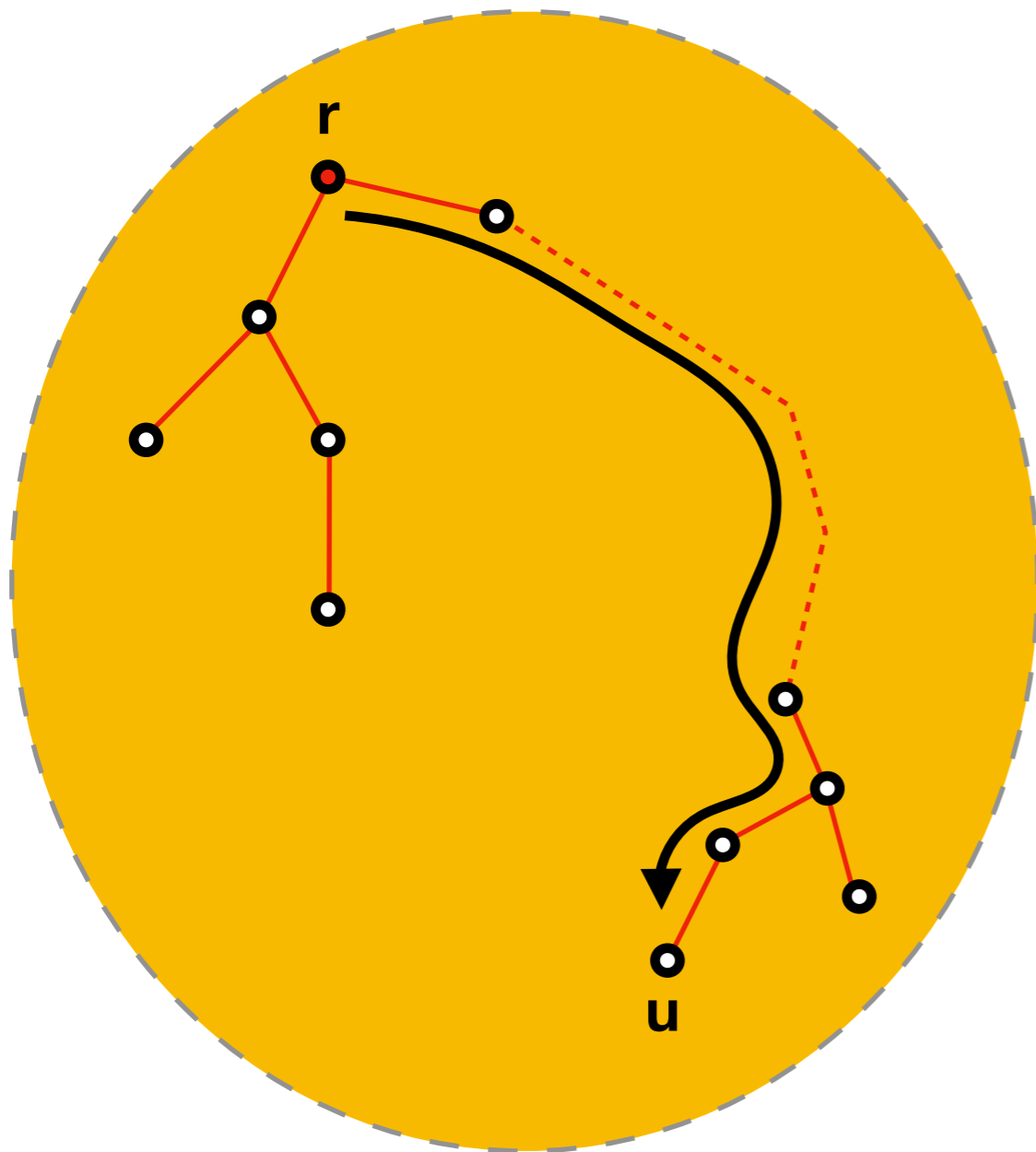


- Overall update time $\approx (1/\beta)^{h+2} + m\beta^h = m^{0.5+o(1)}$
- Overall update time $\approx \beta^{-2} \log^h n + m\beta^h = n^{o(1)}$
- Graph sparsification can improve $m^{0.5+o(1)}$ to $n^{0.5+o(1)}$

Decremental β -decomposition



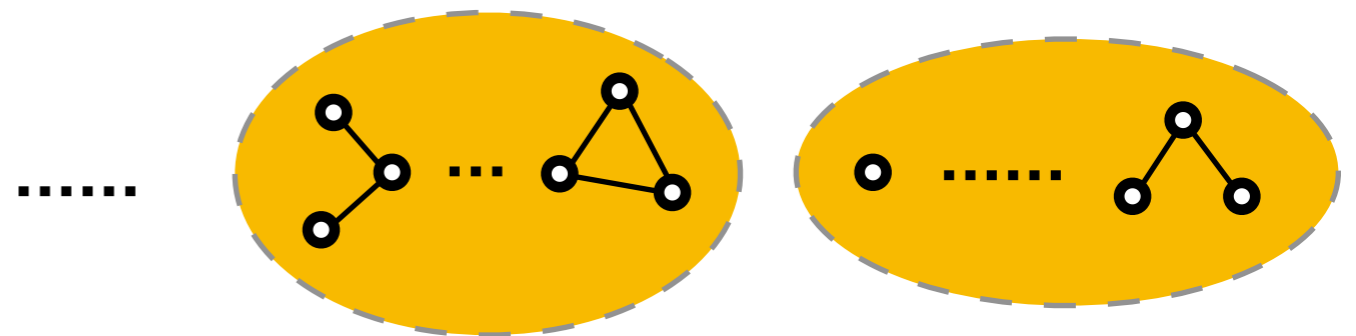
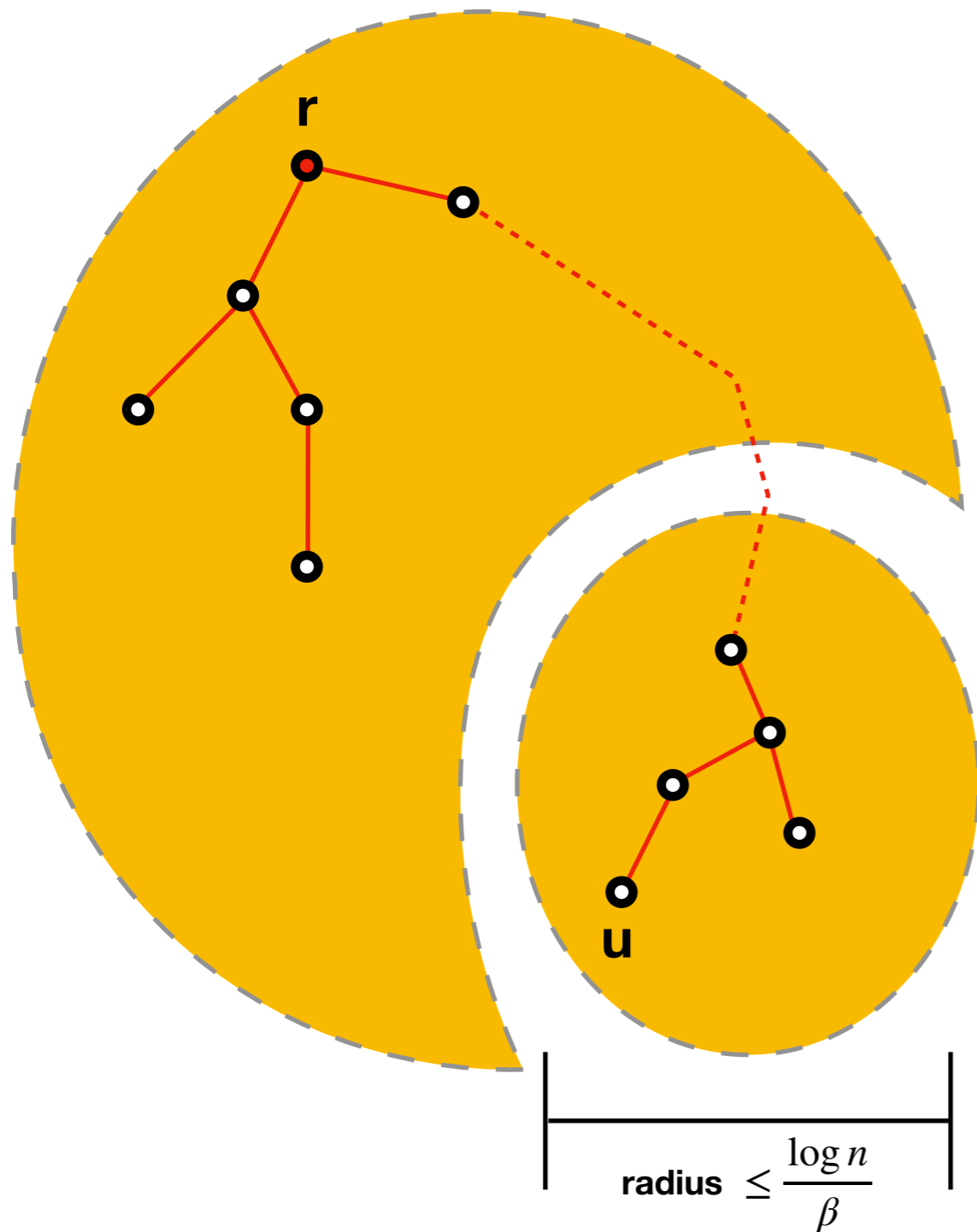
Decremental β -decomposition



In cluster C ,
 u becomes too far away

$$\text{dist}_T(r, u) > \frac{10 \log n}{\beta}$$

Decremental β -decomposition

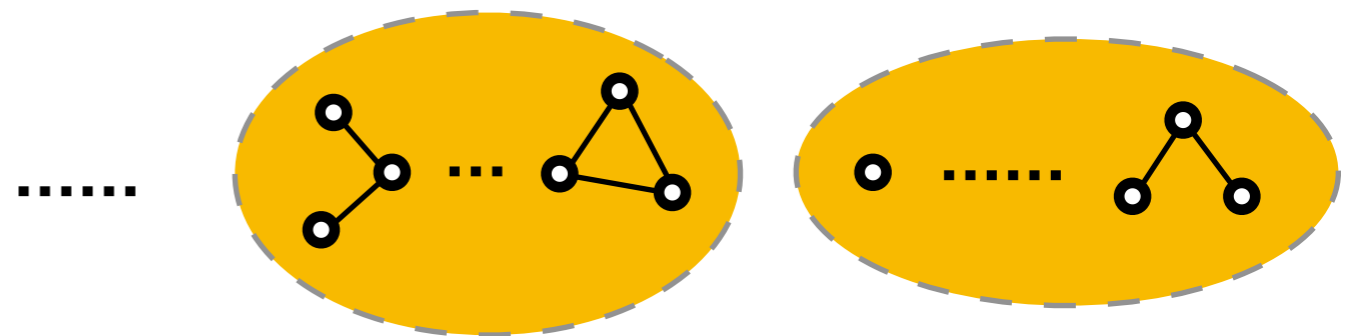
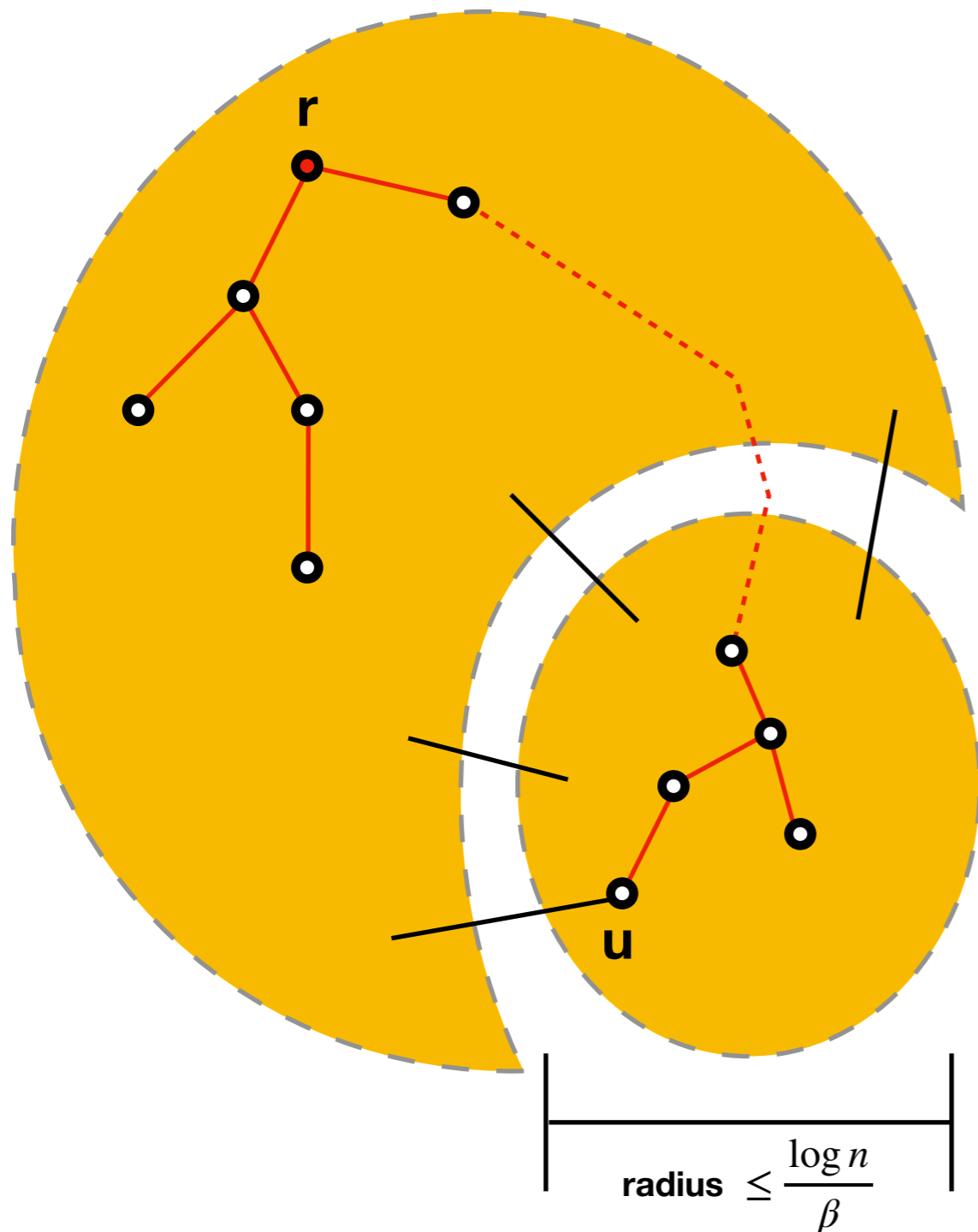


In cluster C ,
 u becomes too far away

$$\text{dist}_T(r, u) > \frac{10 \log n}{\beta}$$

Grow a ball C_1 centered at
 u with **radius** $\leq \log n / \beta$

Decremental β -decomposition



In cluster C ,
 u becomes too far away

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Grow a ball C_1 centered at
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The cut is sparse

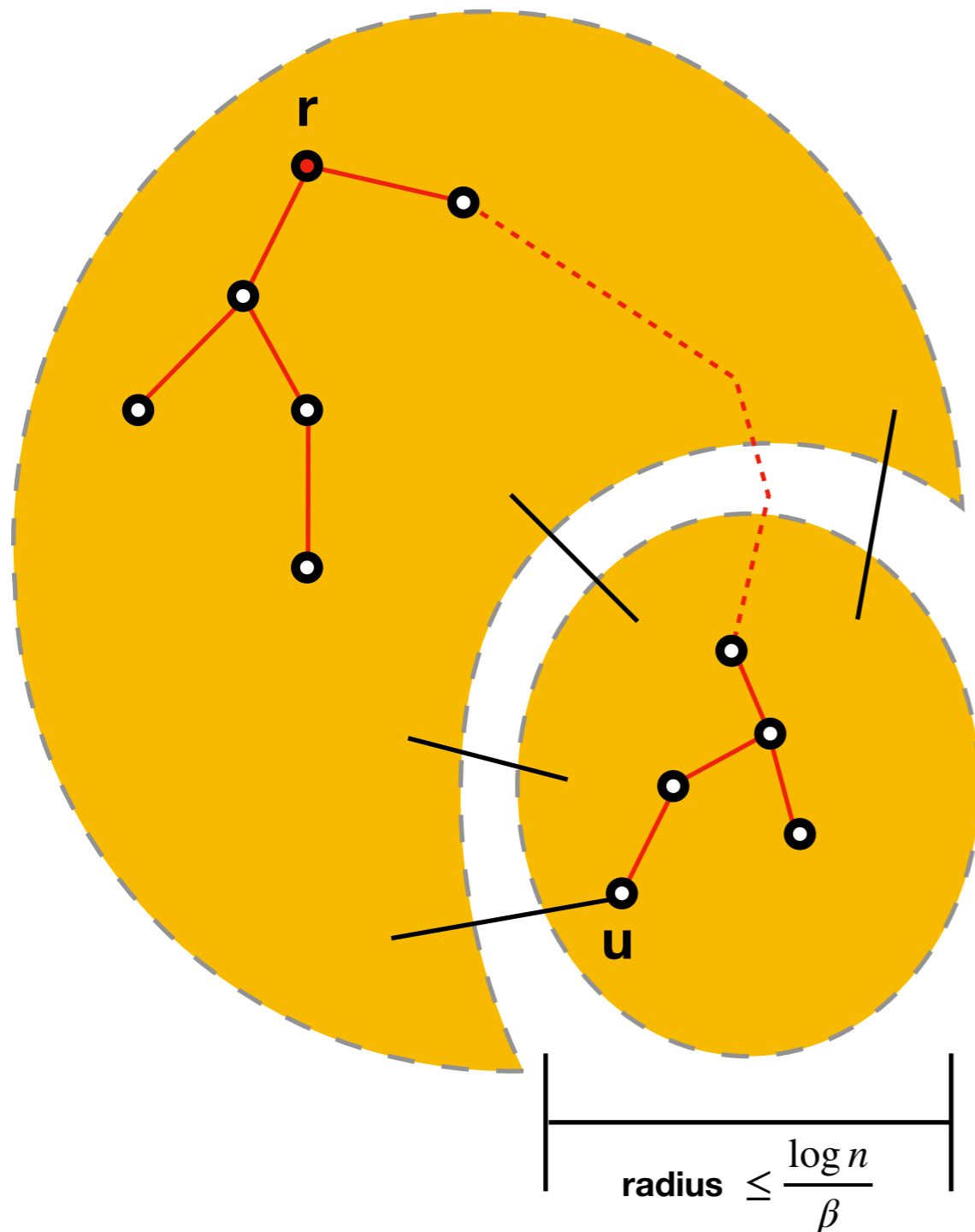
$$|E \cap (C \times C_1)| \leq \beta \cdot \text{vol}(C_1)$$

Decremental β -decomposition

Let C_1 be a new cluster if it does not contain too many edges, namely:

$$\text{vol}(C_1) \leq \frac{1}{2} \text{vol}(C^{\text{init}})$$

Otherwise



In cluster C ,
 u becomes too far away

$$\text{dist}_T(r, u) > \frac{10 \log n}{\beta}$$

Grow a ball C_1 centered at
 u with **radius** $\leq \log n / \beta$

Cut size is small

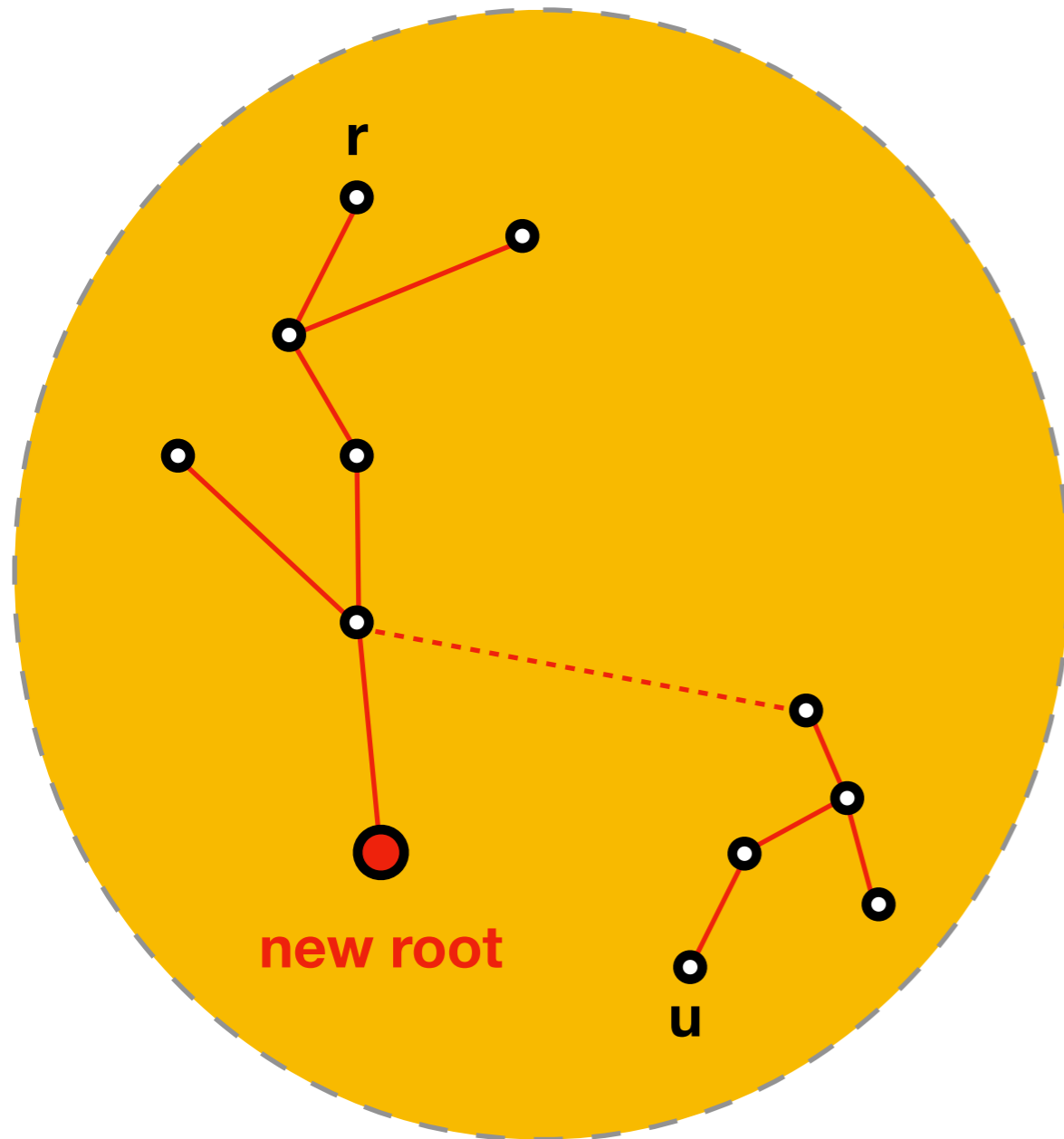
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Decremental β -decomposition

Let C_1 be a new cluster if it does not contain too many edges, namely:

$$\text{vol}(C_1) \leq \frac{1}{2} \text{vol}(C^{\text{init}})$$

Otherwise, randomly reassign the root and rebuild a new BFS tree



In cluster C ,
 u becomes too far away

$$\text{dist}_T(r, u) > \frac{10 \log n}{\beta}$$

Grow a ball C_1 centered at
 u with radius $\leq \log n / \beta$

Cut size is small

$$|E \cap (C \times C_1)| \leq \beta \cdot \text{vol}(C_1)$$

Correctness & running time

- Lemma: (total # inter-cluster edges)
Each time a new cluster C_1 is created,
new inter-cluster edges $\leq \beta \cdot \text{vol}(C_1) \leq \beta \cdot \frac{1}{2} \text{vol}(C^{\text{init}})$
Therefore, eventually #inter-cluster edges $\leq m\beta \log n$
- Lemma: (total running time)
Each cluster reassigns its BFS tree root for $O(\log n)$
times, with high probability. Hence total time is $\tilde{O}(m/\beta)$

Thanks